## Complex General Relativity

Giampiero Esposito

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## by

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## PREFACE

This book is written for theoretical and mathematical physicists and mathematicians interested in recent developments in complex general relativity and their application to classical and quantum gravity. Calculations are presented by paying attention to those details normally omitted in research papers, for pedagogical reasons. Familiarity with fibre-bundle theory is certainly helpful, but in many cases I only rely on two-spinor calculus and conformally invariant concepts in gravitational physics. The key concepts the book is devoted to are complex manifolds, spinor techniques, conformal gravity, $\alpha$-planes, $\alpha$-surfaces, Penrose transform, complex space-time models with non-vanishing torsion, spin- $\frac{1}{2}$ fields and spin- $\frac{3}{2}$ potentials. Problems have been inserted at the end, to help the reader to check his understanding of these topics.

Thus, I can find at least four reasons for writing yet another book on spinor and twistor methods in general relativity: (i) to write a textbook useful to beginning graduate students and research workers, where two-component spinor calculus is the unifying mathematical language. This enables one to use elegant and powerful techniques, while avoiding a part of mathematics that would put off physics-oriented readers; (ii) to make it possible to a wide audience to understand the key concepts about complex space-time, twistor space and Penrose transform for gravitation; (iii) to present a self-consistent mathematical theory of complex space-times with non-vanishing torsion; (iv) to present the first application to boundary-value problems in cosmology of the Penrose formalism for spin- $\frac{3}{2}$ potentials. The self-contained form and the length have been chosen to make the monograph especially suitable for a series of graduate lectures.

Section 7.2 is based on work in collaboration with Hugo A. Morales-Técotl and Giuseppe Pollifrone. It has been a pleasure and a privilege, for me, to work with both of them. Sections 8.2-8.9 are based on work in collaboration with Giuseppe Pollifrone and, more recently, with Gabriele Gionti, Alexander Kamenshchik and

## Preface

Igor Mishakov. Only collaborative work of which I was the first author has been included.

A constant source of inspiration have been the original papers by Roger Penrose and Richard Ward, as well as the more comprehensive monographs by the same authors. The years spent in Cambridge as a graduate student, and the many conversations on geometrical methods with Giuseppe Marmo, also played a key role.

Financial support by the Ministero per l'Università e la Ricerca Scientifica e Tecnologica to attend the Twistor Conference in Seale-Hayne is also gratefully acknowledged. I very much enjoyed such a beautiful and stimulating Conference, and its friendly atmosphere. I am indebted to Stephen Huggett for hospitality in Seale-Hayne and for encouraging my research, and to Mauro Carfora for inviting me to give a series of graduate lectures at SISSA on the theory of the Dirac operator. Partial support by the European Union under the Human Capital and Mobility Program was also obtained.

## PART I:

## SPINOR FORM OF GENERAL RELATIVITY

## INTRODUCTION TO COMPLEX SPACE-TIME


#### Abstract

This chapter begins by describing the physical and mathematical motivations for studying complex space-times or real Riemannian four-manifolds in gravitational physics. They originate from algebraic geometry, Euclidean quantum field theory, the path-integral approach to quantum gravity, and the theory of conformal gravity. The theory of complex manifolds is then briefly outlined. Here, one deals with paracompact Hausdorff spaces where local coordinates transform by complex-analytic transformations. Examples are given such as complex projective space $P_{m}$, non-singular sub-manifolds of $P_{m}$, and orientable surfaces. The plan of the whole monograph is finally presented, with emphasis on two-component spinor calculus, Penrose transform and Penrose formalism for spin- $\frac{3}{2}$ potentials.


## 1. Introduction to Complex Space- Time

### 1.1 From Lorentzian Space-Time to Complex Space-Time

Although Lorentzian geometry is the mathematical framework of classical general relativity and can be seen as a good model of the world we live in (Hawking and Ellis 1973, Esposito 1992, Esposito 1994), the theoretical-physics community has developed instead many models based on a complex space-time picture. We postpone until section 3.3 the discussion of real, complexified or complex manifolds, and we here limit ourselves to say that the main motivations for studying these ideas are as follows.
(1) When one tries to make sense of quantum field theory in flat space-time, one finds it very convenient to study the Wick-rotated version of Green functions, since this leads to well-defined mathematical calculations and elliptic boundaryvalue problems. At the end, quantities of physical interest are evaluated by analytic continuation back to real time in Minkowski space-time.
(2) The singularity at $r=0$ of the Lorentzian Schwarzschild solution disappears on the real Riemannian section of the corresponding complex space-time, since $r=0$ no longer belongs to this manifold (Esposito 1994). Hence there are real Riemannian four-manifolds which are singularity-free, and it remains to be seen whether they are the most fundamental in modern theoretical physics.
(3) Gravitational instantons shed some light on possible boundary conditions relevant for path-integral quantum gravity and quantum cosmology (Gibbons and Hawking 1993, Esposito 1994).
(4) Unprimed and primed spin-spaces are not anti-isomorphic if Lorentzian space-time is replaced by a complex or real Riemannian manifold. Thus, for example, the Maxwell field strength is represented by two independent symmetric spinor fields, and the Weyl curvature is also represented by two independent symmetric spinor fields (see (2.1.35)-(2.1.36)). Since such spinor fields are no longer related by complex conjugation (i.e. the anti-isomorphism between the two spinspaces), one of them may vanish without the other one having to vanish as well.

## 1. Introduction to Complex Space- Time

This property gives rise to the so-called self-dual or anti-self-dual gauge fields, as well as to self-dual or anti-self-dual space-times (section 4.2).
(5) The geometrical study of this special class of space-time models has made substantial progress by using. twistor-theory techniques. The underlying idea (Penrose 1967, Penrose 1968, Penrose and MacCallum 1973, Penrose 1975, Penrose 1977, Penrose 1980, Penrose and Ward 1980, Ward 1980a-b, Penrose 1981, Ward 1981a-b, Huggett and Tod 1985, Woodhouse 1985, Penrose 1986, Penrose 1987, Yasskin 1987, Manin 1988, Bailey and Baston 1990, Mason and Hughston 1990, Ward and Wells 1990) is that conformally invariant concepts such as null lines and null surfaces are the basic building blocks of the world we live in, whereas spacetime points should only appear as a derived concept. By using complex-manifolds theory, twistor theory provides an appropriate mathematical description of this key idea.

A possible mathematical motivation for twistors can be described as follows (papers 99 and 100 in Atiyah 1988). In two real dimensions, many interesting problems are best tackled by using complex-variable methods. In four real dimensions, however, the introduction of two complex coordinates is not, by itself, sufficient, since no preferred choice exists. In other words, if we define the complex variables

$$
\begin{align*}
& z_{1} \equiv x_{1}+i x_{2}  \tag{1.1.1}\\
& z_{2} \equiv x_{3}+i x_{4} \tag{1.1.2}
\end{align*}
$$

we rely too much on this particular coordinate system, and a permutation of the four real coordinates $x_{1}, x_{2}, x_{3}, x_{4}$ would lead to new complex variables not well related to the first choice. One is thus led to introduce three complex variables $\left(u, z_{1}^{u}, z_{2}^{u}\right)$ : the first variable $u$ tells us which complex structure to use, and the next two are the complex coordinates themselves. In geometrical language, we start with the complex projective three-space $P_{3}(C)$ (see section 1.2) with complex homogeneous coordinates $(x, y, u, v)$, and we remove the complex projective line

## 1. Introduction to Complex Space- Time

given by $u=v=0$. Any line in $\left(P_{3}(C)-P_{1}(C)\right)$ is thus given by a pair of equations

$$
\begin{align*}
& x=a u+b v  \tag{1.1.3}\\
& y=c u+d v \tag{1.1.4}
\end{align*}
$$

In particular, we are interested in those lines for which $\boldsymbol{c}=-\bar{b}, \boldsymbol{d}=\overline{\boldsymbol{a}}$. The determinant $\Delta$ of (1.1.3)-(1.1.4) is thus given by

$$
\begin{equation*}
\Delta=a \bar{a}+b \bar{b}=|a|^{2}+|b|^{2} \tag{1.1.5}
\end{equation*}
$$

which implies that the line (1.1.3)-(1.1.4) never intersects the line $x=y=0$, with the obvious exception of the case when they coincide. Moreover, no two lines intersect, and they fill out the whole of $\left(P_{3}(C)-P_{1}(C)\right)$. This leads to the fibration $\left(P_{3}(C)-P_{1}(C)\right) \longrightarrow R^{4}$ by assigning to each point of $\left(P_{3}(C)-P_{1}(C)\right)$ the four coordinates $(\operatorname{Re}(a), \operatorname{Im}(a), \operatorname{Re}(b), \operatorname{Im}(b))$. Restriction of this fibration to a plane of the form

$$
\begin{equation*}
\alpha u+\beta v=0 \tag{1.1.6}
\end{equation*}
$$

yields an isomorphism $C^{2} \cong R^{4}$, which depends on the ratio $(\alpha \beta) \in P_{1}(C)$. This is why the picture embodies the idea of introducing complex coordinates.

Such a fibration depends on the conformal structure of $R^{4}$. Hence, it can be extended to the one-point compactification $S^{4}$ of $R^{4}$, so that we get a fibration $P_{3}(C) \rightarrow S^{4}$ where the line $u=v=0$, previously excluded, sits over the point at $\infty$ of $S^{4}=R^{4} \cup\{\infty\}$. This fibration is naturally obtained if we use the quaternions $H$ to identify $C^{4}$ with $H^{2}$ and the four-sphere $S^{4}$ with $P_{1}(H)$, the quaternion projective line. We should now recall that the quaternions $H$ are obtained from the vector space $R$ of real numbers by adjoining three symbols $i, j, k$ such that

$$
\begin{gather*}
i^{2}=j^{2}=k^{2}=-1  \tag{1.1.7}\\
i j=-j i=k, \quad j k=-k j=i, \quad k i=-i k=j \tag{1.1.8}
\end{gather*}
$$

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Thus, a general quaternion $\in H$ is defined by

$$
\begin{equation*}
x \equiv x_{1}+x_{2} i+x_{3} j+x_{4} k \tag{1.1.9}
\end{equation*}
$$

where $\left(x_{1}, x_{2}, x_{3}, x_{4}\right) \in R^{4}$, whereas the conjugate quaternion $\bar{x}$ is given by

$$
\begin{equation*}
\bar{x} \equiv x_{1}-x_{2} i-x_{3} j-x_{4} k \tag{1.1.10}
\end{equation*}
$$

Note that conjugation obeys the identities

$$
\begin{gather*}
\overline{(x y)}=\bar{y} \bar{x}  \tag{1.1.11}\\
x \bar{x}=\bar{x} x=\sum_{\mu=1}^{4} x_{\mu}^{2} \equiv|x|^{2} \tag{1.1.12}
\end{gather*}
$$

If a quaternion does not vanish, it has a unique inverse given by

$$
\begin{equation*}
x^{-1} \equiv \frac{\bar{x}}{|x|^{2}} \tag{1.1.13}
\end{equation*}
$$

Interestingly, if we identify $i$ with $\sqrt{-1}$, we may view the complex numbers $C$ as contained in $H$ taking $x_{3}=x_{4}=0$. Moreover, every quaternion $x$ as in (1.1.9) has a unique decomposition

$$
\begin{equation*}
x=z_{1}+z_{2} j \tag{1.1.14}
\end{equation*}
$$

where $z_{1} \equiv x_{1}+x_{2} i, z_{2} \equiv x_{3}+x_{4} i, \quad$ by virtue of (1.1.8). This property enables one to identify $H$ with $C^{2}$, and finally $H^{2}$ with $C^{4}$, as we said following (1.1.6).

The map $\sigma: P_{3}(C) \rightarrow P_{3}(C)$ defined by

$$
\begin{equation*}
\sigma(x, y, u, v)=(-\bar{y}, \bar{x},-\bar{v}, \bar{u}) \tag{1.1.15}
\end{equation*}
$$

preserves the fibration because $c=-\bar{b}, \boldsymbol{d}=\bar{a}$, and induces the antipodal map on each fibre. We can now lift problems from $S^{4}$ or $R^{4}$ to $P_{3}(C)$ and try to use complex methods.

## 1. Introduction to Complex Space- Time

### 1.2 Complex Manifolds

Following Chern 1979, we now describe some basic ideas and properties of complex-manifold theory. The reader should thus find it easier (or, at least, less difficult) to understand the holomorphic ideas used in the rest of the book.

We know that a manifold is a space which is locally similar to Euclidean space in that it can be covered by coordinate patches. More precisely (Hawking and Ellis 1973), we say that a real $C^{r} n$-dimensional manifold $M$ is a set $M$ together with a $C^{r}$ atlas $\left\{U_{\alpha}, \phi_{\alpha}\right\}$, i.e. a collection of charts $\left(U_{\alpha}, \phi_{\alpha}\right)$, where the $U_{\alpha}$ are subsets of $M$ and the $\phi_{\alpha}$ are one-one maps of the corresponding $U_{\alpha}$ to open sets in $R^{n}$ such that
(i) $M$ is covered by the $U_{\alpha}$, i.e. $M=\bigcup_{\alpha} U_{\alpha}$
(ii) if $U_{\alpha} \cap U_{\beta}$ is non-empty, the map

$$
\phi_{\alpha} \circ \phi_{\beta}^{-1}: \phi_{\beta}\left(U_{\alpha} \cap U_{\beta}\right) \rightarrow \phi_{\alpha}\left(U_{\alpha} \cap U_{\beta}\right)
$$

is a $C^{r}$ map of an open subset of $R^{n}$ to an open subset of $R^{n}$. In general relativity, it is of considerable importance to require that the Hausdorff separation axiom should hold. This states that if $p, q$ are any two distinct points in $M$, there exist disjoint open sets $U, V$ in $M$ such that $p \in U, q \in V$. The space-time manifold $(M, g)$ is therefore taken to be a connected, four-dimensional, Hausdorff $C^{\infty}$ manifold $M$ with a Lorentz metric $g$ on $M$, i.e. the assignment of a symmetric, nondegenerate bilinear form $g_{\mid p}: T_{p} M \times T_{p} M \rightarrow R$ with diagonal form (,,,-+++ ) to each tangent space. Moreover, a time orientation is given by a globally defined, timelike vector field $X: M \rightarrow T M$. This enables one to say that a timelike or null tangent vector $v \in T_{p} M$ is future-directed if $g(X(p), v)<0$, or past-directed if $g(X(p), v)>0$ (Esposito 1992, Esposito 1994).

By a complex manifold we mean a paracompact Hausdorff space covered by neighbourhoods each homeomorphic to an open set in $C^{m}$, such that where two neighbourhoods overlap, the local coordinates transform by a complex-analytic

## 1. Introduction to Complex Space-Time

transformation. Thus, if $z^{1}, \ldots, z^{m}$ are local coordinates in one such neighbourhood, and if $w^{1}, \ldots, w^{m}$ are local coordinates in another neighbourhood, where they are both defined one has $\boldsymbol{w}^{i}=\boldsymbol{w}^{i}\left(z^{1}, \ldots, \boldsymbol{z}^{m}\right)$, where each $w^{i}$ is a holomorphic function of the $z^{\prime}$ s, and the determinant $\partial\left(w^{1}, \ldots, w^{m}\right) / \partial\left(z^{1}, \ldots, z^{m}\right)$ does not vanish. Various examples can be given as follows (Chern 1979).

E1. The space $C^{m}$ whose points are the $m$-tuples of complex numbers $\left(z^{1}, \ldots, z^{m}\right)$ In particular, $C^{1}$ is the so-called Gaussian plane.

E2. Complex projective space $P_{m}$, also denoted by $P_{m}(C)$ or $C P^{m}$. Denoting by $\{0\}$ the origin $(0, \ldots, 0)$, this is the quotient space obtained by identifying the points $\left(z^{0}, z^{1}, \ldots, z^{m}\right)$ in $C^{m+1}-\{0\}$ which differ from each other by a factor. The covering of $P_{m}$ is given by $m+1$ open sets $U_{i}$ defined respectively by $z^{i} \neq 0$, $0 \leq i \leq m$. In $U_{i}$ we have the local coordinates $\zeta_{i}^{k} \equiv z^{k} / z^{i}, 0 \leq k \leq m, k \neq i$. In $U_{i} \cap U_{j}$, transition of local coordinates is given by $\zeta_{j}^{h} \equiv \zeta_{i}^{h} / \zeta_{i}^{j}, 0 \leq h \leq m, h \neq j$, which are holomorphic functions. A particular case is the Riemann sphere $P_{1}$.

E3. Non-singular sub-manifolds of $P_{m}$, in particular, the non-singular hyperquadric

$$
\begin{equation*}
\left(z^{0}\right)^{2}+\ldots+\left(z^{m}\right)^{2}=0 \tag{1.2.1}
\end{equation*}
$$

A theorem of Chow states that every compact sub-manifold embedded in $P_{m}$ is the locus defined by a finite number of homogeneous polynomial equations. Compact sub-manifolds of $C^{m}$ are not very important, since a connected compact sub-manifold of $C^{m}$ is a point.

E4. Let $\Gamma$ be the discontinuous group generated by $2 m$ translations of $C^{m}$, which are linearly independent over the reals. The quotient space $C^{m} / \Gamma$ is then called the complex torus. Moreover, let $\Delta$ be the discontinuous group generated by $z^{k} \rightarrow 2 z^{k}$, $1 \leq k \leq m$. The quotient manifold $\left(C^{m}-\{0\}\right) / \Delta$ : is the so-called Hopf manifold,

## 1. Introduction to Complex Space- Time

and is homeomorphic to $S^{1} \times S^{2 m-1}$. Last but not least, we consider the group $M_{3}$ of all matrices

$$
F_{3}=\left(\begin{array}{ccc}
1 & z_{1} & z_{2}  \tag{1.2.2}\\
0 & 1 & z_{3} \\
0 & 0 & 1
\end{array}\right)
$$

and let $D$ be the discrete group consisting of those matrices for which $z_{1}, z_{2}, z_{3}$ are Gaussian integers. This means that $z_{k}=m_{k}+i n_{k}, 1 \leq k \leq 3$, where $m_{k}, n_{k}$ are rational integers. An Iwasawa manifold is then defined as the quotient space $M_{3} / D$.

E5. Orientable surfaces are particular complex manifolds. The surfaces are taken to be $C^{\infty}$, and we define on them a positive-definite Riemannian metric. The Korn-Lichtenstein theorem ensures that local parameters $x, y$ exist such that the metric locally takes the form

$$
\begin{equation*}
a=\lambda^{2}(d x \otimes d x+d u \otimes d u) \quad . \quad \lambda>0 \tag{1.2.3}
\end{equation*}
$$

or

$$
\begin{equation*}
g=\lambda^{2} d z \otimes d \bar{z} \quad, \quad z \equiv x+i y \tag{1.2.4}
\end{equation*}
$$

If $w$ is another local coordinate, we have

$$
\begin{equation*}
g=\lambda^{2} d z \otimes d \bar{z}=\mu^{2} d w \otimes d \bar{w} \tag{1.2.5}
\end{equation*}
$$

since $g$ is globally defined. Hence $d w$ is a multiple of $d z$ or $\boldsymbol{d} \bar{z}$. In particular, if the complex coordinates $z$ and $w$ define the same orientation, then $d w$ is proportional to $d z$. Thus, $w$ is a holomorphic function of $z$, and the surface becomes a complex manifold. Riemann surfaces are, by definition, one-dimensional complex manifolds.

Let us denote by $V$ an $m$-dimensional real vector space. We say that $V$ has a complex structure if there exists a linear endomorphism $J: V \rightarrow V$ such that $J^{2}=-1$, where 1 is the identity endomorphism. An eigenvalue of $J$ is a complex number $\lambda$ such that the equation $J x=\lambda x$ has a non-vanishing solution $x \in V$. Applying $J$ to both sides of this equation, one finds $-x=\lambda^{2} x$. Hence $\lambda= \pm i$.

## 1. Introduction to Complex Space-Time

Since the complex eigenvalues occur in conjugate pairs, $V$ is of even dimension $n=2 m$. Let us now denote by $V^{*}$ the dual space of $V$, i.e. the space of all real-valued linear functions over $V$. The pairing of $V$ and $V^{*}$ is $\left\langle x, \mathrm{y}^{*}\right\rangle, x \in V$, $y^{*} \in V^{*}$, so that this function is $R$-linear in each of the arguments. Following Chern 1979, we also consider $V^{*} \otimes C$, i.e. the space of all complex-valued $R$-linear functions over $V$. By construction, $V^{*} \otimes C$ is an $n$-complex-dimensional complex vector space. Elements $f \in V^{*} \otimes C$ are of type $(1,0)$ if $f(J x)=i f(x)$, and of type $(0,1)$ if $f(J x)=-i f(x), x \in V$.

If $V$ has a complex structure $J$, an Hermitian structure in $V$ is a complexvalued function $H$ acting on $x, y \in V$ such that

$$
\begin{gather*}
H\left(\lambda_{1} x_{1}+\lambda_{2} x_{2}, y\right)=\lambda_{1} H\left(x_{1}, y\right)+\lambda_{2} H\left(x_{2}, y\right) \quad x_{1}, x_{2}, y \in V \quad \lambda_{1}, \lambda_{2} \in R  \tag{1.2.6}\\
\overline{H(x, y)}=H(y, x) \quad,  \tag{1.2.7}\\
H(J x, y)=i H(x, y) \Longleftrightarrow H(x, J y)=-i H(x, y) \tag{1.2.8}
\end{gather*}
$$

By using the split of $H(x, y)$ into its real and imaginary parts

$$
\begin{equation*}
H(x, y)=F(x, y)+i G(x, y), \tag{1.2.9}
\end{equation*}
$$

conditions (1.2.7)-( 1.2.8) may be re-expressed as

$$
\begin{gather*}
F(x, y)=F(y, x) \quad, \quad G(x, y)=-G(y, x)  \tag{1.2.10}\\
F(x, y)=G(J x, y) \quad, \quad G(x, y)=-F(J x, y) \tag{1.2.11}
\end{gather*}
$$

If $M$ is a $C^{\infty}$ manifold of dimension $n$, and if $T_{x}$ and $T_{x}^{*}$ are tangent and cotangent spaces respectively at $x \in M$, an almost complex structure on $M$ is a $C^{\infty}$ field of endomorphisms $J_{x}: T_{x} \rightarrow T_{x}$ such that $J_{x}^{2}=-1_{x}$, where $1_{x}$ is the identity endomorphism in $T_{x}$. A manifold with an almost complex structure is called almost complex. If a manifold is almost complex, it is even-dimensional and orientable. However, this is only a necessary condition. Examples can be found

## 1. Introduction to Complex Space-Time

(e.g. the four-sphere $S^{4}$ ) of even-dimensional, orientable manifolds which cannot be given an almost complex structure.

### 1.3 An Outline of This Work

Since this book is devoted to the geometry of complex space-time in spinor form, chapter two presents the basic ideas, methods and results of two-component spinor calculus. Such a calculus is described in terms of spin-space formalism, i.e. a complex vector space endowed with a symplectic form and some fundamental isomorphisms and anti-isomorphisms. These mathematical properties enable one to raise and lower indices, define the conjugation of spinor fields in Lorentzian or Riemannian four-geometries, translate tensor fields into spinor fields (or the other way around). The standard two-spinor form of the Riemann curvature tensor is then obtained by relying on the (more) familiar tensor properties of the curvature. The introductory analysis ends with the Petrov classification of space-times, expressed in terms of the Weyl spinor of conformal gravity.

Since the whole of twistor theory may be viewed as a holomorphic description of space-time geometry in a conformally invariant framework, chapter three studies the key results of conformal gravity, i.e. $C$-spaces, Einstein spaces and complex Einstein spaces. Hence a necessary and sufficient condition for a space-time to be conformal to a complex Einstein space is obtained, following Kozameh et al. 1985. Such a condition involves the Bach and Eastwood-Dighton spinors, and their occurrence is derived in detail. The difference between Lorentzian spacetimes, Riemannian four-spaces, complexified space-times and complex space-times is also analyzed.

Chapter four is a pedagogical introduction to twistor spaces, from the point of view of mathematical physics and relativity theory. This is obtained by defining twistors as $\alpha$-planes in complexified compactified Minkowski space-time, and as $\alpha$-surfaces in curved space-time. In the former case, one deals with totally null

## 1. Introduction to Complex Space-Time

two-surfaces, in that the complexified Minkowski metric vanishes on any pair of null tangent vectors to the surface. Hence such null tangent vectors have the form $\lambda^{A} \pi^{A^{\prime}}$, where $\lambda^{A}$ is varying and $\pi^{A^{\prime}}$ is covariantly constant. This definition can be generalized to complex or real Riemannian four-manifolds, providing the Weyl curvature is anti-self-dual. An alternative definition of twistors in Minkowski spacetime is instead based on the vector space of solutions of a differential equation, which involves the symmetrized covariant derivative of an unprimed spinor field. Interestingly, a deep correspondence exists between flat space-time and twistor space. Hence complex space-time points correspond to spheres in the so-called projective twistor space, and this concept is made precise. Sheaf cohomology is then presented as the mathematical tool necessary to describe a conformally invariant isomorphism between the complex vector space of holomorphic solutions of the wave equation on the forward tube of flat space-time, and the complex vector space of complex-analytic functions of three variables. These are arbitrary, in that they are not subject to any differential equation. In the end, Ward's one-to-one correspondence between complex space-times with non-vanishing cosmological constant, and sufficiently small deformations of flat projective twistor space, is presented.

An example of explicit construction of anti-self-dual space-time is given in chapter five, following Ward 1978. This generalization of Penrose's non-linear graviton (Penrose 1976a-b) combines two-spinor techniques and twistor theory in a way very instructive for beginning graduate students. However, it appears necessary to go beyond anti-self-dual space-times, since they are only a particular class of (complex) space-times, and they do not enable one to recover the full physical content of (complex) general relativity. This implies going beyond the original twistor theory, since the three-complex-dimensional space of $\alpha$-surfaces only exists in anti-self-dual space-times. After a brief review of alternative ideas, attention is focused on the recent attempt by Roger Penrose to define twistors as charges for massless spin- $\frac{3}{2}$ fields. Such an approach has been considered since a vanishing Ricci tensor provides the consistency condition for the existence and propagation of

## 1. Introduction to Complex Space-Time

massless helicity- $\frac{3}{2}$ fields in curved space-time. Moreover, in Minkowski space-time the space of charges for such fields is naturally identified with the corresponding twistor space. The resulting geometrical scheme in the presence of curvature is as follows. First, define a twistor for Ricci-flat space-time. Second, characterize the resulting twistor space. Third, reconstruct the original Ricci-flat space-time out of such a twistor space. One of the main technical difficulties of the program proposed by Penrose is to obtain a global description of the space of potentials for massless spin $-\frac{3}{2}$ fields. The corresponding local theory is instead used, for other purposes, in our chapter eight (see below).

The two-spinor description of complex space-times with torsion is given in chapter six. These space-times are studied since torsion is a naturally occurring geometric property of relativistic theories of gravitation, the gauge theory of the Poincaré group leads to its presence and the occurrence of cosmological singularities can be less generic than in general relativity (Esposito 1994 and references therein). It turns out that, before studying the complex theory, many differences already arise, since the Riemann tensor has 36 independent real components at each point (Penrose 1983), rather than 20 as in general relativity. This happens since the connection is no longer symmetric. Hence the Ricci tensor acquires an anti-symmetric part, and the reality conditions for the trace-free part of Ricci and for the scalar curvature no longer hold. Hence, on taking a complex space-time with non-vanishing torsion, all components of the Riemann curvature are given by independent spinor fields and scalar fields, not related by any conjugation. Torsion is, itself, described by two independent spinor fields. The corresponding integrability condition for $\alpha$-surfaces is shown to involve the self-dual Weyl spinor, the torsion spinor with three primed indices and one unprimed index (in a non-linear way), and covariant derivatives of such a torsion spinor. The key identities of two-spinor calculus within this framework, including in particular the spinor Ricci identities, are derived in a self-consistent way for pedagogical reasons.

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The last chapters of our monograph are devoted to the application of twospinor techniques to problems motivated by supersymmetry and quantum cosmology. For this purpose, chapter seven studies spin- $\frac{1}{2}$ fields in real Riemannian fourgeometries. After deriving the Dirac and Weyl equations in two-component spinor form in Riemannian backgrounds, we focus on boundary conditions for massless fermionic fields motivated by local supersymmetry. These involve the normal to the boundary and a pair of independent spinor fields $\Psi^{A}$ and $\widetilde{\boldsymbol{\psi}}^{A^{\prime}}$. In the case of flat Euclidean four-space bounded by a three-sphere, they imply that the classical modes of the massless spin- $\frac{1}{2}$ field multiplying harmonics having positive eigenvalues for the intrinsic three-dimensional Dirac operator on $S^{3}$ should vanish on $S^{3}$. Remarkably, this coincides with the property of the classical boundary-value problem when global boundary conditions are imposed on the three-sphere in the massless case. The boundary term in the action functional is also derived. Our analysis makes it necessary to use part of the analysis in section 5.8 of Esposito 1994, to prove that the Dirac operator subject to supersymmetric boundary conditions on the three-sphere admits self-adjoint extensions. The proof relies on the Euclidean conjugation and on a result originally proved by von Neumann for complex scalar fields. Chapter seven ends with a mathematical introduction to the global theory of the total Dirac operator in Riemannian four-geometries, described as a first-order elliptic operator mapping smooth sections (i.e. the spinor fields) of a complex vector bundle to smooth sections of the same bundle. Its action on the sections is obtained by composition of Clifford multiplication with covariant differentiation, and provides an intrinsic formulation of the spinor covariant derivative frequently used in our monograph.

The local theory of potentials for massless spin- $\frac{3}{2}$ fields is applied to the classical boundary-value problems relevant for quantum cosmology in chapter eight (cf. chapter five). For this purpose, we first study local boundary conditions involving field strengths and the normal to the boundary, originally considered in anti-de Sitter space-time, and recently applied in one-loop quantum cosmology. First, following Esposito 1994 and Esposito and Pollifrone 1994, we derive the conditions

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under which spin-lowering and spin-raising operators preserve these local boundary conditions on a three-sphere for fields of $\operatorname{spin} 0, \frac{1}{2}, 1, \frac{3}{2}$ and 2 . Second, the twocomponent spinor analysis of the four Dirac potentials of the totally symmetric and independent field strengths for spin $\frac{3}{2}$ is applied to the case of a three-sphere boundary. It is found that such boundary conditions can only be imposed in a flat Euclidean background, for which the gauge freedom in the choice of the potentials remains. Third, we study the alternative, Rarita-Schwinger form of the spin- $\frac{3}{2}$ potentials. They are no longer symmetric in the pair of unprimed or primed spinor indices, and their gauge freedom involves a spinor field which is no longer a solution of the Weyl equation. By requiring that also the gauge-related potentials should obey the same differential equations (Aichelburg and Urbantke 1981), one finds a set of compatibility equations, finally expressed as a first-order system of spinor equations. On studying boundary conditions for the Rarita-Schwinger potentials compatible with Becchi-Rouet-Stora-Tyutin invariance and local supersymmetry, one finds equations and boundary conditions for the admissible background four-geometries. Interestingly, it is now possible to use perturbation theory about Einstein backgrounds, i.e. such that their Ricci tensor is proportional to the four-metric. The Rarita-Schwinger potentials may be supplemented by secondary potentials recently introduced by Penrose in Ricci-flat space-times. The Penrose construction is here generalized to curved four-dimensional Riemannian backgrounds with boundary. Remarkably, the traces of the secondary potentials are proportional to the spinor fields corresponding to the Majorana field of the Lorentzian version of the theory, while the symmetric parts of such potentials depend on the conformal curvature, the trace-free part of the Ricci spinor, and the cosmological constant.

The mathematical foundations of twistor theory are re-analyzed in chapter nine. After a review of various definitions of twistors in curved space-time, we present the Penrose transform and the ambitwistor correspondence in terms of the double-fibration picture. The Radon transform in complex geometry is also defined, and the Ward construction of massless fields as bundles is given. The

## 1. Introduction to Complex Space-Time

latter concept has motivated the recent work by Penrose and by the author and his collaborators on secondary potentials which supplement the Rarita-Schwinger potentials in curved space-time. Recent progress on quantum field theories in the presence of boundaries is finally described, since the boundary conditions of chapters seven and eight are relevant for the analysis of mixed boundary conditions in quantum field theory and quantum gravity.

## TWO-COMPONENT SPINOR CALCULUS


#### Abstract

Spinor calculus is presented by relying on spin-space formalism. Given the existence of unprimed and primed spin-space, one has the isomorphism between such vector spaces and their duals, realized by a symplectic form. Moreover, for Lorentzian metrics, complex conjugation is the anti-isomorphism between unprimed and primed spin-space. Finally, for any space-time point, its tangent space is isomorphic to the tensor product of unprimed and primed spin-spaces via the Infeld-van der Waerden symbols. Hence the correspondence between tensor fields and spinor fields. Euclidean conjugation in Riemannian geometries is also discussed in detail. The Maxwell field strength is written in this language, and many useful identities are given. The curvature spinors of general relativity are then constructed explicitly, and the Petrov classification of space-times is obtained in terms of the Weyl spinor for conformal gravity.


## 2. Two-Component Spinor Calculus

### 2.1 Two-Component Spinor Calculus

Two-component spinor calculus is a powerful tool for studying classical field theories in four-dimensional space-time models. Within this framework, the basic object is spin-space, a two-dimensional complex vector space $S$ with a symplectic form $\epsilon$, i.e. an antisymmetric complex bilinear form. Unprimed spinor indices $A, B, \ldots$ take the values 0,1 whereas primed spinor indices $A^{\prime}, B^{\prime}, \ldots$ take the values 0 ', 1 ' since there are actually two such spaces: unprimed spin-space ( $S, \in$ ) and primed spin-space $\left(S^{\prime}, \epsilon^{\prime}\right)$. The whole two-spinor calculus in Lorentzian fourmanifolds relies on three fundamental properties (Penrose and Rindler 1984, Ward and Wells 1990, Esposito 1992, Esposito 1994):
(i) The isomorphism between $\left(S, \in_{A B}\right)$ and its dual $\left(S^{*}, \in{ }^{A B}\right)$. This is provided by the symplectic form $\in$, which raises and lowers indices according to the rules

$$
\begin{align*}
& \epsilon^{A B} \varphi_{B}=\varphi^{A} \in S,  \tag{2.1.1}\\
& \varphi^{B} \in_{B A}=\varphi_{A} \in S^{*} . \tag{2.1.2}
\end{align*}
$$

Thus, since

$$
\epsilon_{A B}=\epsilon^{A B}=\left(\begin{array}{cc}
0 & 1  \tag{2.1.3}\\
-1 & 0
\end{array}\right)
$$

one finds in components $\varphi^{0}=\varphi_{1}, \varphi^{1}-\varphi_{0}$.
Similarly, one has the isomorphism $\left(S^{\prime}, \in_{A^{\prime} B^{\prime}}\right) \cong\left(\left(S^{\prime}\right)^{*}, \in^{A^{\prime} B^{\prime}}\right)$, which implies

$$
\begin{gather*}
\epsilon^{A^{\prime} B^{\prime}} \varphi_{B^{\prime}}=\varphi^{A^{\prime}} \in S^{\prime},  \tag{2.1.4}\\
\varphi^{B^{\prime}} \in B_{B^{\prime} A^{\prime}}=\varphi_{A^{\prime}} \in\left(S^{\prime}\right)^{*}, \tag{2.1.5}
\end{gather*}
$$

where

$$
\boldsymbol{\epsilon}_{A^{\prime} B^{\prime}}=\epsilon^{\boldsymbol{A}^{\prime} \boldsymbol{B}^{\prime}}=\left(\begin{array}{cc}
0^{\prime} & 1^{\prime}  \tag{2.1.6}\\
-1^{\prime} & 0^{\prime}
\end{array}\right)
$$

## 2. Two-Component Spinor Calculus

(ii) The anti-isomorphism between $\left(S, \in_{A B}\right)$ and $\left(S^{\prime}, \in_{A^{\prime} B^{\prime}}\right)$, called complex conjugation, and denoted by an overbar. According to a standard convention, one has

$$
\begin{align*}
& \overline{\psi^{A}} \equiv \bar{\psi}^{A^{\prime}} \in S^{\prime}  \tag{2.1.7}\\
& \overline{\psi^{A^{\prime}}} \equiv \bar{\psi}^{A} \in S \tag{2.1.8}
\end{align*}
$$

Thus, complex conjugation maps elements of a spin-space to elements of the complementary spin-space. Hence we say it is an anti-isomorphism. In components, if $w^{A}$ is thought as $w^{A}=\binom{\alpha}{\beta}$, the action of (2.1.7) leads to

$$
\begin{equation*}
\overline{w^{\boldsymbol{A}}} \equiv \bar{w}^{A^{\prime}} \equiv\left(\frac{\bar{\alpha}}{\bar{\beta}}\right) \tag{2.1.9}
\end{equation*}
$$

whereas, if $z^{A^{\prime}}=\binom{\gamma}{\delta}$, then (2.1.8) leads to

$$
\begin{equation*}
\overline{z^{A^{\prime}}} \equiv \bar{z}^{A}=\binom{\bar{\gamma}}{\delta} \tag{2.1.10}
\end{equation*}
$$

With our notation, $\bar{\alpha}$ denotes complex conjugation of the function $\alpha$, and so on. Note that the symplectic structure is preserved by complex conjugation, since $\bar{\epsilon}_{A^{\prime} B^{\prime}}=\boldsymbol{\epsilon}_{A^{\prime} B^{\prime}}$.
(iii) The isomorphism between the tangent space $T$ at a point of space-time and the tensor product of the unprimed spin-space $\left(S, \in_{A B}\right)$ and the primed spin$\operatorname{space}\left(S^{\prime}, \epsilon_{A}{ }^{\prime}{ }_{B}\right)$ :

$$
\begin{equation*}
T \cong(S, \in A B) \otimes\left(S^{\prime}, \in_{A^{\prime} B^{\prime}}\right) \tag{2.1.11}
\end{equation*}
$$

The Infeld-van der Waerden symbols $\sigma^{a}{ }_{A A}$, and $\sigma_{a}{ }^{A A^{\prime}}$ express this isomorphism, and the correspondence between a vector $v^{a}$ and a spinor $v^{A A^{\prime}}$ is given by

$$
\begin{equation*}
v^{A A^{\prime}} \equiv v^{a} \sigma_{a}^{A A^{\prime}} \tag{2.1.12}
\end{equation*}
$$

## 2. Two-Component Spinor Calculus

$$
\begin{equation*}
v^{a} \equiv v^{A A^{\prime}} \sigma_{A A^{\prime}}^{a} \tag{2.1.13}
\end{equation*}
$$

These mixed spinor-tensor symbols obey the identities

$$
\begin{gather*}
\bar{\sigma}_{a} A A^{\prime}=\sigma_{a} A A^{\prime}  \tag{2.1.14}\\
\sigma_{a}{ }^{A A^{\prime}} \sigma_{A A^{\prime}}^{b}=\delta_{a}^{b},  \tag{2.1.15}\\
\sigma_{a}{ }^{A A^{\prime}} \sigma_{B B^{\prime}}^{a}=\epsilon_{B}{ }^{A} \epsilon_{B^{\prime}}^{A^{\prime}},  \tag{2.1.16}\\
\sigma_{[a}^{A A^{\prime}} \sigma_{b] A}{ }^{B^{\prime}}=-\frac{i}{2} \epsilon_{a b c d} \sigma^{c A A^{\prime}} \sigma_{A}^{d} B^{\prime} \tag{2.1.17}
\end{gather*}
$$

Similarly, a one-form $\omega_{a}$ has a spinor equivalent

$$
\begin{equation*}
\omega_{A A^{\prime}} \equiv \omega_{a} \sigma_{A A^{\prime}}^{a} \tag{2.1.18}
\end{equation*}
$$

whereas the spinor equivalent of the metric is

$$
\begin{equation*}
\eta_{a b} \sigma_{A A^{\prime}}^{a} \sigma_{B B^{\prime}}^{b} \equiv \epsilon_{A B} \in_{A^{\prime} B^{\prime}} . \tag{2.1.19}
\end{equation*}
$$

In particular, in Minkowski space-time Eqs. (2.1.12) and (2.1.17) enable one to write down a coordinate system in $2 \times 2$ matrix form

$$
x^{A A^{\prime}}=\frac{1}{\sqrt{2}}\left(\begin{array}{cc}
x^{0}+x^{3} & x^{1}-i x^{2}  \tag{2.1.20}\\
x^{1}+i x^{2} & x^{0}-x^{3}
\end{array}\right)
$$

In the Lorentzian-signature case, the Maxwell two-form $F \equiv F_{a b} d x^{a} \wedge d x^{b}$ can be written spinorially (Ward and Wells 1990) as

$$
\begin{equation*}
F_{A A^{\prime} B B^{\prime}}=\frac{1}{2}\left(F_{A A^{\prime} B B^{\prime}}-F_{B B^{\prime} A A^{\prime}}\right)=\varphi_{A B} \epsilon_{A^{\prime} B^{\prime}}+\varphi_{A^{\prime} B^{\prime}} \epsilon_{A B}, \tag{2.1.21}
\end{equation*}
$$

where

$$
\begin{gather*}
\varphi_{A B} \equiv \frac{1}{2} F_{A C^{\prime} B^{\prime}} C^{\prime}=\varphi_{(A B)}  \tag{2.1.22}\\
\varphi_{A^{\prime} B^{\prime}} \equiv \frac{1}{2} F_{C B^{\prime} A_{A^{\prime}}}=\varphi_{\left(A^{\prime} B^{\prime}\right)} \tag{2.1.23}
\end{gather*}
$$

## 2. Two-Component Spinor Calculus

These formulae are obtained by applying the identity

$$
\begin{equation*}
T_{A B}-T_{B A}=\in_{A B} T_{C}^{C} \tag{2.1.24}
\end{equation*}
$$

to express $\frac{1}{2}\left(F_{A A^{\prime} B B^{\prime}}-F_{A B^{\prime} B A^{\prime}}\right)$ and $\frac{1}{2}\left(F_{A B^{\prime} B A^{\prime}}-F_{B B^{\prime} A A^{\prime}}\right)$. Note also that round brackets $(A B)$ denote (as usual) symmetrization over the spinor indices $A$ and $B$, and that the antisymmetric part of $\varphi_{A B}$ vanishes by virtue of the antisymmetry of $F_{a b}$, since (Ward and Wells 1990) $\varphi_{[A B]}=\frac{1}{4} \epsilon_{A B} F_{C C^{\prime}}{ }^{\prime} C^{\prime}=$ $\frac{1}{2} \in_{A B} \eta^{c d} F_{c d}=0$. Last but not least, in the Lorentzian case

$$
\begin{equation*}
\overline{\varphi_{A B}} \equiv \bar{\varphi}_{A^{\prime} B^{\prime}}=\varphi_{A^{\prime} B^{\prime}} \tag{2.1.25}
\end{equation*}
$$

The symmetric spinor fields $\varphi_{A B}$ and $\varphi_{A^{\prime} B^{\prime}}$ are the anti-self-dual and self-dual parts of the curvature two-form, respectively.

Similarly, the Weyl curvature $C^{a}{ }_{b c d}$, i.e. the part of the Riemann curvature tensor invariant under conformal rescalings of the metric, may be expressed spinorially, omitting soldering forms (see below) for simplicity of notation, as

$$
\begin{equation*}
C_{a b c d}=\psi_{A B C D} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}}+\bar{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D} \tag{2.1.26}
\end{equation*}
$$

In canonical gravity (Ashtekar 1988, Esposito 1994) two-component spinors lead to a considerable simplification of calculations. Denoting by $n^{\mu}$ the futurepointing unit timelike normal to a spacelike three-surface, its spinor version obeys the relations

$$
\begin{align*}
& n_{A A^{\prime}} e_{i}^{A A^{\prime}}=0  \tag{2.1.27}\\
& n_{A A^{\prime}} n^{A A^{\prime}}=1 \tag{2.1.28}
\end{align*}
$$

where $e^{A A^{\prime}} \equiv e^{a}{ }_{\mu} \sigma_{a}{ }^{A A^{\prime}}$ is the two-spinor version of the tetrad, often referred to in the literature as soldering form (Ashtekar 1988). Denoting by $h$ the induced metric on the three-surface, other useful relations are (Esposito 1994)

$$
\begin{equation*}
h_{i j}=-e_{A A^{\prime} i} e^{A A^{\prime}}, \tag{2.1.29}
\end{equation*}
$$

$$
\begin{gather*}
e_{0}^{A A^{\prime}}=N n^{A A^{\prime}}+N^{i} e_{i}^{A A_{i}^{\prime}}  \tag{2.1.30}\\
\boldsymbol{n}_{\boldsymbol{A} \boldsymbol{A}^{\prime}} \boldsymbol{n}^{\boldsymbol{B} \boldsymbol{A}^{\prime}}=\frac{1}{2} \boldsymbol{\epsilon}_{\boldsymbol{A}}^{\boldsymbol{B}}  \tag{2.1.31}\\
n_{\boldsymbol{A} \boldsymbol{A}^{\prime}} \boldsymbol{n}^{\boldsymbol{A} \boldsymbol{B}^{\prime}}=\frac{1}{2} \boldsymbol{\epsilon}_{\boldsymbol{A}^{\prime}}^{\boldsymbol{B}^{\prime}}  \tag{2.1.32}\\
n_{\left[E B^{\prime}\right.} \boldsymbol{n}_{\boldsymbol{A}] \boldsymbol{A}^{\prime}}=\frac{1}{4} \boldsymbol{\epsilon}_{\boldsymbol{E} \boldsymbol{A}} \boldsymbol{\epsilon}_{\boldsymbol{B}^{\prime} \boldsymbol{A}^{\prime}} \tag{2.1.33}
\end{gather*}
$$

$$
\begin{equation*}
e_{A A^{\prime} j} e_{k}^{A B^{\prime}}=-\frac{1}{2} h_{j k} \epsilon_{A^{\prime}}^{B^{\prime}}-i \epsilon_{j k l} \sqrt{\operatorname{det} h} n_{A A^{\prime}} e^{A B^{\prime} t} \tag{2.1.34}
\end{equation*}
$$

In Eq. (2.1.30), $N$ and $N^{i}$ are the lapse and shift functions respectively (Esposito 1994).

To obtain the space-time curvature, we first need to define the spinor covariant derivative $\nabla_{A A^{\prime}}$. If $\theta, \phi, \psi$ are spinor fields, $\nabla_{A A^{\prime}}$ is a map such that (Penrose and Rindler 1984, Stewart 1991)
(1) $\nabla_{A A^{\prime}}(\theta+\phi)=\nabla_{A A^{\prime}} \theta+\nabla_{A A^{\prime}} \phi$ (i.e. linearity).
(2) $\nabla_{A A^{\prime}}(\theta \psi)=\left(\nabla_{A A^{\prime}} \theta\right) \psi+\theta\left(\nabla_{A A^{\prime}} \psi\right)$ (i.e. Leibniz rule).
(3) $\psi=\nabla_{A A^{\prime}} \theta$ implies $\overline{\boldsymbol{\psi}}=\nabla_{A A} \overline{\boldsymbol{\theta}}$ (i.e. reality condition).
(4) $\nabla_{A A^{\prime}} \epsilon_{B C}=\nabla_{A A^{\prime}} \in^{B C}=0$, i.e. the symplectic form may be used to raise or lower indices within spinor expressions acted upon by $\nabla_{A A^{\prime}}$, in addition to the usual metricity condition $\nabla g=0$, which involves instead the product of two $\epsilon$-symbols (see also section 6.3).
(5) $\nabla_{A A^{\prime}}$ commutes with any index substitution not involving $A, A^{\prime}$.
(6) For any function $f$, one finds $\left(\nabla_{a} \nabla_{b}-\nabla_{b} \nabla_{a}\right) f=2 S_{a}{ }^{c} \nabla_{c} f$, where $S_{a b}{ }^{c}$ is the torsion tensor.
(7) For any derivation $D$ acting on spinor fields, a spinor field $\xi^{A A^{\prime}}$ exists such that $D \psi=\xi^{A A^{\prime}} \nabla_{A A^{\prime}} \psi, \forall \psi$.

## 2. Two-Component Spinor Calculus

As proved in Penrose and Rindler 1984, such a spinor covariant derivative exists and is unique.

If Lorentzian space-time is replaced by a complex or real Riemannian fourmanifold, an important modification should be made, since the anti-isomorphism between unprimed and primed spin-space no longer exists. This means that primed spinors can no longer be regarded as complex conjugates of unprimed spinors, or viceversa, as in (2.1.7)-(2.1.8). In particular, Eqs. (2.1.21) and (2.1.26) should be re-written as

$$
\begin{gather*}
F_{A A^{\prime} B B^{\prime}}=\varphi_{A B} \epsilon_{A^{\prime} B^{\prime}}+\widetilde{\varphi}_{A^{\prime} B^{\prime}} \epsilon_{A B}  \tag{2.1.35}\\
\psi_{A B C D} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}}+\widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D} \tag{2.1.36}
\end{gather*}
$$

With our notation, $\varphi_{A B}, \widetilde{\varphi}_{A^{\prime} B^{\prime}}$, as well as $\psi_{A B C D}, \widetilde{\boldsymbol{\psi}}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}$ are completely independent symmetric spinor fields, not related by any conjugation.

Indeed, a conjugation can still be defined in the real Riemannian case, but it no longer relates $\left(S, \in_{A B}\right)$ to $\left(S^{\prime}, \epsilon_{A^{\prime} B^{\prime}}\right)$. It is instead an anti-involutory operation which maps elements of a spin-space (either unprimed or primed) to elements of the same spin-space. By anti-involutory we mean that, when applied twice to a spinor with an odd number of indices, it yields the same spinor with the opposite sign, i.e. its square is minus the identity, whereas the square of complex conjugation as defined in (2.1.9)-(2.1.10) equals the identity. Following Woodhouse 1985 and Esposito 1994, Euclidean conjugation, denoted by a dagger, is defined as follows:

$$
\begin{align*}
& \left(w^{A}\right)^{\dagger} \equiv\binom{\bar{\beta}}{-\bar{\alpha}},  \tag{2.1.37}\\
& \left(z^{A^{\prime}}\right)^{\dagger} \equiv\binom{-\bar{\delta}}{\bar{\gamma}} \tag{2.1.38}
\end{align*}
$$

This means that, in flat Euclidean four-space, a unit $2 \times 2$ matrix $\delta_{B A^{\prime}}$ exists such that

$$
\begin{equation*}
\left(w^{A}\right)^{\dagger} \equiv \epsilon^{A B} \delta_{B A^{\prime}} \bar{w}^{A^{\prime}} \tag{2.1.39}
\end{equation*}
$$

## 2. Two-Component Spinor Calculus

We are here using the freedom to regard $w^{A}$ either as an $S L(2, C)$ spinor for which complex conjugation can be defined, or as an $S U(2)$ spinor for which Euclidean conjugation is instead available. The soldering forms for $S U(2)$ spinors only involve spinor indices of the same spin-space, i.e. $\widetilde{\boldsymbol{e}}_{\boldsymbol{i}}{ }^{A B}$ and $\widetilde{\boldsymbol{e}}_{\boldsymbol{i}}{ }^{A^{\prime} B^{\prime}}$ (cf. Ashtekar 1991). More precisely, denoting by $E_{a}^{i}$ a real triad, where $i=1,2,3$, and by $\tau^{a}{ }_{A}{ }^{B}$ the three Pauli matrices obeying the identity

$$
\begin{equation*}
\tau^{a}{ }_{A}^{B} \tau^{b}{ }_{B}^{D}=i \in \epsilon^{a b c} \tau_{c A}{ }^{D}+\delta^{a b} \delta_{A}^{D}, \tag{2.1.40}
\end{equation*}
$$

the $S U(2)$ soldering forms are defined by

$$
\begin{equation*}
\tilde{e}_{A}^{j} B \equiv-\frac{i}{\sqrt{2}} E_{a}^{j} \tau_{A}^{a} B \tag{2.1.41}
\end{equation*}
$$

Note that our conventions differ from the ones in Ashtekar 1991, i.e. we use $\widetilde{\boldsymbol{e}}$ instead of $\sigma$, and $a, b$ for Pauli-matrix indices, $i, j$ for tangent-space indices on a three-manifold $\sum$, to agree with our previous notation. The soldering form in (2.1.41) provides an isomorphism between the three-real-dimensional tangent space at each point of $\Sigma$, and the three-real-dimensional vector space of $2 \times 2$ trace-free Hermitian matrices. The Riemannian three-metric on $\sum$ is then given by

$$
\begin{equation*}
h^{i j}=-\widetilde{e}_{A}^{i} \tilde{e}_{B}^{A} \tag{2.1.42}
\end{equation*}
$$

### 2.2 Curvature in General Relativity

In this section, following Penrose and Rindler 1984, we want to derive the spinorial form of the Riemann curvature tensor in a Lorentzian space-time with vanishing torsion, starting from the well-known symmetries of Riemann. In agreement with the abstract-index translation of tensors into spinors, soldering forms will be omitted in the resulting equations (cf. Ashtekar 1991).

## 2. Two-Component Spinor Calculus

Since $R_{a b c d}=-R_{b a c d}$ we may write

$$
\begin{align*}
R_{a b c d} & =R_{A A^{\prime} B B^{\prime} C C^{\prime} D D^{\prime}} \\
& =\frac{1}{2} R_{A F^{\prime}} \boldsymbol{F}^{\prime \prime}{ }_{c d} \epsilon_{A^{\prime} B^{\prime}}+\frac{1}{2} R_{F A^{\prime}} F_{B^{\prime} c d} \epsilon_{A B} \tag{2.2.1}
\end{align*} .
$$

Moreover, defining

$$
\begin{align*}
& X_{A B C D} \equiv \frac{1}{4} R_{A F^{\prime} B} F_{C L^{\prime} D} L^{\prime},  \tag{2.2.2}\\
& \Phi_{A B C^{\prime} D^{\prime}} \equiv \frac{1}{4} R_{A F^{\prime} B}{ }^{F^{\prime}}{ }_{L C^{\prime}}{ }^{L} D^{\prime}, \tag{2.2.3}
\end{align*}
$$

the anti-symmetry in $c d$ leads to

$$
\begin{align*}
R_{a b c d} & =X_{A B C D} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}}+\Phi_{A B C^{\prime} D^{\prime}} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C D} \\
& +\bar{\Phi}_{A^{\prime} B^{\prime} C D} \epsilon_{A B} \epsilon_{C^{\prime} D^{\prime}}+\bar{X}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D} \tag{2.2.4}
\end{align*}
$$

According to a standard terminology, the spinors (2.2.2)-(2.2.3) are called the curvature spinors. In the light of the (anti-)symmetries of $R_{a b c d}$, they have the following properties:

$$
\begin{gather*}
X_{A B C D}=X_{(A B)(C D)}  \tag{2.2.5}\\
\Phi_{A B C^{\prime} D^{\prime}}=\Phi_{(A B)\left(C^{\prime} D^{\prime}\right)}  \tag{2.2.6}\\
X_{A B C D}=X_{C D A B}  \tag{2.2.7}\\
\overline{\boldsymbol{\Phi}}_{A B C^{\prime} D^{\prime}}=\boldsymbol{\Phi}_{A B C^{\prime} D^{\prime}} \tag{2.2.8}
\end{gather*}
$$

Remarkably, Eqs. (2.2.6) and (2.2.8) imply that $\Phi_{A A^{\prime} B B^{\prime}}$ corresponds to a tracefree and real tensor:

$$
\begin{equation*}
\Phi_{a}^{a}=0 \quad, \quad \Phi_{A A^{\prime} B B^{\prime}}=\Phi_{a b}=\bar{\Phi}_{a b} \tag{2.2.9}
\end{equation*}
$$

Moreover, from Eqs. (2.2.5) and (2.2.7) one obtains

$$
\begin{equation*}
X_{A(B C)}{ }^{A}=0 \tag{2.2.10}
\end{equation*}
$$

## 2. Two-Component Spinor Calculus

Three duals of $R_{a b c d}$ exist which are very useful and are defined as follows:

$$
\begin{gather*}
R_{a b c d}^{*} \equiv \frac{1}{2} \epsilon_{c d}{ }^{p q} R_{a b p q}=i R_{A A^{\prime} B B^{\prime} C D^{\prime} D C^{\prime}},  \tag{2.2.11}\\
* R_{a b c d} \equiv \frac{1}{2} \epsilon_{a b}^{p q} R_{p q c d}=i R_{A B^{\prime} B A^{\prime} C C^{\prime} D D^{\prime}},  \tag{2.2.12}\\
{ }^{*} R_{a b c d}^{*} \equiv \frac{1}{4} \epsilon_{a b}{ }^{p q} \epsilon_{c d}{ }^{r s} R_{p q r s}=-R_{A B^{\prime} B A^{\prime} C D^{\prime} D C^{\prime}} . \tag{2.2.13}
\end{gather*}
$$

For example, in terms of the dual (2.2.11), the familiar equation $R_{a[b c d]}=0$ reads

$$
\begin{equation*}
R^{*}{ }_{a b}{ }^{b c}=0 . \tag{2.2.14}
\end{equation*}
$$

Thus, to derive the spinor form of the cyclic identity, one can apply (2.2.14) to the equation

$$
\begin{align*}
R_{a b c d}^{*} & =-i X_{A B C D} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}}+i \Phi_{A B C^{\prime} D^{\prime}} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C D} \\
& -i \bar{\Phi}_{A^{\prime} B^{\prime} C D} \epsilon_{A B} \epsilon_{C^{\prime} D^{\prime}}+i \bar{X}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D} \tag{2.2.15}
\end{align*}
$$

By virtue of (2.2.6) and (2.2.8) one thus finds

$$
\begin{equation*}
X_{A B}{ }^{B}{ }_{C} \epsilon_{A^{\prime} C^{\prime}}=\bar{X}_{A^{\prime} B^{\prime}}{ }^{B^{\prime}} C^{\prime} \epsilon_{A C} \tag{2.2.16}
\end{equation*}
$$

which implies, on defining

$$
\begin{equation*}
\Lambda \equiv \frac{1}{6} X_{A B}^{A B} \tag{2.2.17}
\end{equation*}
$$

the reality condition

$$
\begin{equation*}
\Lambda=\bar{\Lambda} \tag{2.2.18}
\end{equation*}
$$

Eq. (2.2.1) enables one to write down the Ricci tensor $R_{a b} \equiv R_{a c b}{ }^{c}$ in spinor form as

$$
\begin{equation*}
R_{a b}=6 \Lambda \epsilon_{A B} \in_{A^{\prime} B^{\prime}}-2 \Phi_{A B A^{\prime} B^{\prime}} . \tag{2.2.19}
\end{equation*}
$$

Thus, the resulting scalar curvature, trace-free part of Ricci and Einstein tensor are

$$
\begin{equation*}
R=24 \Lambda \tag{2.2.20}
\end{equation*}
$$

## 2. Two-Component Spinor Calculus

$$
\begin{gather*}
R_{a b}-\frac{1}{4} R g_{a b}=-2 \Phi_{a b}=-2 \Phi_{A B A^{\prime} B^{\prime}},  \tag{2.2.21}\\
G_{a b}=R_{a b}-\frac{1}{2} R g_{a b}=-6 \Lambda \epsilon_{A B} \epsilon_{A^{\prime} B^{\prime}}-2 \Phi_{A B A^{\prime} B^{\prime}}, \tag{2.2.22}
\end{gather*}
$$

respectively.
We have still to obtain a more suitable form of the Riemann curvature. For this purpose, following again Penrose and Rindler 1984, we point out that the curvature spinor $X_{A B C D}$ can be written as

$$
\begin{align*}
X_{A B C D} & =\frac{1}{3}\left(X_{A B C D}+X_{A C D B}+X_{A D B C}\right)+\frac{1}{3}\left(X_{A B C D}-X_{A C B D}\right) \\
& +\frac{1}{3}\left(X_{A B C D}-X_{A D C B}\right) \\
& =X_{(A B C D)}+\frac{1}{3} \epsilon_{B C} X_{A F} F_{D}+\frac{1}{3} \epsilon_{B D} X_{A F C}{ }^{F} . \tag{2.2.23}
\end{align*}
$$

Since $X_{A F C}^{F}=3 \Lambda \in_{A F}$, Eq. (2.2.23) leads to

$$
\begin{equation*}
X_{A B C D}=\psi_{A B C D}+\Lambda\left(\epsilon_{A C} \in_{B D}+\epsilon_{A D} \in B C\right) \tag{2.2.24}
\end{equation*}
$$

where $\psi_{A B C D}$ is the Weyl spinor.
Since $\Lambda=\bar{\Lambda}$ from (2.2.18), the insertion of (2.2.24) into (2.2.4), jointly with the identity

$$
\begin{equation*}
\epsilon_{A^{\prime} B^{\prime}} \in_{C^{\prime} D^{\prime}}+\epsilon_{A^{\prime} D^{\prime}} \epsilon_{B^{\prime} C^{\prime}}-\epsilon_{A^{\prime} C^{\prime}} \epsilon_{B^{\prime} D^{\prime}}=0 \tag{2.2.25}
\end{equation*}
$$

yields the desired decomposition of the Riemann curvature as

$$
\begin{align*}
R_{a b c d} & =\psi_{A B C D} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}}+\bar{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D} \\
& +\Phi_{A B C^{\prime} D^{\prime}} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C D}+\bar{\Phi}_{A^{\prime} B^{\prime} C D} \epsilon_{A B} \epsilon_{C^{\prime} D^{\prime}} \\
& +2 \Lambda\left(\epsilon_{A C} \epsilon_{B D} \epsilon_{A^{\prime} C^{\prime}} \epsilon_{B^{\prime} D^{\prime}}-\epsilon_{A D} \epsilon_{B C} \epsilon_{A^{\prime} D^{\prime}} \epsilon_{B^{\prime} C^{\prime}}\right) \tag{2.2.26}
\end{align*}
$$

With this standard notation, the conformally invariant part of the curvature takes the form $C_{a b c d}={ }^{-} C_{a b c d}+{ }^{+} C_{a b c d}$, where

$$
\begin{equation*}
{ }^{-} C_{a b c d} \equiv \psi_{A B C D} \in_{A^{\prime} B^{\prime}} \in C^{\prime} D^{\prime}, \tag{2.2.27}
\end{equation*}
$$

## 2. Two-Component Spinor Calculus

$$
\begin{equation*}
{ }^{+} C_{a b c d} \equiv \bar{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D}, \tag{2.2.28}
\end{equation*}
$$

are the anti-self-dual and self-dual Weyl tensors respectively.

### 2.3 Petrov Classification

Since the Weyl spinor is totally symmetric, we may use a well-known result of two-spinor calculus, according to which, if $\Omega_{A B \ldots L}$ is totally symmetric, then there exist univalent spinors $\alpha_{A}, \beta_{B}, \ldots, \gamma_{L}$ such that (Stewart 1991)

$$
\begin{equation*}
\Omega_{A B \ldots L}=\alpha_{(A} \beta_{B \ldots \gamma_{L)}} \tag{2.3.1}
\end{equation*}
$$

where $\alpha, \ldots, \gamma$ are called the principal spinors of $\Omega$, and the corresponding real null vectors are called the principal null directions of $\Omega$. In the case of the Weyl spinor, such a theorem implies that

$$
\begin{equation*}
\psi_{A B C D}=\alpha_{(A} \beta_{B} \gamma_{C} \delta_{D)} \tag{2.3.2}
\end{equation*}
$$

The corresponding space-times can be classified as follows (Stewart 1991).
(1) Type I. Four distinct principal null directions. Hence the name algebraically general.
(2) Type II. Two directions coincide. Hence the name algebraically special.
(3) Type D. Two different pairs of repeated principal null directions exist.
(4) Type III, i.e. three principal null directions coincide.
(5) Type $N$, i.e. all four principal null directions coincide.

Such a classification is the Petrov classification, and it provides a relevant example of the superiority of the two-spinor formalism in four space-time dimensions, since the alternative ways to obtain it are far more complicated.

## 2. Two- Component Spinor Calculus

Within this framework (as well as in chapter three) we need to know that $\psi_{A B C D}$ has two scalar invariants:

$$
\begin{gather*}
I \equiv \psi_{A B C D} \psi^{A B C D}  \tag{2.3.3}\\
J \equiv \psi_{A B}^{C D} \psi_{C D}^{E F} \psi_{E F}^{A B} \tag{2.3.4}
\end{gather*}
$$

Type-II space-times are such that $I^{3}=6 J^{2}$, while in type-III space-times $I=J=$ 0 . Moreover, type-D space-times are characterized by the condition

$$
\begin{equation*}
\psi_{P Q R(A} \psi_{B C}^{P Q} \psi_{D E F)}^{R}=0 \tag{2.3.5}
\end{equation*}
$$

while in type-N space-times

$$
\begin{equation*}
\psi_{(A B}^{E F} \psi_{C D) E F}=0 \tag{2.3.6}
\end{equation*}
$$

These results, despite their simplicity, are not well-known to many physicists and mathematicians. Hence they have been included also in this monograph, to prepare the ground for the more advanced topics of the following chapters.

## CONFORMAL GRAVITY


#### Abstract

Since twistor theory enables one to reconstruct the space-time geometry out of conformally invariant geometrical objects, it is important to know the basic tools for studying conformal gravity within the framework of general relativity. This is achieved by defining and using the Bach and Eastwood-Dighton tensors, here presented in two-spinor form (relying on previous work by Kozameh, Newman and Tod). After defining $C$-spaces and Einstein spaces, it is shown that a space-time is conformal to an Einstein space if and only if some equations involving the Weyl spinor, its covariant derivatives, and the trace-free part of Ricci are satisfied. Such a result is then extended to complex Einstein spaces. The conformal structure of infinity of Minkowski space-time is introduced in the end.


## 3. Conformal Gravity

## 3.1 $C$-Spaces

Twistor theory may be viewed as the attempt to describe fundamental physics in terms of conformally invariant geometrical objects within a holomorphic framework. Space-time points are no longer of primary importance, since they only appear as derived concepts out of such a scheme. To understand the following chapters, almost entirely devoted to twistor theory and its applications, it is therefore necessary to study the main results of the theory of conformal gravity. They can be understood by focusing on $C$-spaces, Einstein spaces, complex space-times and complex Einstein spaces, as we do from now on in this chapter.

To study $C$-spaces in a self-consistent way, we begin by recalling some basic properties of conformal rescalings. By definition, a conformal rescaling of the space-time metric $g$ yields the metric $\widehat{\boldsymbol{g}}$ as

$$
\begin{equation*}
\hat{g}_{a b}=e^{2 \omega} g_{a b}, \tag{3.1.1}
\end{equation*}
$$

where $\omega$ is a smooth scalar. Correspondingly, any tensor field $T$ of type $(r, s)$ is conformally weighted if

$$
\begin{equation*}
\widehat{T}=e^{k \omega} T \tag{3.1.2}
\end{equation*}
$$

for some integer $k$. In particular, conformal invariance of $T$ is achieved if $k=0$.
It is useful to know the transformation rules for covariant derivatives and Riemann curvature under the rescaling (3.1.1). For this purpose, defining

$$
\begin{equation*}
F_{a b}^{m} \equiv 2 \delta_{a}^{m} \nabla_{b} \omega-g_{a b} g^{m n} \nabla_{n} \omega \tag{3.1.3}
\end{equation*}
$$

one finds

$$
\begin{equation*}
\hat{\nabla}_{a} V_{b}=\nabla_{a} V_{b}-F_{a b}^{m} V_{m}, \tag{3.1.4}
\end{equation*}
$$

where $\widehat{\nabla}_{a}$ denotes covariant differentiation with respect to the metric $\widehat{g}$. Hence the Weyl tensor $C_{a b c}{ }^{d}$, the Ricci tensor $R_{a b} \equiv R_{c a b}{ }^{c}$ and the Ricci scalar transform as

$$
\begin{equation*}
\widehat{C}_{a b c}{ }^{d}=C_{a b c}{ }^{d}, \tag{3.1.5}
\end{equation*}
$$

## 3. Conformal Gravity

$$
\begin{gather*}
\widehat{R}_{a b}=R_{a b}+2 \nabla_{a} \omega_{b}-2 \omega_{a} \omega_{b}+g_{a b}\left(2 \omega^{c} \omega_{c}+\nabla^{c} \omega_{c}\right)  \tag{3.1.6}\\
\widehat{R}=e^{-2 \omega}\left[R+6\left(\nabla^{c} \omega_{c}+\omega^{c} \omega_{c}\right)\right] \tag{3.1.7}
\end{gather*}
$$

With our notation, $\omega_{\mathrm{c}} \equiv \nabla_{\mathrm{c}} \omega=\omega_{, c}$.
We are here interested in space-times which are conformal to $C$-spaces. The latter are a class of space-times such that

$$
\begin{equation*}
\widehat{\nabla}^{f} \widehat{C}_{a b c f}=0 \tag{3.1.8}
\end{equation*}
$$

By virtue of (3.1.3)-(3.1.4) one can see that the conformal transform of Eq. (3.1.8) is

$$
\begin{equation*}
\nabla^{f} C_{a b c d}+\omega^{f} C_{a b c f}=0 \tag{3.1.9}
\end{equation*}
$$

This is the necessary and sufficient condition for a space-time to be conformal to a $C$-space. Its two-spinor form is

$$
\begin{equation*}
\nabla^{F A^{\prime}} \psi_{F B C D}+\omega^{F A^{\prime}} \psi_{F B C D}=0 \tag{3.1.10}
\end{equation*}
$$

However, note that only a real solution $\omega^{F A^{\prime}}$ of (3.1.10) satisfies (3.1.9). Hence, whenever we use (3.1.10), we are also imposing a reality condition (Kozameh et al. 1985).

On using the invariants defined in (2.3.3)-(2.3.4), one finds the useful identities

$$
\begin{gather*}
\psi_{A B C D} \psi^{A B C E}=\frac{1}{2} I \delta_{D}^{E}  \tag{3.1.11}\\
\psi_{A B C D} \psi_{P Q}^{A B} \psi^{P Q C E}=\frac{1}{2} J \delta_{D}^{E} \tag{3.1.12}
\end{gather*}
$$

The idea is now to act with $\psi^{A B C D}$ on the left-hand side of (3.1.10) and then use (3.1.11) when $I \neq 0$. This leads to

$$
\begin{equation*}
\omega^{A A^{\prime}}=-\frac{2}{I} \psi^{A B C D} \nabla^{F A^{\prime}} \psi_{F B C D} \tag{3.1.13}
\end{equation*}
$$

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By contrast, when $I=0$ but $J \neq 0$, we multiply twice Eq. (3.1.10) by the Weyl spinor and use (3.1.12). Hence one finds

$$
\begin{equation*}
\omega^{A A^{\prime}}=-\frac{2}{J} \psi_{E D}^{C D} \psi^{E F G A} \nabla^{B A^{\prime}} \psi_{B C D G} . \tag{3.1.14}
\end{equation*}
$$

Thus, by virtue of (3.1.13), the reality condition $\omega^{A A^{\prime}}=\overline{\boldsymbol{\omega}^{\boldsymbol{A A}}}=\bar{\omega}^{\boldsymbol{A} \boldsymbol{A}^{\prime}}$ implies

$$
\begin{equation*}
\bar{I} \psi^{A B C D} \nabla^{F A^{\prime}} \psi_{F B C D}-I \bar{\psi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \nabla^{A F^{\prime}} \bar{\psi}_{F^{\prime} B^{\prime} C^{\prime} D^{\prime}}=0 \tag{3.1.15}
\end{equation*}
$$

We have thus shown that a space-time is conformally related to a $C$-space if and only if Eq. (3.1.10) holds for some vector $\omega^{D D^{\prime}}=K^{D D^{\prime}}$, and Eq. (3.1.15) holds as well.

### 3.2 Einstein Spaces

By definition, Einstein spaces are such that their Ricci tensor is proportional to the metric: $R_{a b}=\lambda g_{a b}$. A space-time is conformal to an Einstein space if and only if a function $\omega$ exists (see (3.1.1)) such that (cf. (3.1.6))

$$
\begin{equation*}
R_{a b}+2 \nabla_{a} \omega_{b}-2 \omega_{a} \omega_{b}-\frac{1}{4} T g_{a b}=0 \tag{3.2.1}
\end{equation*}
$$

where

$$
\begin{equation*}
T \equiv R+2 \nabla^{c} \omega_{c}-2 \omega^{c} \omega_{c} \tag{3.2.2}
\end{equation*}
$$

Of course, Eq. (3.2.1) leads to restrictions on the metric. These are obtained by deriving the corresponding integrability conditions. For this purpose, on taking the curl of Eq. (3.2.1) and using the Bianchi identities, one finds

$$
\nabla^{f} C_{a b c f}+\omega^{f} C_{a b c f}=0
$$

## 3. Conformal Gravity

which coincides with Eq. (3.1.9). Moreover, acting with $\nabla^{a}$ on Eq. (3.1.9), applying the Leibniz rule, and using again (3.1.9) to re-express $\nabla^{f} C_{a b c f}$ as $-\omega^{f} C_{a b c f}$, one obtains

$$
\begin{equation*}
\left[\nabla^{a} \nabla^{d}+\nabla^{a} \omega^{d}-\omega^{a} \omega^{d}\right] C_{a b c d}=0 \tag{3.2.3}
\end{equation*}
$$

We now re-express $\nabla^{a} \omega^{d}$ from (3.2.1) as

$$
\begin{equation*}
\nabla^{a} \omega^{d}=\omega^{a} \omega^{d}+\frac{1}{8} T g^{a d}-\frac{1}{2} R^{a d} \tag{3.2.4}
\end{equation*}
$$

Hence Eqs. (3.2.3)-(3.2.4) lead to

$$
\begin{equation*}
\left[\nabla^{a} \nabla^{d}-\frac{1}{2} R^{a d}\right] C_{a b c d}=0 \tag{3.2.5}
\end{equation*}
$$

This calculation only proves that the vanishing of the Bach tensor, defined as

$$
\begin{equation*}
B_{b c} \equiv \nabla^{a} \nabla^{d} C_{a b c d}-\frac{1}{2} R^{a d} C_{a b c d} \tag{3.2.6}
\end{equation*}
$$

is a necessary condition for a space-time to be conformal to an Einstein space (jointly with (3.1.9)). To prove sufficiency of the condition, we first need the following Lemma (Kozameh et al. 1985):

Lemma 3.2.1 Let $H^{a b}$ be a trace-free symmetric tensor. Then, providing the scalar invariant $J$ defined in (2.3.4) does not vanish, the only solution of the equations

$$
\begin{gather*}
C_{a b c d} H^{a d}=0,  \tag{3.2.7}\\
C_{a b c d}^{*} H^{a d}=0, \tag{3.2.8}
\end{gather*}
$$

is $H^{a d}=0$. As shown in Kozameh et al. 1985, such a Lemma is best proved by using two-spinor methods. Hence $H_{a b}$ corresponds to the spinor field

$$
\begin{equation*}
H_{A A^{\prime} B B^{\prime}}=\phi_{A B A^{\prime} B^{\prime}}=\bar{\phi}_{\left(A^{\prime} B^{\prime}\right)(A B)} \tag{3.2.9}
\end{equation*}
$$

## 3. Conformal Gravity

and Eqs. (3.2.7)-(3.2.8) imply that

$$
\begin{equation*}
\Psi_{A B C D} \phi^{C D}{ }_{A^{\prime} B^{\prime}}=0 . \tag{3.2.10}
\end{equation*}
$$

Note that the extra primed spinor indices $A^{\prime} B^{\prime}$ are irrelevant. Hence we can focus on the simpler eigenvalue equation

$$
\begin{equation*}
\psi_{A B C D} \varphi^{C D}=\lambda \varphi_{A B} \tag{3.2.11}
\end{equation*}
$$

The corresponding characteristic equation for $\lambda$ is

$$
\begin{equation*}
-\lambda^{3}+\frac{1}{2} I \lambda+\operatorname{det}(\psi)=0 \tag{3.2.12}
\end{equation*}
$$

by virtue of (2.3.3). Moreover, the Cayley-Hamilton theorem enables one to rewrite (3.2.12) as

$$
\begin{equation*}
\psi_{A B}^{P Q} \psi_{P Q}{ }^{R S} \psi_{R S}{ }^{C D}=\frac{1}{2} I \psi_{A B}^{C D}+\operatorname{det}(\psi) \delta_{(A}^{C} \delta_{B)}{ }^{D} \tag{3.2.13}
\end{equation*}
$$

and contraction of $A B$ with $C D$ yields

$$
\begin{equation*}
\operatorname{det}(\psi)=\frac{1}{3} J \tag{3.2.14}
\end{equation*}
$$

Thus, the only solution of (3.2.10) is the trivial one unless $J=0$ (Kozameh et al. 1985).

We are now in a position to prove sufficiency of the conditions (cf. (3.1.9) and (3.2.5))

$$
\begin{gather*}
\nabla^{f} C_{a b c f}+K^{f} C_{a b c f}=0,  \tag{3.2.15}\\
B_{b c}=0 \tag{3.2.16}
\end{gather*}
$$

Indeed, Eq. (3.2.15) ensures that (3.1.9) is satisfied with $\omega_{f}=\nabla_{f} \omega$ for some $\omega$. Hence Eq. (3.2.3) holds. If one now subtracts Eq. (3.2.3) from Eq. (3.2.16) one finds

$$
\begin{equation*}
C_{a b c d}\left(R^{a d}+2 \nabla^{a} \omega^{d}-2 \omega^{a} \omega^{d}\right)=0 \tag{3.2.17}
\end{equation*}
$$

## 3. Conformal Gravity

Remarkably, this is Eq. (3.2.7) of Lemma 3.2.1. To obtain Eq. (3.2.8), we act with $\nabla^{a}$ on the dual of Eq. (3.1.9). This leads to

$$
\begin{equation*}
\nabla^{a} \nabla^{d} C_{a b c d}^{*}+\left(\nabla^{a} \omega^{d}-\omega^{a} \omega^{d}\right) C_{a b c d}^{*}=0 \tag{3.2.18}
\end{equation*}
$$

Following Kozameh et al. 1985, the gradient of the contracted Bianchi identity and Ricci identity is then used to derive the additional equation

$$
\begin{equation*}
\nabla^{a} \nabla^{d} C_{a b c d}^{*}-\frac{1}{2} R^{a d} C_{a b c d}^{*}=0 \tag{3.2.19}
\end{equation*}
$$

Subtraction of (3.2.19) from (3.2.18) now yields

$$
\begin{equation*}
C_{a b c d}^{*}\left(R^{a d}+2 \nabla^{a} \omega^{d}-2 \omega^{a} \omega^{d}\right)=0 \tag{3.2.20}
\end{equation*}
$$

which is the desired form of Eq. (3.2.8).
We have thus completed the proof that (3.2.15)-(3.2.16) are necessary and sufficient conditions for a space-time to be conformal to an Einstein space. In two-spinor language, when Einstein's equations are imposed, after a conformal rescaling the equation for the trace-free part of Ricci becomes (see section 2.2)

$$
\begin{equation*}
\Phi_{A B A^{\prime} B^{\prime}}-\nabla_{B B^{\prime}} \omega_{A A^{\prime}}-\nabla_{B A^{\prime}} \omega_{A B^{\prime}}+\omega_{A A^{\prime}} \omega_{B B^{\prime}}+\omega_{A B^{\prime}} \omega_{B A^{\prime}}=0 . \tag{3.2.21}
\end{equation*}
$$

Similarly to the tensorial analysis performed so far, the spinorial analysis shows that the integrability condition for Eq. (3.2.21) is

$$
\begin{equation*}
\nabla^{A A^{\prime}} \psi_{A B C D}+\omega^{A A^{\prime}} \psi_{A B C D}=0 \tag{3.2.22}
\end{equation*}
$$

The fundamental theorem of conformal gravity states therefore that a space-time is conformal to an Einstein space if and only if (Kozameh et al. 1985)

$$
\begin{gather*}
\nabla^{D D^{\prime}} \psi_{A B C D}+k^{D D^{\prime}} \psi_{A B C D}=0,  \tag{3.2.23}\\
\bar{I} \psi^{A B C D} \nabla^{F A^{\prime}} \psi_{F B C D}-I \bar{\psi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \nabla^{A F^{\prime}} \bar{\psi}_{F^{\prime} B^{\prime} C^{\prime} D^{\prime}}=0 . \tag{3.2.24}
\end{gather*}
$$

## 3. Conformal Gravity

$$
\begin{equation*}
B_{A F A^{\prime} F^{\prime}} \equiv 2\left(\nabla_{A^{\prime}}^{C} \nabla_{F^{\prime}}^{D} \psi_{A F C D}+\Phi_{A^{\prime} F^{\prime}}^{C D} \psi_{A F C D}\right)=0 \tag{3.2.25}
\end{equation*}
$$

Note that reality of Eq. (3.2.25) for the Bach spinor is ensured by the Bianchi identities.

### 3.3 Complex Space-Times

Since this book is devoted to complex general relativity and its applications, it is necessary to extend the theorem expressed by (3.2.23)-(3.2.25) to complex space-times. For this purpose, we find it appropriate to define and discuss such spaces in more detail in this section. In this respect, we should say that four distinct geometrical objects are necessary to study real general relativity and complex general relativity, here defined in four-dimensions (Penrose and Rindler 1986, Esposito 1994).
(1) Lorentzian space-time $\left(M, g_{L}\right)$. This is a Hausdorff four-manifold $M$ jointly with a symmetric, non-degenerate bilinear form $g_{L}$ to each tangent space with signature (,,,+---$)($ or $(-,+,+,+)$ ). The latter is then called a Lorentzian four-metric $g_{L}$.
(2) Riemannian four-space $\left(M, g_{R}\right)$, where $g_{R}$ is a smooth and positive-definite section of the bundle of symmetric bilinear two-forms on $M$. Hence $g_{R}$ has signature (+, +, +, +).
(3) Complexified space-time. This manifold originates from a real-analytic spacetime with real-analytic coordinates $x^{a}$ and real-analytic Lorentzian metric $g_{L}$ by allowing the coordinates to become complex, and by an holomorphic extension of the metric coefficients into the complex domain. In such manifolds the operation of complex conjugation, taking any point with complexified coordinates $z^{a}$ into the point with coordinates $\overline{z^{a}}$, still exists. Note that, however, it is not possible

## 3. Conformal Gravity

to define reality of tensors at complex points, since the conjugate tensor lies at the complex conjugate point, rather than at the original point.
(4) Complex space-time. This is a four-complex-dimensional complex-Riemannian manifold, and no four-real-dimensional subspace has been singled out to give it a reality structure (Penrose and Rindler 1986). In complex space-times no complex conjugation exists, since such a map is not invariant under holomorphic coordinate transformations.

Thus, the complex-conjugate spinors $\lambda^{A \ldots M}$ and $\bar{\lambda}^{A^{\prime} \ldots M^{\prime}}$ of a Lorentzian spacetime are replaced by independent spinors $\lambda A \ldots M$ and $\widetilde{\lambda}^{A^{\prime} \ldots M^{\prime}}$. This means that unprimed and primed spin-spaces become unrelated to one another. Moreover, the complex scalars $\phi$ and $\bar{\phi}$ are replaced by the pair of independent complex scalars $\phi$ and $\widetilde{\phi}$. On the other hand, quantities $X$ that are originally real yield no new quantities, since the reality condition $X=\bar{X}$ becomes $X=\widetilde{\boldsymbol{X}}$. For example, the covariant derivative operator $\nabla_{a}$ of Lorentzian space-time yields no new operator $\widetilde{\nabla}_{a}$, since it is originally real. One should instead regard $\nabla_{a}$ a s a complex-holomorphic operator. The spinors $\psi_{A B C D}, \Phi_{A B C^{\prime} D^{\prime}}$ and the scalar $\Lambda$ appearing in the Riemann curvature (see (2.2.26)) have as counterparts the spinors
 conditions in Lorentzian space-time, one has (Penrose and Rindler 1986)

$$
\begin{align*}
\tilde{\Phi}_{A B C^{\prime} D^{\prime}} & =\Phi_{A B C^{\prime} D^{\prime}},  \tag{3.3.1}\\
\tilde{\Lambda} & =\Lambda, \tag{3.3.2}
\end{align*}
$$

while the Weyl spinors $\psi_{A B C D}$ and $\widetilde{\boldsymbol{\psi}}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}$ remain independent of each other. Hence one Weyl spinor may vanish without the other Weyl spinor having to vanish as well. Correspondingly, a complex space-time such that $\widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}=0$ is called right conformally flat or conformally anti-self-dual, whereas if $\psi_{A B C D}=0$, one deals with a left conformally flat or conformally self-dual complex space-time. Moreover, if the remaining part of the Riemann curvature vanishes as well, i.e.

## 3. Conformal Gravity

$\Phi_{A B C^{\prime} D^{\prime}}=0$ and $\Lambda=0$, the word conformally should be omitted in the terminology described above (cf. chapter four). Interestingly, in a complex space-time the principal null directions (cf. section 2.3) of the Weyl spinors $\psi_{A B C D}$ and $\tilde{\boldsymbol{\psi}}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}$ are independent of each other, and one has two independent classification schemes at each point.

### 3.4 Complex Einstein Spaces

In the light of the previous discussion, the fundamental theorem of conformal gravity in complex space-times can be stated as follows (cf. Baston and Mason 1987).

Theorem 3.4.1A complex space-time is conformal to a complex Einstein space if and only if

$$
\begin{gather*}
\nabla^{D D^{\prime}} \psi_{A B C D}+k^{D D^{\prime}} \psi_{A B C D}=0  \tag{3.4.1}\\
\tilde{I} \psi^{A B C D} \nabla^{F A^{\prime}} \psi_{F B C D}-I \widetilde{\psi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \nabla^{A F^{\prime}} \tilde{\psi}_{F^{\prime} B^{\prime} C^{\prime} D^{\prime}}=0,  \tag{3.4.2}\\
B_{A F A^{\prime} F^{\prime}} \equiv 2\left(\nabla_{A^{\prime}}^{C} \nabla_{F^{\prime}}^{D_{A F C D}+\Phi_{A C D}^{C A^{\prime}},} \psi_{A F C D}\right)=0, \tag{3.4.3}
\end{gather*}
$$

where $I$ is the complex scalar invariant defined in (2.3.3), whereas $\tilde{I}$ is the independent invariant defined as

$$
\begin{equation*}
\tilde{I} \equiv \tilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \tilde{\psi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \tag{3.4.4}
\end{equation*}
$$

The left-hand side of Eq. (3.4.2) is called the Eastwood-Dighton spinor.

## 3. Conformal Gravity

### 3.5 Conformal Infinity

To complete our introduction to conformal gravity, we find it helpful for the reader to outline the construction of conformal infinity for Minkowski space-time (see also an application in section 9.5). Starting from polar local coordinates in Minkowski, we first introduce (in $c=1$ units) the retarded coordinate $w \equiv t-r$ and the advanced coordinate $v \equiv t+r$. To eliminate the resulting cross term in the local form of the metric, new coordinates $p$ and $q$ are defined implicitly as (Esposito 1994)

$$
\begin{equation*}
\tan p \equiv v \quad, \quad \tan q \equiv w, \quad p-q \geq 0 \tag{3.5.1}
\end{equation*}
$$

Hence one finds that a conformal-rescaling factor $\omega \equiv(\cos p)(\cos q)$ exists such that, locally, the metric of Minkowski space-time can be written as $\omega^{-2} \widetilde{\boldsymbol{g}}$, where

$$
\begin{equation*}
\tilde{g}=-d t^{\prime} \otimes d t^{\prime}+\left[d r^{\prime} \otimes d r^{\prime}+\frac{1}{4}\left(\sin \left(2 r^{\prime}\right)\right)^{2} \Omega_{2}\right] \tag{3.5.2}
\end{equation*}
$$

where $t^{\prime} \equiv \frac{(p+q)}{2}, r^{\prime} \equiv \frac{(p-q)}{2}$, and $\Omega_{2}$ is the metric on a unit two-sphere. Although (3.5.2) is locally identical to the metric of the Einstein static universe, it is necessary to go beyond a local analysis. This may be achieved by analytic extension to the whole of the Einstein static universe. The original Minkowski space-time is then found to be conformal to the following region of the Einstein static universe:

$$
\begin{equation*}
\left.\left(t^{\prime}+r^{\prime}\right) \in\right]-\pi, \pi\left[\quad, \quad\left(t^{\prime}-r\right) \in\right]-\pi, \pi\left[\quad, \quad r^{\prime} \geq 0 .\right. \tag{3.5.3}
\end{equation*}
$$

By definition, the boundary of the region in (3.5.3) represents the conformal structure of infinity of Minkowski space-time. It consists of two null surfaces and three points, i.e. (Esposito 1994)
(i) The null surface $\mathrm{SCRI}^{-} \equiv\left\{t^{\prime}-r^{\prime}=q=-\frac{\pi}{2}\right\}$, i.e. the future light cone of the point $r^{\prime}=0, t^{\prime}=-\frac{\pi}{2}$.

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(ii) The null surface $\mathrm{SCRI}^{+} \equiv\left\{t^{\prime}+r^{\prime}=p=\frac{\pi}{2}\right\}$, i.e. the past light cone of the point $r^{\prime}=0, t^{\prime}=\frac{\pi}{2}$.
(iii) Past timelike infinity, i.e. the point

$$
\iota^{-} \equiv\left\{r^{\prime}=0, t^{\prime}=-\frac{\pi}{2}\right\} \Rightarrow p=q=-\frac{\pi}{2}
$$

(iv) Future timelike infinity, defined as

$$
\iota^{+} \equiv\left\{r^{\prime}=0, t^{\prime}=\frac{\pi}{2}\right\} \Rightarrow p=q=\frac{\pi}{2}
$$

(v) Spacelike infinity, i.e. the point

$$
\iota^{0} \equiv\left\{r^{\prime}=\frac{\pi}{2}, t^{\prime}=0\right\} \Rightarrow p=-q=\frac{\pi}{2}
$$

The extension of the SCRI formalism to curved space-times is an open research problem, but we limit ourselves to the previous definitions in this section.

## PART II:

HOLOMORPHIC IDEAS IN GENERAL RELATIVITY

## TWISTOR SPACES

Abstract. In twistor theory, $\alpha$-planes are the building blocks of classical field theory in complexified compactified Minkowski space-time. $\alpha$-Planes are totally null two-surfaces $S$ in that, if $p$ is any point on $S$, and if $v$ and $w$ are any two null tangent vectors at $p \in S$, the complexified Minkowski metric $\eta$ satisfies the identity $\eta(v, w)=v_{a} w^{a}=0$. By definition, their null tangent vectors have the two-component spinor form $\lambda^{A} \pi^{A^{\prime}}$, where $\lambda^{A}$ is varying and $\pi^{A^{\prime}}$ is fixed. Therefore, the induced metric vanishes identically since $\eta(v, w)=\left(\lambda^{\boldsymbol{A}} \pi^{\boldsymbol{A}^{\prime}}\right)\left(\mu_{A^{\prime}} \pi_{A^{\prime}}\right)=$ $0=\eta(v, v)=\left(\lambda^{\boldsymbol{A}} \boldsymbol{\pi}^{\boldsymbol{A}^{\prime}}\right)\left(\lambda_{\boldsymbol{A}} \pi_{\boldsymbol{A}^{\prime}}\right)$. One thus obtains a conformally invariant characterization of flat space-times. This definition can be generalized to complex or real Riemannian space-times with non-vanishing curvature, provided the Weyl curvature is anti-self-dual. One then finds that the curved metric $g$ is such that $g(v, w)=0$ on $S$, and the spinor field $\pi_{A^{\prime}}$ is covariantly constant on $S$. The corresponding holomorphic two-surfaces are called $\alpha$-surfaces, and they form a three-complex-dimensional family. Twistor space is the space of all $\alpha$-surfaces and depends only on the conformal structure of complex space-time.

Projective twistor space $P T$ is isomorphic to complex projective space $C P^{3}$. The correspondence between flat space-time and twistor space shows that complex $\alpha$-planes correspond to points in $P T$, and real null geodesics to points in $P N$, i.e. the space of null twistors. Moreover, a complex space-time point corresponds to a sphere in $P T$, and a real space-time point to a sphere in $P N$. Remarkably, the points $x$ and $y$ are null-separated if and only if the corresponding spheres in $P T$ intersect. This is the twistor description of the light-cone structure of Minkowski space-time.

## 4. Twistor Spaces

A conformally invariant isomorphism exists between the complex vector space of holomorphic solutions of $\square \phi=0$ on the forward tube of flat space-time, and the complex vector space of arbitrary complex-analytic functions of three variables, not subject to any differential equation. Moreover, when curvature is nonvanishing, there is a one-to-one correspondence between complex space-times with anti-self-dual Weyl curvature and scalar curvature $R=24 \Lambda$, and sufficiently small deformations of flat projective twistor space $P T$ which preserve a one-form $\tau$ homogeneous of degree 2 and a three-form $\rho$ homogeneous of degree 4 , with $\tau \wedge d \tau=2 \Lambda \rho$. Thus, to solve the anti-self-dual Einstein equations, one has to study a geometrical problem, i.e. finding the holomorphic curves in deformed projective twistor space.

## 4. Twistor Spaces

## $4.1 \alpha$-Planes in Minkowski Space-Time

$\alpha$-Planes provide a geometrical definition of twistors in Minkowski space-time. For this purpose, we first complexify flat space-time, so that real coordinates $\left(x^{0}, x^{1}, x^{2}, x^{3}\right)$ are replaced by complex coordinates $\left(z^{0}, z^{1}, z^{2}, z^{3}\right)$, and we obtain a four-dimensional complex vector space equipped with a non-degenerate complexbilinear form (Ward and Wells 1990)

$$
\begin{equation*}
(z, w) \equiv z^{0} w^{0}-z^{1} w^{1}-z^{2} w^{2}-z^{3} w^{3} . \tag{4.1.1}
\end{equation*}
$$

The resulting matrix $z^{A A^{\prime}}$, which, by construction, corresponds to the position vector $z^{a}=\left(z^{0}, z^{1}, z^{2}, z^{3}\right)$, is no longer Hermitian as in the real case. Moreover, we compactify such a space by identifying future null infinity with past null infinity (Penrose 1974, Penrose and Rindler 1986, Esposito 1994). The resulting manifold is here denoted by $C M^{\#}$, following Penrose and Rindler 1986.,

In $C M^{\#}$ with metric $\eta$, we consider two-surfaces $S$ whose tangent vectors have the two-component spinor form

$$
\begin{equation*}
v^{a}=\lambda^{A} \pi^{A^{\prime}} \tag{4.1.2}
\end{equation*}
$$

where $\lambda^{A}$ is varying and $\pi^{A^{\prime}}$ is fixed. This implies that these tangent vectors are null, since $\eta(v, v)=v_{a} v^{a}=\left(\lambda^{\boldsymbol{A}} \lambda_{\boldsymbol{A}}\right)\left(\pi^{\boldsymbol{A}^{\prime}} \pi_{\boldsymbol{A}^{\prime}}\right)=0$. Moreover, the induced metric on $S$ vanishes identically since any two null tangent vectors $v^{a}=\lambda^{A} \pi^{A^{\prime}}$ and $w^{a}=\mu^{A} \pi^{A^{\prime}}$ at $p \in S$ are orthogonal:

$$
\begin{equation*}
\eta(v, w)=\left(\lambda^{A} \mu_{A}\right)\left(\pi^{A^{\prime}} \pi_{A^{\prime}}\right)=0 \tag{4.1.3}
\end{equation*}
$$

where we have used the property $\boldsymbol{\pi}^{\boldsymbol{A}^{\prime}} \pi_{\boldsymbol{A}^{\prime}}=\boldsymbol{\epsilon}^{\boldsymbol{A}^{\prime} \boldsymbol{B}^{\prime}} \pi_{\boldsymbol{A}^{\prime}} \boldsymbol{\pi}_{\boldsymbol{B}^{\prime}}=0$. By virtue of (4.1.3), the resulting $\alpha$-plane is said to be totally null. A twistor is then an $\alpha$-plane with

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constant $\pi_{A}$, associated to it. Note that two disjoint families of totally null twosurfaces exist in $C M^{\#}$, since one might choose null tangent vectors of the form

$$
\begin{equation*}
u^{a}=\nu^{A} \pi^{A^{\prime}} \tag{4.1.4}
\end{equation*}
$$

where $v^{A}$ is fixed and $\pi^{A^{\prime}}$ is varying. The resulting two-surfaces are called $\beta$-planes (Penrose 1986).

Theoretical physicists are sometimes more familiar with a definition involving the vector space of solutions of the differential equation

$$
\begin{equation*}
\mathcal{D}_{A^{\prime}}^{(A} \omega^{B)}=0 \tag{4.1.5}
\end{equation*}
$$

where $D$ is the flat connection, and $D_{A A^{\prime}}$ the corresponding spinor covariant derivative. The general solution of Eq. (4.1.5) in $C M^{\#}$ takes the form (Penrose and Rindler 1986, Esposito 1994)

$$
\begin{gather*}
\omega^{A}=\left(\omega^{o}\right)^{A}-i x^{A A^{\prime}} \pi_{A^{\prime}}^{o}  \tag{4.1.6}\\
\pi_{A^{\prime}}=\pi_{A^{\prime}}^{o} \tag{4.1.7}
\end{gather*}
$$

where $\omega_{A}^{\circ}$ and $\pi_{A^{\prime}}^{\circ}$ are arbitrary constant spinors, and $x^{A A^{\prime}}$ is the spinor version of the position vector with respect to some origin. A twistor is then represented by the pair of spinor fields $\left(\omega^{\boldsymbol{A}}, \pi_{\boldsymbol{A}^{\prime}}\right) \Leftrightarrow Z^{\alpha}$ (Penrose 1975). The twistor equation (4.1.5) is conformally invariant. This is proved bearing in mind the spinor form of the flat four-metric

$$
\begin{equation*}
\eta_{a b}=\epsilon_{A B} \epsilon_{A^{\prime} B^{\prime}}, \tag{4.1.8}
\end{equation*}
$$

and making the conformal rescaling

$$
\begin{equation*}
\widehat{\eta}_{a b}=\Omega^{2} \eta_{a b} \tag{4.1.9}
\end{equation*}
$$

which implies

$$
\begin{equation*}
\widehat{\epsilon}_{A B}=\Omega \epsilon_{A B}, \widehat{\epsilon}_{A^{\prime} B^{\prime}}=\Omega \epsilon_{A^{\prime} B^{\prime}}, \widehat{\epsilon}^{A B}=\Omega^{-1} \epsilon^{A B}, \widehat{\epsilon}^{A^{\prime} B^{\prime}}=\Omega^{-1} \epsilon^{A^{\prime} B^{\prime}} \tag{4.1.10}
\end{equation*}
$$

## 4. Twistor Spaces

Thus, defining $T_{a} \equiv D_{a}(\log \Omega)$ and choosing $\widehat{\omega}^{B}=\omega^{B}$, one finds (Penrose and Rindler 1986, Esposito 1994)

$$
\begin{equation*}
\widehat{\mathcal{D}}_{A A^{\prime} \hat{\omega}^{B}}=\mathcal{D}_{A A^{\prime}} \omega^{B}+\epsilon_{A}^{B} T_{C A^{\prime}} \omega^{C}, \tag{4.1.11}
\end{equation*}
$$

which implies

$$
\begin{equation*}
\widehat{\mathcal{D}}_{A^{\prime}}^{(A} \widehat{\omega}^{B)}=\omega^{-1} \mathcal{D}_{A^{\prime}}^{(A} \omega^{B)} \tag{4.1.12}
\end{equation*}
$$

Note that the solutions of (4.1.5) are completely determined by the four complex components at O of $\omega^{A}$ and $\pi_{A}$, in a spin-frame at O . They are a four-dimensional vector space over the complex numbers, called twistor space (Penrose and Rindler 1986, Esposito 1994).

Requiring that $v_{A}$ be constant over the $\beta$-planes implies that $v^{A} \pi^{A^{\prime}} D_{A A^{\prime}} v_{B}=$ 0 , for each $\pi^{A}$, i.e. $v^{A} D_{A A^{\prime}} v_{B}=0$. Moreover, a scalar product can be defined between the $\omega^{A}$ field and the $v_{A}$-scaled $\beta$-plane: $\omega^{A} v_{A}$. Its constancy over the $\beta$-plane implies that (Penrose 1986)

$$
\begin{equation*}
\nu^{A} \pi^{A^{\prime}} \mathcal{D}_{A A^{\prime}}\left(\omega^{B} \nu_{B}\right)=0 \tag{4.1.13}
\end{equation*}
$$

for each $\pi^{A^{\prime}}$, which leads to

$$
\begin{equation*}
\nu_{A} \nu_{B}\left(\mathcal{D}_{A^{\prime}}^{(A} \omega^{B)}\right)=0 \tag{4.1.14}
\end{equation*}
$$

for each $\beta$ - plane and hence for each $v_{A}$. Thus, Eq. (4.1.14) becomes the twistor equation (4.1.5). In other words, it is the twistor concept associated with a $\beta$-plane which is dual to that associated with a solution of the twistor equation (Penrose 1986).

Flat projective twistor space $P T$ can be thought of as three-dimensional complex projective space $C P^{3}$ (cf. example E2 in section 1.2). This means that we take the space $C^{4}$ of complex numbers $\left(z^{0}, z^{1}, z^{2}, z^{3}\right)$ and factor out by the proportionality relation $\left(\lambda z^{0}, \ldots, \lambda z^{3}\right) \sim\left(z^{0}, \ldots, z^{3}\right)$, with $\lambda \in C-\{0\}$. The homogeneous coordinates $\left(z^{0}, \ldots, z^{3}\right)$ are, in the case of $P T \cong C P^{3}$, as follows:

## 4. Twistor Spaces

$\left(\omega^{\mathbf{0}}, \boldsymbol{\omega}^{\mathbf{1}}, \pi_{0^{\prime}}, \pi_{1^{\prime}}\right) \equiv\left(\boldsymbol{\omega}^{\boldsymbol{A}}, \boldsymbol{\pi}_{\boldsymbol{A}^{\prime}}\right)$. The $\alpha$-planes defined in this section can be obtained from the equation (cf. (4.1.6))

$$
\begin{equation*}
\omega^{A}=i x^{A A^{\prime}} \pi_{A^{\prime}} \tag{4.1.15}
\end{equation*}
$$

where $\left(\omega^{\boldsymbol{A}}, \pi_{\boldsymbol{A}^{\prime}}\right)$ is regarded as fixed, with $\pi_{A^{\prime}} \neq 0$. This means that Eq. (4.1.15), considered as an equation for $x^{A A^{\prime}}$, has as its solution a complex two-plane in $C M^{\#}$, whose tangent vectors take the form in Eq. (4.1.2), i.e. we have found an $\alpha$-plane. The $\alpha$-planes are self-dual in that, if $v$ and $u$ are any two null tangent vectors to an $\alpha$-plane, then $F \equiv v \otimes u-u \otimes v$ is a self-dual bivector since

$$
\begin{equation*}
F^{A A^{\prime} B B^{\prime}}=\epsilon^{A B} \phi^{\left(A^{\prime} B^{\prime}\right)} \tag{4.1.16}
\end{equation*}
$$

where $\phi^{\left(A^{\prime} B^{\prime}\right)}=\sigma \pi^{A^{\prime}} \pi^{B^{\prime}}$, with $\sigma \in C-\{0\}$ (Ward 1981b). Note also that $\alpha$-planes remain unchanged if we replace $\left(\omega^{\boldsymbol{A}}, \boldsymbol{\pi}_{\boldsymbol{A}^{\prime}}\right)$ by $\left(\lambda \boldsymbol{\omega}^{\boldsymbol{A}}, \lambda \pi_{\boldsymbol{A}^{\prime}}\right)$ with $\lambda \in C-\{0\}$, and that all $\alpha$-planes arise as solutions of Eq. (4.1.15). If real solutions of (4.1.15) exist, this implies that $x^{A A^{\prime}}=\overline{\boldsymbol{x}}^{\boldsymbol{A} \boldsymbol{A}^{\prime}}$. This leads to

$$
\begin{equation*}
\omega^{A} \bar{\pi}_{A}+\bar{\omega}^{A^{\prime}} \pi_{A^{\prime}}=i x^{A A^{\prime}}\left(\pi_{A^{\prime}} \bar{\pi}_{A}-\pi_{A^{\prime}} \bar{\pi}_{A}\right)=0 \tag{4.1.17}
\end{equation*}
$$

where overbars denote complex conjugation in two-spinor language, defined according to the rules described in section 2.1. If (4.1.17) holds and $\pi_{A^{\prime}} \neq 0$, the solution space of (4.1.15) in real Minkowski space-time is a null geodesic, and all null geodesics arise in this way (Ward 1981b). Moreover, if $\pi_{A}$, vanishes, the point $\left(\omega^{\boldsymbol{A}}, \pi_{A^{\prime}}\right)=\left(\omega^{\boldsymbol{A}}, 0\right)$ can be regarded as an $\alpha$-plane at infinity in compactified Minkowski space-time. Interestingly, Eq. (4.1.15) is the two-spinor form of the equation expressing the incidence property of a point $(t, x, y, z)$ in Minkowski space-time with the twistor $Z^{\alpha}$, i.e. (Penrose 1981)

$$
\binom{Z^{0}}{Z^{1}}=\frac{i}{\sqrt{2}}\left(\begin{array}{cc}
t+z & x+i y  \tag{4.1.18}\\
x-i y & t-z
\end{array}\right)\binom{Z^{2}}{Z^{3}}
$$

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The left-hand side of Eq. (4.1.17) may be then re-interpreted as the twistor pseudonorm (Penrose 1981)

$$
\begin{equation*}
Z^{\alpha} \bar{Z}_{\alpha}=Z^{0} \overline{Z^{2}}+Z^{1} \overline{Z^{3}}+Z^{2} \overline{Z^{0}}+Z^{3} \overline{Z^{1}}=\omega^{A} \bar{\pi}_{A}+\pi_{A^{\prime}} \bar{\omega}^{A^{\prime}} \tag{4.1.19}
\end{equation*}
$$

by virtue of the property $\left(\bar{Z}_{0}, \bar{Z}_{1}, \bar{Z}_{2}, \bar{Z}_{3}\right)=\left(\overline{Z^{2}}, \overline{Z^{3}}, \overline{Z^{0}}, \overline{Z^{1}}\right)$. Such a pseudonorm makes it possible to define the top half $P T^{+}$of $P T$ by the condition $Z^{\alpha} \bar{Z}_{\alpha}>$ 0 , and the bottom half $P T^{-}$of $P T$ by the condition $Z^{\alpha} \bar{Z}_{\boldsymbol{\alpha}}<\mathbf{0}$.

So far, we have seen that an $\alpha$-plane corresponds to a point in $P T$, and null geodesics to points in $P N$, the space of null twistors. However, we may also interpret (4.1.15) as an equation where $x^{A A^{\prime}}$ is fixed, and solve for $\left(\omega^{\boldsymbol{A}}, \boldsymbol{\pi}_{\boldsymbol{A}^{\prime}}\right)$. Within this approach, $\pi_{A^{\prime}}$ remains arbitrary, and $\omega^{A}$ is thus given by $i x A^{A A^{\prime}} \pi_{A^{\prime}}$. This yields a complex two-plane, and factorization by the proportionality relation $\left(\lambda \omega^{\boldsymbol{A}}, \lambda \pi_{\boldsymbol{A}^{\prime}}\right) \sim\left(\omega^{\boldsymbol{A}}, \pi_{\boldsymbol{A}^{\prime}}\right)$ leads to a complex projective one-space $C P^{1}$, with twosphere topology. Thus, the fixed space-time point $x$ determines a Riemann sphere $L_{x} \cong C P^{1}$ in $P T$. In particular, if $x$ is real, then $L_{x}$ lies entirely within $P N$, given by those twistors whose homogeneous coordinates satisfy (4.1.17). To sum up, a complex space-time point corresponds to a sphere in $P T$, whereas a real space-time point corresponds to a sphere in $P N$ (Penrose 1981, Ward 1981b).

In Minkowski space-time, two points $p$ and $q$ are null-separated if and only if there is a null geodesic connecting them. In projective twistor space $P T$, this implies that the corresponding lines $L_{p}$ and $L_{q}$ intersect, since the intersection point represents the connecting null geodesic. To conclude this section it may be now instructive, following Huggett and Tod 1985, to study the relation between null twistors and null geodesics. Indeed, given the null twistors $X^{\alpha}, Y^{\alpha}$ defined by

$$
\begin{align*}
& X^{\alpha} \equiv\left(i x_{0}^{A A^{\prime}} X_{A^{\prime}}, X_{A^{\prime}}\right)  \tag{4.1.20}\\
& Y^{\alpha} \equiv\left(i x_{1}^{A A^{\prime}} Y_{A^{\prime}}, Y_{A^{\prime}}\right) \tag{4.1.21}
\end{align*}
$$

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the corresponding null geodesics are

$$
\begin{align*}
& \gamma_{X}: x^{A A^{\prime}} \equiv x_{0}^{A A^{\prime}}+\lambda \bar{X}^{A} X^{A^{\prime}}  \tag{4.1.22}\\
& \gamma_{Y}: x^{A A^{\prime}} \equiv x_{1}^{A A^{\prime}}+\mu \bar{Y}^{A} Y^{A^{\prime}} \tag{4.1.23}
\end{align*}
$$

If these intersect at some point, say $x_{2}$, one finds

$$
\begin{equation*}
x_{2}^{A A^{\prime}}=x_{0}^{A A^{\prime}}+\lambda \bar{X}^{A} X^{A^{\prime}}=x_{1}^{A A^{\prime}}+\mu \bar{Y}^{A} Y^{A^{\prime}} \tag{4.1.24}
\end{equation*}
$$

where $\lambda, \mu \in R$. Hence

$$
\begin{equation*}
x_{2}^{A A^{\prime}} \bar{Y}_{A} X_{A^{\prime}}=x_{0}^{A A^{\prime}} \bar{Y}_{A} X_{A^{\prime}}=x_{1}^{A A^{\prime}} \bar{Y}_{A} X_{A^{\prime}} \tag{4.1.25}
\end{equation*}
$$

by virtue of the identities $\boldsymbol{X}^{\boldsymbol{A}^{\prime}} \boldsymbol{X}_{\boldsymbol{A}^{\prime}}=\overline{\boldsymbol{Y}}^{\boldsymbol{A}} \bar{Y}_{\boldsymbol{A}}=\mathbf{0}$. Eq. (4.1.25) leads to

$$
\begin{equation*}
X^{\alpha} \bar{Y}_{\alpha}=i\left(x_{0}^{A A^{\prime}} \bar{Y}_{A} X_{A^{\prime}}-x_{1}^{A A^{\prime}} \bar{Y}_{A} X_{A^{\prime}}\right)=0 \tag{4.1.26}
\end{equation*}
$$

Suppose instead we are given Eq. (4.1.26). This implies that some real $\lambda$ and $\mu$ exist such that

$$
\begin{equation*}
x_{0}^{A A^{\prime}}-x_{1}^{A A^{\prime}}=-\lambda \bar{X}^{A} X^{A^{\prime}}+\mu \bar{Y}^{A} Y^{A^{\prime}} \tag{4.1.27}
\end{equation*}
$$

where signs on the right-hand side of (4.1.27) have been suggested by (4.1.24). Note that (4.1.27) only holds if $X_{A^{\prime}} Y^{A^{\prime}} \neq 0$, i.e. if $\gamma_{X}$ and $\gamma_{Y}$ are not parallel. However, the whole argument can be generalized to this case as well (our problem 4.2, Huggett and Tod 1985), and one finds that in all cases the null geodesics $\gamma_{X}$ and $\gamma_{Y}$ intersect if and only if $X^{\boldsymbol{\alpha}} \bar{Y}_{\boldsymbol{\alpha}}$ vanishes.

## $4.2 \alpha$-Surfaces and Twistor Geometry

The $\alpha$-planes defined in section 4.1 can be generalized to a suitable class of curved complex space-times. By a complex space-time $(M, g)$ we mean a fourdimensional Hausdorff manifold $M$ with holomorphic metric $g$. Thus, with respect

## 4. Twistor Spaces

to a holomorphic coordinate basis $x^{a}, g$ is a $4 \times 4$ matrix of holomorphic functions of $x^{a}$, and its determinant is nowhere-vanishing (Ward 1980b, Ward and Wells 1990). Remarkably, $g$ determines a unique holomorphic connection $\nabla$, and a holomorphic curvature tensor $R_{b c d}^{a}$. Moreover, the Ricci tensor $R_{a b}$ becomes complex-valued, and the Weyl tensor $C^{a}{ }_{b c d}$ may be split into independent holomorphic tensors, i.e. its self-dual and anti-self-dual parts respectively. With our two-spinor notation, one has (see (2.1.36))

$$
\begin{equation*}
C_{a b c d}=\psi_{A B C D} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}}+\widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D}, \tag{4.2.1}
\end{equation*}
$$

where $\psi_{A B C D}=\psi_{(A B C D)}, \widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}=\widetilde{\psi}_{\left(A^{\prime} B^{\prime} C^{\prime} D^{\prime}\right)}$. The spinors $\psi$ and $\tilde{\psi}$ are the anti-self-dual and self-dual Weyl spinors respectively. Following Penrose 1976a-b, Ward and Wells 1990, complex vacuum space-times such that

$$
\begin{equation*}
\widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}=0 \quad, \quad R_{a b}=0 \tag{4.2.2}
\end{equation*}
$$

are called right-flat or anti-self-dual, whereas complex vacuum space-times such that

$$
\begin{equation*}
\psi_{A B C D}=0 \quad, \quad R_{a b}=0 \tag{4.2.3}
\end{equation*}
$$

are called left-flat or self-dual. Note that this definition only makes sense if spacetime is complex (or real Riemannian), since in this case no complex conjugation relates primed to unprimed spinors (i.e. the corresponding spin-spaces are no longer anti-isomorphic). Hence, for example, the self-dual Weyl spinor $\widetilde{\boldsymbol{\psi}} \cdot A^{\prime} B^{\prime} C^{\prime} D^{\prime}$ may vanish without its anti-self-dual counterpart $\psi_{A B C D}$ having to vanish as well, as in Eq. (4.2.2), or the converse may hold, as in Eq. (4.2.3) (see section 1.1 and problem 2.3).

By definition, $\alpha$-surfaces are complex two-surfaces $S$ in a complex space-time $(M, g)$ whose tangent vectors $v$ have the two-spinor form (4.1.2), where $\lambda^{A}$ is varying, and $\pi^{A^{\prime}}$ is a fixed primed spinor field on $S$. From this definition, the following properties can be derived (cf. section 4.1).
(i) tangent vectors to $\alpha$-surfaces are null;

## 4. Twistor Spaces

(ii) any two null tangent vectors $v$ and $u$ to an $\alpha$-surface are orthogonal to one another;
(iii) the holomorphic metric $g$ vanishes on $S$ in that $g(v, u)=g(v, v)=0, \forall v, u$ (cf. (4.1.3)), so that $\alpha$-surfaces are totally null;
(iv) $\alpha$-surfaces are self-dual, in that $F \equiv v \otimes u-u \otimes v$ takes the two-spinor form (4.1.16);
(v) $\alpha$-surfaces exist in $(M, g)$ if and only if the self-dual Weyl spinor vanishes, so that $(M, g)$ is anti-self-dual.

Note that properties (i)-(iv), here written in a redundant form for pedagogical reasons, are the same as in the flat-space-time case, provided we replace the flat metric $\eta$ with the curved metric $g$. Condition (v), however, is a peculiarity of curved space-times. The reader may find a detailed proof of the necessity of this condition as a particular case of the calculations appearing in chapter six, where we study a holomorphic metric-compatible connection $\nabla$ with non-vanishing torsion. To avoid repeating ourselves, we focus instead on the sufficiency of the condition, following Ward and Wells 1990.

We want to prove that, if $(M, g)$ is anti-self-dual, it admits a three-complexparameter family of self-dual $\alpha$-surfaces. Indeed, given any point $p \in M$ and a spinor $\mu_{A^{\prime}}$ at $p$, one can find a spinor field $\pi_{A}$ 'on $M$, satisfying the equation (cf. Eq. (6.2.10))

$$
\begin{equation*}
\pi^{A^{\prime}}\left(\nabla_{A A^{\prime}} \pi_{B^{\prime}}\right)=\xi_{A} \pi_{B^{\prime}} \tag{4.2.4}
\end{equation*}
$$

and such that

$$
\begin{equation*}
\pi_{A^{\prime}}(p)=\mu_{A^{\prime}}(p) \tag{4.2.5}
\end{equation*}
$$

Hence $\pi_{A}$ ' defines a holomorphic two-dimensional distribution, spanned by the vector fields of the form $\lambda^{A} \pi^{A^{\prime}}$, which is integrable by virtue of (4.2.4). Thus, in particular, there exists a self-dual $\alpha$-surface through $p$, with tangent vectors of the form $\lambda^{A} \mu^{A^{\prime}}$ at $p$. Since $p$ is arbitrary, this argument may be repeated $\forall p \in M$. The space $P$ of all self-dual $\alpha$-surfaces in $(M, g)$ is three-complex-dimensional, and is called twistor space of $(M, g)$.

## 4. Twistor Spaces

### 4.3 Geometrical Theory of Partial Differential Equations

One of the main results of twistor theory has been a deeper understanding of the solutions of partial differential equations of classical field theory. Remarkably, a problem in analysis becomes a purely geometrical problem (Ward 1981b, Ward and Wells 1990). For example, in Bateman 1904 it was shown that the general real-analytic solution of the wave equation $\square \phi=0$ in Minkowski space-time is

$$
\begin{equation*}
\phi(x, y, z, t)=\int_{-\pi}^{\pi} F(x \cos \theta+y \sin \theta+i z, y+i z \sin \theta+t \cos \theta, \theta) d \theta \tag{4.3.1}
\end{equation*}
$$

where $F$ is an arbitrary function of three variables, complex-analytic in the first two. Indeed, twistor theory tells us that $F$ is a function on $P T$. More precisely, let $f\left(\omega^{\boldsymbol{A}}, \pi_{\boldsymbol{A}^{\prime}}\right)$ be a complex-analytic function, homogeneous of degree -2 , i.e. such that

$$
\begin{equation*}
f\left(\lambda \omega^{A}, \lambda \pi_{A^{\prime}}\right)=\lambda^{-2} f\left(\omega^{A}, \pi_{A^{\prime}}\right) \tag{4.3.2}
\end{equation*}
$$

and possibly having singularities (Ward 1981b). We now define a field $\phi\left(x^{a}\right)$ by

$$
\begin{equation*}
\phi\left(x^{a}\right) \equiv \frac{1}{2 \pi i} \oint f\left(i x^{A A^{\prime}} \pi_{A^{\prime}}, \pi_{B^{\prime}}\right) \pi_{C^{\prime}} d \pi^{C^{\prime}} \tag{4.3.3}
\end{equation*}
$$

where the integral is taken over any closed one-dimensional contour that avoids the singularities of $f$. Such a field satisfies the wave equation, and every solution of $\square \phi=0$ can be obtained in this way. The function $f$ has been taken to have homogeneity -2 since the corresponding one-form $f \pi_{C^{\prime}} d \pi^{C^{\prime}}$ has homogeneity zero and hence is a one-form on projective twistor space $P T$, or on some subregion of $P T$, since it may have singularities. The homogeneity is related to the property of $f$ of being a free function of three variables. Since $f$ is not defined on the whole of $P T$, and $\phi$ does not determine $f$ uniquely, because we can replace $f$ by $f+\tilde{f}$, where $\tilde{f}$ is any function such that

$$
\begin{equation*}
\oint \tilde{f} \pi_{C^{\prime}} d \pi^{C^{\prime}}=0, \tag{4.3.4}
\end{equation*}
$$

## 4. Twistor Spaces

we conclude that $f$ is an element of the sheaf-cohomology group $H^{1}\left(P T^{4}, O(-2)\right)$, i.e. the complex vector space of arbitrary complex-analytic functions of three variables, not subject to any differential equations (Penrose 1980, Ward 1981b, Ward and Wells 1990). Remarkably, a conformally invariant isomorphism exists between the complex vector space of holomorphic solutions of $\square \phi=0$ on the forward tube $C M^{+}$(i.e. the domain of definition of positive-frequency fields), and the sheaf-cohomology group $H^{1}\left(P T^{+}, O(-2)\right)$.

It is now instructive to summarize some basic ideas of sheaf-cohomology theory and its use in twistor theory, following Penrose 1980. For this purpose, let us begin by recalling how Cech cohomology is obtained. We consider a Hausdorff paracompact topological space $X$, covered with a locally finite system of open sets $U_{i}$. With respect to this covering, we define a cochain with coefficients in an additive Abelian group $G$ (e.g. $Z, R$ or $C$ ) in terms of elements $f_{i}, f_{i j}, f_{i j k \ldots} \ldots G$. These elements are assigned to the open sets $U_{i}$ of the covering, and to their non-empty intersections, as follows: $f_{i}$ to $U_{i}, f_{i j}$ to $U_{i} \cap U_{j}, f_{i j k}$ to $U_{i} \cap U_{j} \cap U_{k}$ and so on. The elements assigned to non-empty intersections are completely antisymmetric, so that $f_{i \ldots p}=f_{[i \ldots p]}$. One is thus led to define

$$
\begin{align*}
& \text { zero - cochain } \alpha \equiv\left(f_{1}, f_{2}, f_{3}, \ldots\right)  \tag{4.3.5}\\
& \text { one - cochain } \beta \equiv\left(f_{12}, f_{23}, f_{13}, \ldots\right)  \tag{4.3.6}\\
& \text { two - cochain } \gamma \equiv\left(f_{123}, f_{124}, \ldots\right) \tag{4.3.7}
\end{align*}
$$

and the coboundary operator $\delta$ :

$$
\begin{gather*}
\delta \alpha \equiv\left(f_{2}-f_{1}, f_{3}-f_{2}, f_{3}-f_{1}, \ldots\right) \equiv\left(f_{12}, f_{23}, f_{13}, \ldots\right),  \tag{4.3.8}\\
\delta \beta \equiv\left(f_{12}-f_{13}+f_{23}, f_{12}-f_{14}+f_{24}, \ldots\right) \equiv\left(f_{123}, f_{121}, \ldots\right) . \tag{4.3.9}
\end{gather*}
$$

By virtue of (4.3.8)-(4.3.9), one finds $\delta^{2} \alpha=\delta^{2} \beta=\ldots=0$. Cocycles $\gamma$ are cochains such that $\delta \gamma=0$. Coboundaries are a particular set of cocycles, i.e. such that

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$\gamma=\delta \beta$ for some cochain $\beta$. Of course, all coboundaries are cocycles, whereas the converse does not hold. This enables one to define the $\mathrm{p}^{\text {th }}$ cohomology group as the quotient space

$$
\begin{equation*}
H_{\left\{U_{i}\right\}}^{p}(X, G) \equiv G_{C C}^{p} / G_{C B}^{p} \tag{4.3.10}
\end{equation*}
$$

where $G_{C C}^{p}$ is the additive group of p-cocycles, and $G_{C B}^{p}$ is the additive group of p-coboundaries. To avoid having a definition which depends on the covering $\left\{U_{i}\right\}$, one should then take finer and finer coverings of $X$ and settle on a sufficiently fine covering $\left\{U_{i}\right\}^{*}$. Following Penrose 1980, by this we mean that all the $H^{p}\left(U_{i} \cap\right.$ $\left.\ldots \cap U_{k}, G\right)$ vanish $\forall p>0$. One then defines

$$
\begin{equation*}
H_{\left\{U_{i}\right\}^{p}}(X, G) \equiv H^{p}(X, G) \tag{4.3.11}
\end{equation*}
$$

We always assume such a covering exists, is countable and locally finite. Note that, rather than thinking of $f_{i}$ as an element of $G$ assigned to $U_{i}$, of $f_{i j}$ as assigned to $U_{i j}$ and so on, we can think of $f_{i}$ as a function defined on $U_{i}$ and taking a constant value $\in G$. Similarly, we can think of $f_{i j}$ as a $G$-valued constant function defined on $U_{i} \cap U_{j}$, and this implies it is not strictly necessary to assume that $U_{i} \cap U_{j}$ is non-empty.

The generalization to sheaf cohomology is obtained if we do not require the functions $f_{i}, f_{i j}, f_{i j k} \ldots$ to be constant (there are also cases when the additive group $G$ is allowed to vary from point to point in $X$ ). The assumption of main interest is the holomorphic nature of the $f$ 's. A sheaf is so defined that the Cech cohomology previously defined works as well as before (Penrose 1980). In other words, a sheaf $S$ defines an additive group $G_{u}$ for each open set $U \subset X$. Relevant examples are as follows.
(i) The sheaf $O$ of germs of holomorphic functions on a complex manifold $X$ is obtained if $G_{u}$ is taken to be the additive group of all holomorphic functions on $U$.

## 4. Twistor Spaces

(ii) Twisted holomorphic functions, i.e. functions whose values are not complex numbers, but are taken in some complex line bundle over $X$.
(iii) A particular class of twisted functions is obtained if $X$ is projective twistor space $P T$ (or $P T^{+}$, or $P T^{-}$), and the functions studied are holomorphic and homogeneous of some degree n in the twistor variable, i.e.

$$
\begin{equation*}
f\left(\lambda \omega^{A}, \lambda \pi_{A^{\prime}}\right)=\lambda^{n} f\left(\omega^{A}, \pi_{A^{\prime}}\right) \tag{4.3.12}
\end{equation*}
$$

If $G_{u}$ consists of all such twisted functions on $U \subset X$, the resulting sheaf, denoted by $O(n)$, is the sheaf of germs of holomorphic functions twisted by $n$ on $X$.
(iv) We can also consider vector-bundle-valued functions, where the vector bundle $B$ is over $X$, and $G_{u}$ consists of the cross-sections of the portion of $B$ lying above $U$.

Defining cochains and coboundary operator as before, with $f_{i} \in G_{U_{i}}$ and so on, we obtain the $\mathrm{p}^{\text {th }}$ cohomology group of $X$, with coefficients in the sheaf $S$, as the quotient space

$$
\begin{equation*}
H^{p}(X, S) \equiv G^{p}(S) / G_{C B}^{p}(S) \tag{4.3.13}
\end{equation*}
$$

where $G^{p}(S)$ is the group of p-cochains with coefficients in $S$, and $G_{C}^{p}{ }_{B}(S)$ is the group of p-coboundaries with coefficients in $S$. Again, we take finer and finer coverings $\left\{U_{i}\right\}$ of $X$, and we settle on a sufficiently fine covering. To understand this concept, we recall the following definitions (Penrose 1980).

Definition 4.3.1A coherent analytic sheaf is locally defined by $n$ holomorphic functions factored out by a set of $s$ holomorphic relations.

Definition 4.3.2A Stein manifold is a holomorphically convex open subset of $C^{n}$.

Thus, we can say that, provided $S$ is a coherent analytic sheaf, sufficiently fine means that each of $U_{i}, U_{i} \cap U_{j}, U_{i} \cap U_{j} \cap U_{k} \ldots$ is a Stein manifold. If $X$ is Stein and $S$ is coherent analytic, then $H^{p}(X, S)=0, \forall p>0$.

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We can now come back to the remarks following Eq. (4.3.4), i.e. the interpretation of twistor functions as elements of $H^{1}\left(P T^{+}, O(-2)\right)$. Let $X$ be a part of $P T$, e.g. the neighbourhood of a line in $P T$, or the top half $P T^{+}$, or the closure $\overline{P T^{+}}$of the top half. We assume $X$ can be covered with two open sets $U_{1}, U_{2}$ such that every projective line $L$ in $X$ meets $U_{1} \cap U_{2}$ in an annular region. For us, $U_{1} \cap U_{2}$ corresponds to the domain of definition of a twistor function $f\left(Z^{\alpha}\right)$, homogeneous of degree n in the twistor $Z^{\alpha}$ (see (4.3.12)). Then $f \equiv f_{12} \equiv f_{2}-f_{1}$ is a twisted function on $U_{1} \cap U_{2}$, and defines a one-cochain $\in$, with coefficients in $O(n)$, for $X$. By construction $\delta \in=0$, hence $\in$ is a cocycle. For this covering, the one-coboundaries are functions of the form $l_{2}-l_{1}$, where $l_{2}$ is holomorphic on $U_{2}$ and $l_{1}$ on $U_{1}$. The equivalence between twistor functions is just the cohomological equivalence between one-cochains $\in, \epsilon^{\prime}$ that their difference should be a coboundary: $\epsilon^{\prime}-\epsilon=\delta \alpha$, with $\alpha=\left(l_{1}, l_{2}\right)$ This is why we view twistor functions as defining elements of $H^{1}(X, O(n))$. Indeed, if we try to get finer coverings, we realize it is often impossible to make $U_{1}$ and $U_{2}$ into Stein manifolds. However, if $X=\overline{P T^{+}}$, the covering $\left\{U_{1}, U_{2}\right\}$ by two sets is sufficient for any analytic, positive-frequency field (Penrose 1980).

The most striking application of twistor theory to partial differential equations is perhaps the geometric characterization of anti-self-dual space-times with a cosmological constant. For these space-times, the Weyl tensor takes the form

$$
\begin{equation*}
C_{a b c d}^{(A . S . D .)}=\psi_{A B C D} \boldsymbol{e}_{A^{\prime} B^{\prime}} e_{C^{\prime} D^{\prime}}, \tag{4.3.14}
\end{equation*}
$$

and the Ricci tensor reads

$$
\begin{equation*}
R_{a b}=-2 \Phi_{a b}+6 \Lambda g_{a b} . \tag{4.3.15}
\end{equation*}
$$

With our notation, $e_{A B}$ and $e_{A^{\prime} B^{\prime}}$ are the curved-space version of the $\epsilon$-symbols (denoted again by $\in_{A B}$ and $\in_{A^{\prime} B^{\prime}}$ in Eqs. (2.1.36) and (4.2.1)), $\Phi_{a b}$ is the tracefree part of Ricci, $24 \Lambda$ is the trace $R=R^{a}{ }_{a}$ of Ricci (Ward 1980b). The local

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structure in projective twistor space which gives information about the metric is a pair of differential forms: a one-form $\tau$ homogeneous of degree 2 and a three-form $\rho$ homogeneous of degree 4 . Basically, $\tau$ contains relevant information about $e_{A^{\prime} B^{\prime}}$ and $\rho$ tells us about $e_{A B}$, hence their knowledge determines $g_{a b}=e_{A B} e_{A^{\prime} B^{\prime}}$. The result proved in Ward 1980b states that a one-to-one correspondence exists between sufficiently local anti-self-dual solutions with scalar curvature $R=24 \Lambda$ and sufficiently small deformations of flat projective twistor space which preserve the one-form $\tau$ and the three-form $\rho$, where $\tau \Lambda d \tau=2 \Lambda \rho$. We now describe how to define the forms $\tau$ and $\rho$, whereas the explicit construction of a class of anti-self-dual space-times is given in chapter five.

The geometrical framework is twistor space $P$ defined at the end of section 4.2, i.e. the space of all $\alpha$-surfaces in $(M, g)$. We take $M$ to be sufficiently small and convex to ensure that $P$ is a complex manifold with topology $R^{4} \times S^{2}$, since every point in an anti-self-dual space-time has such a neighbourhood (Ward 1980b). If $Q$, represented by the pair $\left(\alpha^{A}, \beta_{A^{\prime}}\right)$, is any vector in $P$, then $\tau$ is defined by

$$
\begin{equation*}
\tau(Q) \equiv e^{A^{\prime} B^{\prime}} \pi_{A^{\prime}} \beta_{B^{\prime}} \tag{4.3.16}
\end{equation*}
$$

To make sure $\tau$ is well-defined, one has to check that the right-hand side of (4.3.16) remains covariantly constant over $\alpha$-surfaces, i.e. is annihilated by the first-order operator $\lambda^{A} \pi^{A^{\prime}} \nabla_{A A^{\prime}}$, since otherwise $\tau$ does not correspond to a differential form on $P$. It turns out that $\tau$ is well-defined provided the trace-free part of Ricci vanishes. This is proved using spinor Ricci identities and the equations of local twistor transport as follows (Ward 1980b).

Let $v$ be a vector field on the $\alpha$-surface $Z$ such that $\in v^{a}$ joins $Z$ to the neighbouring $\alpha$-surface $Y$. Since $\in v^{a}$ acts as a connecting vector, the Lie bracket of $v^{a}$ and $\lambda^{B} \pi^{B^{\prime}}$ vanishes for all $\lambda^{B}$, i.e.

$$
\begin{equation*}
\lambda^{B} \pi^{B^{\prime}} \nabla_{B B^{\prime}} v^{A A^{\prime}}-v^{B B^{\prime}} \nabla_{B B^{\prime}} \lambda^{A} \pi^{A^{\prime}}=0 \tag{4.3.17}
\end{equation*}
$$

Thus, defining

$$
\begin{equation*}
\beta_{A^{\prime}} \equiv v^{B B^{\prime}} \nabla_{B B^{\prime}} \pi_{A^{\prime}}, \tag{4.3.18}
\end{equation*}
$$

## 4. Twistor Spaces

one finds

$$
\begin{equation*}
\pi_{A^{\prime}} \lambda^{B} \pi^{B^{\prime}} \nabla_{B B^{\prime}} v^{A A^{\prime}}=\lambda^{A} \beta^{A^{\prime}} \pi_{A^{\prime}} \tag{4.3.19}
\end{equation*}
$$

If one now applies the torsion-free spinor Ricci identities (see Eqs. (6.3.17)-( 6.3.18) setting $\tilde{\chi}=\tilde{\Sigma}=X=\Sigma=0$ therein), one finds that the spinor field $\beta_{A^{\prime}}(x)$ on $Z$ satisfies the equation

$$
\begin{equation*}
\lambda^{B} \pi^{B^{\prime}} \nabla_{B B^{\prime}} \beta_{A^{\prime}}=-i \lambda^{B} \pi^{B^{\prime}} P_{A B A^{\prime} B^{\prime}} \alpha^{A} \tag{4.3.20}
\end{equation*}
$$

where $P_{a b}=\Phi a b-\Lambda g_{a b}$ and $\alpha^{A}=i v^{A C^{\prime}} \pi_{C^{\prime}}$. Moreover, Eq. (4.3.19) and the Leibniz rule imply that

$$
\begin{equation*}
\lambda^{B} \pi^{B^{\prime}} \nabla_{B B^{\prime}} \alpha^{A}=-i \lambda^{A} \pi^{A^{\prime}} \beta_{A^{\prime}} \tag{4.3.21}
\end{equation*}
$$

since $\pi^{B^{\prime}} \nabla_{B B^{\prime}} \pi_{C^{\prime}}=0$. Eqs. (4.3.20)-(4.3.21) are indeed the equations of local twistor transport, and Eq. (4.3.20) leads to

$$
\begin{align*}
\lambda^{C} \pi^{C^{\prime}} \nabla_{C C^{\prime}}\left(e^{A^{\prime} B^{\prime}} \pi_{A^{\prime}} \beta_{B^{\prime}}\right) & =e^{A^{\prime} B^{\prime}} \pi_{A^{\prime}}\left(\lambda^{C} \pi^{C^{\prime}} \nabla_{C C^{\prime}} \beta_{B^{\prime}}\right) \\
& =-i \lambda^{B} \pi^{B^{\prime}} \pi_{C^{\prime}} e^{C^{\prime} A^{\prime}} \alpha^{A}\left(\Phi_{A B A^{\prime} B^{\prime}}-\Lambda e_{A B} e_{A^{\prime} B^{\prime}}\right) \\
& =i \lambda^{B} \pi^{\boldsymbol{A}^{\prime}} \pi^{B^{\prime}} \alpha^{\boldsymbol{A}} \Phi_{A B A^{\prime} \boldsymbol{B}^{\prime}} \tag{4.3.22}
\end{align*}
$$

since $\pi^{A^{\prime}} \pi^{B^{\prime}} e_{A^{\prime} B^{\prime}}=0$. Hence, as we said before, $\tau$ is well-defined provided the trace-free part of Ricci vanishes. Note that, strictly, $\tau$ is a twisted form rather than a form on $P$, since it is homogeneous of degree 2 , one from $\pi_{A^{\prime}}$ and one from $\beta_{B^{\prime}}$. By contrast, a one-form would be independent of the scaling of $\pi_{A^{\prime}}$ and $\beta_{B^{\prime}}$ (Ward 1980b).

We are now in a position to define the three-form $\rho$, homogeneous of degree 4 . For this purpose, let us denote by $Q_{h}, h=1,2,3$ three vectors in $P$, represented by the pairs $\left(\alpha_{h}^{A}, \beta_{h A}\right)$. The corresponding $\rho\left(Q_{1}, Q_{2}, Q_{3}\right)$ is obtained by taking

$$
\begin{equation*}
\rho_{123} \equiv \frac{1}{2}\left(e^{A^{\prime} B^{\prime}} \pi_{A^{\prime}} \beta_{1 B^{\prime}}\right)\left(e_{A B} \alpha_{2}^{A} \alpha_{3}^{B}\right) \tag{4.3.23}
\end{equation*}
$$

## 4. Twistor Spaces

and then anti-symmetrizing $\rho_{123}$ over $1,2,3$. This yields

$$
\begin{equation*}
\rho\left(Q_{1}, Q_{2}, Q_{3}\right) \equiv \frac{1}{6}\left(\rho_{125}-\rho_{132}+\rho_{231}-\rho_{213}+\rho_{312}-\rho_{321}\right) . \tag{4.3.24}
\end{equation*}
$$

The reader can check that, by virtue of Eqs. (4.3.20)-(4.3.21), $\rho$ is well-defined, since it is covariantly constant over $\alpha$-surfaces:

$$
\begin{equation*}
\lambda^{A} \pi^{A^{\prime}} \nabla_{A A^{\prime}} \rho\left(Q_{1}, Q_{2}, Q_{3}\right)=0 . \tag{4.3.25}
\end{equation*}
$$

## PENROSE TRANSFORM FOR GRAVITATION


#### Abstract

Deformation theory of complex manifolds is applied to construct a class of anti-self-dual solutions of Einstein's vacuum equations, following the work of Penrose and Ward. The hard part of the analysis is to find the holomorphic cross-sections of a deformed complex manifold, and the corresponding conformal structure of an anti-self-dual space-time. This calculation is repeated in detail, using complex analysis and two-component spinor techniques.

If no assumption about anti-self-duality is made, twistor theory is by itself insufficient to characterize geometrically a solution of the full Einstein equations. After a brief review of alternative ideas based on the space of complex null geodesics of complex space-time, and Einstein-bundle constructions, attention is focused on the recent attempt by Penrose to define twistors as charges for massless spin$\frac{3}{2}$ fields. This alternative definition is considered since a vanishing Ricci tensor provides the consistency condition for the existence and propagation of massless spin- $\frac{3}{2}$ fields in curved space-time, whereas in Minkowski space-time the space of charges for such fields is naturally identified with the corresponding twistor space.

The two-spinor analysis of the Dirac form of such fields in Minkowski spacetime is carried out in detail by studying their two potentials with corresponding gauge freedoms. The Rarita-Schwinger form is also introduced, and self-dual vacuum Maxwell fields are obtained from massless spin- $\frac{3}{2}$ fields by spin-lowering. In curved space-time, however, the local expression of spin- $\frac{3}{2}$ field strengths in terms of the second of these potentials is no longer possible, unless one studies the selfdual Ricci-flat case. Thus, much more work is needed to characterize geometrically a Ricci-flat (complex) space-time by using this alternative concept of twistors.


## 5. Penrose Transform for Gravitation

### 5.1 Anti-Self-Dual Space-Times

Following Ward 1978, we now use twistor-space techniques to construct a family of anti-self-dual solutions of Einstein's vacuum equations. Bearing in mind the space-time twistor-space correspondence in Minkowskian geometry described in section 4.1, we take a region $R$ of $C M^{\#}$, whose corresponding region in $P T$ is $\widetilde{\mathcal{R}}$ Moreover, $N$ is the non-projective version of $\widetilde{\mathcal{R}}$, which implies $N \subset T \subset C^{4}$. In other words, as coordinates on $N$ we may use $\left(\omega^{o}, \omega^{1}, \pi_{o^{\prime}}, \pi_{1^{\prime}}\right)$. The geometricallyoriented reader may like it to know that three important structures are associated with $N$ :
(i) the fibration $\left(\omega^{A}, \pi_{A^{\prime}}\right) \rightarrow \pi_{A^{\prime}}$, which implies that $N$ becomes a bundle over $C^{2}-\{0\}$;
(ii) the two-form $\frac{1}{2} d \omega_{A} \wedge d \omega^{A}$ on each fibre;
(iii) the projective structure $\mathcal{N} \rightarrow \widetilde{\mathcal{R}}$.

Deformations of $N$ which preserve this projective structure correspond to rightflat metrics (see section 4.2) in $R$. To obtain such deformations, cover $N$ with two patches $Q$ and $\widehat{\boldsymbol{Q}}$. Coordinates on $Q$ and on $\widehat{\mathcal{Q}}$ are $\left(\omega^{\boldsymbol{A}}, \pi_{\boldsymbol{A}^{\prime}}\right)$ and $\left(\widehat{\omega}^{\boldsymbol{A}}, \widehat{\pi}_{\boldsymbol{A}^{\prime}}\right)$ respectively. We may now glue $Q$ and $\widehat{\mathcal{Q}}$ together according to

$$
\begin{gather*}
\widehat{\omega}^{A}=\omega^{A}+f^{A}\left(\omega^{B}, \pi_{B^{\prime}}\right)  \tag{5.1.1}\\
\widehat{\pi}_{A^{\prime}}=\pi_{A^{\prime}} \tag{5.1.2}
\end{gather*}
$$

where $f^{A}$ is homogeneous of degree 1 , holomorphic on $\mathcal{Q} \bigcap \widehat{\mathcal{Q}}$, and satisfies

$$
\begin{equation*}
\operatorname{det}\left(\epsilon_{A}^{B}+\frac{\partial f^{B}}{\partial \omega^{A}}\right)=1 \tag{5.1.3}
\end{equation*}
$$

Such a patching process yields a complex manifold $N^{D}$ which is a deformation of $N$. The corresponding right-flat space-time $\mathcal{G}$ is such that its points correspond

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to the holomorphic cross-sections of $N^{D}$. The hard part of the analysis is indeed to find these cross-sections, but this can be done explicitly for a particular class of patching functions. For this purpose, we first choose a constant spinor field $P^{A A^{\prime} B^{\prime}}=P^{A\left(A^{\prime} B^{\prime}\right)}$ and a homogeneous holomorphic function $g\left(\gamma, \pi A^{\prime}\right)$ of three complex variables:

$$
\begin{equation*}
g\left(\lambda^{3} \gamma, \lambda \pi_{A^{\prime}}\right)=\lambda^{-1} g\left(\gamma, \pi_{A^{\prime}}\right) \forall \lambda \in C-\{0\} \tag{5.1.4}
\end{equation*}
$$

This enables one to define the spinor field

$$
\begin{equation*}
p^{A} \equiv p^{A A^{\prime} B^{\prime}} \pi_{A^{\prime}} \pi_{B^{\prime}} \tag{5.1.5}
\end{equation*}
$$

and the patching function

$$
\begin{equation*}
f^{A} \equiv p^{A} g\left(p_{B} \omega^{B}, \pi_{B^{\prime}}\right) \tag{5.1.6}
\end{equation*}
$$

and the function

$$
\begin{equation*}
F\left(x^{a}, \pi_{A^{\prime}}\right) \equiv g\left(i p_{A} x^{A C^{\prime}} \pi_{C^{\prime}}, \pi_{A^{\prime}}\right) \tag{5.1.7}
\end{equation*}
$$

Under suitable assumptions on the singularities of $g$, $F$ may turn out to be holomorphic if $x^{a} \in R$ and if the ratio $\left.\tilde{\pi} \equiv \frac{\pi_{o^{\prime}}}{\pi_{1^{\prime}}} \in\right] \frac{\mathbf{1}}{\mathbf{2}}, \frac{\mathbf{5}}{\mathbf{2}}$ [. It is also possible to express $F$ as the difference of two contour integrals after defining the differential form

$$
\begin{equation*}
\Omega \equiv\left(2 \pi i \rho^{A^{\prime}} \pi_{A^{\prime}}\right)^{-1} F\left(x^{b}, \rho_{B^{\prime}}\right) \rho_{C^{\prime}} d \rho^{C^{\prime}} \tag{5.1.8}
\end{equation*}
$$

In other words, if T and $\widehat{\Gamma}$ are closed contours on the projective $\rho_{A^{\prime}}$-sphere defined by $|\tilde{\rho}|=1$ and $|\tilde{\rho}|=2$ respectively, we may define the function

$$
\begin{equation*}
h \equiv \oint_{\Gamma} \Omega \tag{5.1.9}
\end{equation*}
$$

holomorphic for $\tilde{\pi}<2$, and the function

$$
\begin{equation*}
\widehat{h} \equiv \oint_{\hat{\Gamma}} \Omega, \tag{5.1.10}
\end{equation*}
$$

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holomorphic for $\bar{\pi}>1$. Thus, by virtue of Cauchy's integral formula, one finds (cf. Ward 1978)

$$
\begin{equation*}
F\left(x^{a}, \pi_{A^{\prime}}\right)=\widehat{h}\left(x^{a}, \pi_{A^{\prime}}\right)-h\left(x^{a}, \pi_{A^{\prime}}\right) \tag{5.1.11}
\end{equation*}
$$

The basic concepts of sheaf-cohomology presented in section 4.3 are now useful to understand the deep meaning of these formulae. For any fixed $x^{a}, F\left(x^{a}, \pi_{A^{\prime}}\right)$ determines an element of the sheaf-cohomology group $H^{1}\left(P_{1}(C), O(-1)\right)$, where $P_{1}(C)$ is the Riemann sphere of projective $\pi_{A^{\prime}}$ spinors and $O(-1)$ is the sheaf of germs of holomorphic functions of $\pi_{A^{\prime}}$, homogeneous of degree -1 . Since $H^{1}$ vanishes, $F$ is actually a coboundary. Hence it can be split according to (5.1.11).

In the subsequent calculations, it will be useful to write a solution of the Weyl equation $\nabla^{\boldsymbol{A} \boldsymbol{A}^{\prime}} \boldsymbol{\psi}_{\boldsymbol{A}}=\mathbf{0}$ in the form

$$
\begin{equation*}
\psi_{A} \equiv i \pi^{A^{\prime}} \nabla_{A A^{\prime}} h\left(x^{a}, \pi_{C^{\prime}}\right) \tag{5.1.12}
\end{equation*}
$$

Moreover, following again Ward 1978, we note that a spinor field $\boldsymbol{\xi}_{\boldsymbol{A}^{\prime}} \boldsymbol{B}^{\boldsymbol{\prime}}(\boldsymbol{x})$ can be defined by

$$
\begin{equation*}
\xi_{A^{\prime}}^{B^{\prime}} \pi_{B^{\prime}} \equiv i p^{A B^{\prime} C^{\prime}} \pi_{B^{\prime}} \pi_{C^{\prime}} \nabla_{A A^{\prime}} h\left(x, \pi_{D^{\prime}}\right) \tag{5.1.13}
\end{equation*}
$$

and that the following identities hold:

$$
\begin{gather*}
i p^{A A^{\prime} B^{\prime}} \pi_{B^{\prime}} \nabla_{A A^{\prime}} h\left(x, \pi_{C^{\prime}}\right)=\xi \equiv \frac{1}{2} \xi_{A^{\prime}}^{A^{\prime}}  \tag{5.1.14}\\
\psi_{A} p^{A A^{\prime} B^{\prime}}=-\xi^{\left(A^{\prime} B^{\prime}\right)} \tag{5.1.15}
\end{gather*}
$$

We may now get back to our deformed twistor space $N^{D}$, written in the form (cf. (5.1.1)-(5.1.2))

$$
\begin{gather*}
=\omega^{A}+p^{A} g\left(p_{B} \omega^{B}, \pi_{B^{\prime}}\right)  \tag{5.1.16a}\\
\widehat{\pi}_{A^{\prime}}=\pi_{A^{\prime}} \tag{5.1.16b}
\end{gather*}
$$

In the light of the splitting (5.1.11), holomorphic sections of $N^{D}$ are given by

$$
\begin{equation*}
\omega^{A}\left(x^{b}, \pi_{B^{\prime}}\right)=i x^{A A^{\prime}} \pi_{A^{\prime}}+p^{A} h\left(x^{b}, \pi_{B^{\prime}}\right) \text { in } \mathcal{Q} \tag{5.1.17}
\end{equation*}
$$

$$
\begin{equation*}
\widehat{\omega}^{A}\left(x^{b}, \pi_{B^{\prime}}\right)=i x^{A A^{\prime}} \pi_{A^{\prime}}+p^{A} \widehat{h}\left(x^{b}, \pi_{B^{\prime}}\right) \text { in } \widehat{\mathcal{Q}}, \tag{5.1.18}
\end{equation*}
$$

where $x^{b}$ are complex coordinates on $\mathcal{G}$. The conformal structure of $\mathcal{G}$ can be computed as follows. A vector $U=U^{B B^{\prime}} \nabla_{B B^{\prime}}$ at $x^{a} \in \mathcal{G}$ may be represented in $N^{D}$ by the displacement

$$
\begin{equation*}
\delta \omega^{A}=U^{b} \nabla_{b} \omega^{A}\left(x^{c}, \pi_{C^{\prime}}\right) \tag{5.1.19a}
\end{equation*}
$$

By virtue of (5.1.17), Eq. (5.1.19a) becomes

$$
\begin{equation*}
\delta \omega^{A}=U^{B B^{\prime}}\left(i \epsilon_{B}^{A} \pi_{B^{\prime}}+p^{A} \nabla_{B B^{\prime}} h\left(x^{c}, \pi_{C^{\prime}}\right)\right) \tag{5.1.19b}
\end{equation*}
$$

The vector $U$ is null, by definition, if and only if

$$
\begin{equation*}
\delta \omega^{A}\left(x^{b}, \pi_{B^{\prime}}\right)=0 \tag{5.1.20}
\end{equation*}
$$

for some spinor field $\pi_{B^{\prime}}$. To prove that the solution of (5.1.20) exists, one defines (see (5.1.14))

$$
\begin{equation*}
\Omega_{A A^{\prime}}^{B B^{\prime}} \equiv \theta \epsilon_{A}^{B} \epsilon_{A^{\prime}}^{B^{\prime}}-\psi_{A} p_{A^{\prime}}^{B B^{\prime}} \tag{5.1.21}
\end{equation*}
$$

We are now aiming to show that the desired solution of Eq. (5.1.20) is given by

$$
\begin{equation*}
U^{B B^{\prime}}=\Omega_{A A^{\prime}}^{B B^{\prime}} \lambda^{A} \pi^{A^{\prime}} \tag{5.1.23}
\end{equation*}
$$

Indeed, by virtue of (5.1.21)-(5.1.23) one finds

$$
\begin{equation*}
U^{B B^{\prime}}=(1-\xi) \lambda^{B} \pi^{B^{\prime}}-\psi_{A} p_{A^{\prime}}^{B B^{\prime}} \lambda^{A} \pi^{A^{\prime}} \tag{5.1.24}
\end{equation*}
$$

Thus, since $\pi^{B^{\prime}} \pi_{B^{\prime}}=0$, the calculation of (5.1.19b) yields

$$
\begin{align*}
\delta \omega^{A} & =-\psi_{C} \lambda^{C} \pi^{A^{\prime}}\left[i p_{A^{\prime}}^{A B^{\prime}} \pi_{B^{\prime}}+p_{A^{\prime}}^{B B^{\prime}} p^{A} \nabla_{B B^{\prime}} h(x, \pi)\right] \\
& +(1-\xi) \lambda^{B} \pi^{B^{\prime}} p^{A} \nabla_{B B^{\prime}} h(x, \pi) \tag{5.1.25}
\end{align*}
$$

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Note that (5.1.12) may be used to re-express the second line of (5.1.25). This leads to

$$
\begin{equation*}
\delta \omega^{A}=-\psi_{C} \lambda^{C} \Gamma^{A}, \tag{5.1.26}
\end{equation*}
$$

where

$$
\begin{align*}
\Gamma^{A} & \equiv \pi^{A^{\prime}}\left[i p_{A^{\prime}}{ }^{A B^{\prime}} \pi_{B^{\prime}}+p_{A^{\prime}}^{B B^{\prime}} p^{A} \nabla_{B B^{\prime}} h(x, \pi)\right]+i(1-\xi) p^{A} \\
& =-i p^{A A^{\prime} B^{\prime}} \pi_{A^{\prime}} \pi_{B^{\prime}}+i p^{A}+p^{A}\left[-p^{B B^{\prime} A^{\prime}} \pi_{A^{\prime}} \nabla_{B B^{\prime}} h(x, \pi)-i \xi\right] \\
& =[-i+i+i \xi-i \xi] p^{A}=0, \tag{5.1.27}
\end{align*}
$$

in the light of (5.1.5) and (5.1.14). Hence the solution of (5.1.20) is given by (5.1.23).

Such null vectors determine the conformal metric of $\mathcal{G}$. For this purpose, one defines (Ward 1978)

$$
\begin{gather*}
\nu_{A^{\prime}}^{B^{\prime}} \equiv \epsilon_{A^{\prime}}^{B^{\prime}}-\xi_{A^{\prime}}^{B^{\prime}},  \tag{5.1.28}\\
\Lambda \equiv \frac{\theta}{2} \nu_{A^{\prime} B^{\prime}} \nu^{A^{\prime} B^{\prime}},  \tag{5.1.29}\\
\Sigma_{B B^{\prime}} C^{C C^{\prime}} \equiv \theta^{-1} \epsilon_{B}^{C} \epsilon_{B^{\prime}}^{C^{\prime}}+\Lambda^{-1} \psi_{B} p_{A^{\prime}}^{C C^{\prime}} \nu_{B^{\prime}} A^{\prime}  \tag{5.1.30}\\
\hline
\end{gather*}
$$

Interestingly, $\Sigma_{b}{ }^{c}$ is the inverse of $\Omega^{b}{ }_{a}$, since

$$
\begin{equation*}
\Omega_{a}^{b} \Sigma_{b}^{c}=\delta_{a}^{c} \tag{5.1.31}
\end{equation*}
$$

Indeed, defining

$$
\begin{gather*}
{H_{A^{\prime}}}_{C C^{\prime}} \equiv{p_{A^{\prime}}}_{C C^{\prime}}-p_{D^{\prime}}^{C C^{\prime}} \xi_{A^{\prime}}^{D^{\prime}}  \tag{5.1.32}\\
\Phi_{A^{\prime}} C C^{\prime} \equiv\left[\theta \Lambda^{-1} H_{A^{\prime}} C C^{\prime}-\Lambda^{-1}{p_{A^{\prime}}}_{B B^{\prime}} \psi_{B} H_{B^{\prime}} C C^{\prime}-\theta^{-1}{p_{A^{\prime}}}_{C C^{\prime}}\right] \tag{5.1.33}
\end{gather*}
$$

a detailed calculation shows that

$$
\begin{equation*}
\Omega^{B B_{A A^{\prime}}}, \Sigma_{B B^{\prime}} C C^{\prime}-\epsilon_{A}^{C} \epsilon_{A^{\prime}} C^{\prime}=\psi_{A} \Phi_{A^{\prime}} C C^{\prime} . \tag{5.1.34}
\end{equation*}
$$

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One can now check that the right-hand side of (5.1.34) vanishes (see problem 5.1). Hence (5.1.31) holds. For our anti-self-dual space-time $\mathcal{G}$, the metric $g=$ $g_{a b} d x^{a} \otimes d x^{b}$ is such that

$$
\begin{equation*}
g_{a b}=\Xi(x) \Sigma_{a}^{c} \Sigma_{b c} \tag{5.1.35}
\end{equation*}
$$

Two null vectors $U$ and $V$ at $x \in \mathcal{G}$ have, by definition, the form

$$
\begin{align*}
U^{A A^{\prime}} & \equiv \Omega_{B B^{\prime}}^{A A^{\prime}} \lambda^{B} \alpha^{B^{\prime}},  \tag{5.1.36}\\
V^{A A^{\prime}} & \equiv \Omega_{B B^{\prime}}^{A A^{\prime}} \chi^{B} \beta^{B^{\prime}}, \tag{5.1.37}
\end{align*}
$$

for some spinors $\lambda^{B} X^{B}, \alpha^{B^{\prime}}, \beta^{B^{\prime}}$. In the deformed space $N D, U$ and $V$ correspond to two displacements $\delta_{1} \omega^{A}$ and $\delta_{2} \omega^{A}$ respectively, as in Eq. (5.1.19b). If one defines the corresponding skew-symmetric form

$$
\begin{equation*}
\mathcal{S}_{\pi}(U, V) \equiv \delta_{1} \omega_{A} \delta_{2} \omega^{A} \tag{5.1.38}
\end{equation*}
$$

the metric is given by

$$
\begin{equation*}
g(U, V) \equiv\left(\alpha^{A^{\prime}} \beta_{A^{\prime}}\right)\left(\alpha^{B^{\prime}} \pi_{B^{\prime}}\right)^{-1}\left(\beta^{C^{\prime}} \pi_{C^{\prime}}\right)^{-1} \mathcal{S}_{\pi}(U, V) \tag{5.1.39}
\end{equation*}
$$

However, in the light of (5.1.31), (5.1.35)-(5.1.37) one finds

$$
\begin{equation*}
g(U, V) \equiv g_{a b} U^{a} V^{b}=\Xi(x)\left(\lambda^{A} \chi_{A}\right)\left(\alpha^{A^{\prime}} \beta_{A^{\prime}}\right) \tag{5.1.40}
\end{equation*}
$$

By comparison with (5.1.39) this leads to

$$
\begin{equation*}
\mathcal{S}_{\pi}(U, V)=\Xi(x)\left(\lambda^{A} \chi_{A}\right)\left(\alpha^{B^{\prime}} \pi_{B^{\prime}}\right)\left(\beta^{C^{\prime}} \pi_{C^{\prime}}\right) \tag{5.1.41}
\end{equation*}
$$

If we now evaluate (5.1.41) with $\beta^{A^{\prime}}=\alpha^{A^{\prime}}$, comparison with the definition (5.1.38) and use of (5.1.12)-(5.1.13), (5.1.19b) and (5.1.36) yield

$$
\begin{equation*}
\Xi=\Lambda \tag{5.1.42}
\end{equation*}
$$

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The anti-self-dual solution of Einstein's equations is thus given by (5.1.30), (5.1.35) and (5.1.42).

The construction of an anti-self-dual space-time described in this section is a particular example of the so-called non-linear graviton (Penrose 1976a-b). In mathematical language, if $M$ is a complex three-manifold, $B$ is the bundle of holomorphic three-forms on $M$ and $H$ is the standard positive line bundle on $P_{1}$, a non-linear graviton is the following set of data (Hitchin 1979):
(i) $M$, the total space of a holomorphic fibration $\pi: M \rightarrow P_{1}$;
(ii) a four-parameter family of sections, each having $H \oplus H$ as normal bundle (see e.g. Huggett and Tod 1985 for the definition of normal bundle);
(iii) a non-vanishing holomorphic section $s$ of $B \otimes \pi^{*} H^{4}$, where $H^{4}=H \otimes$ $H \otimes H \otimes H$, and $\pi{ }^{*} H^{4}$ denotes the pull-back of $H^{4}$ by $\pi$;
(iv) a real structure on $M$ such that $\pi$ and $s$ are real. $M$ is then fibred from the real sections of the family.

### 5.2 Beyond Anti-Self-Duality

The limit of the analysis performed in section 5.1 is that it deals with a class of solutions of (complex) Einstein equations which is not sufficiently general. In Yasskin and Isenberg 1982 and Yasskin 1987 the authors have examined in detail the limits of the anti-self-dual analysis. The two main criticisms are as follows:
(a) a right-flat space-time (cf. Law 1985) does not represent a real Lorentzian space-time manifold. Hence it cannot be applied directly to classical gravity (Ward 1980b);
(b) there are reasons fo expecting that the equations of a quantum theory of gravity are much more complicated, and thus are not solved by right-flat spacetimes.

However, an alternative approach due to Le Brun has become available in recent years (Le Brun 1985). Le Brun's approach focuses on the space $G$ of complex null

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geodesics of complex space-time ( $M, \mathrm{~g}$ ), called ambitwistor space. Thus, one deals with a standard rank-2 holomorphic vector bundle $E \rightarrow G$, and in the conformal class determined by the complex structure of $G$, a one-to-one correspondence exists between non-vanishing holomorphic sections of $E$ and Einstein metrics on $(M, g)$ (Le Brun 1985). The bundle $E$ is called Einstein bundle, and has also been studied in Eastwood 1987. The work by Eastwood adds evidence in favour of the Einstein bundle being the correct generalization of the non-linear-graviton construction to the non-right-flat case (cf. Law 1985, Park 1990, Le Brun 1991, Park 1991, our section 9.6). Indeed, the theorems discussed so far provide a characterization of the vacuum Einstein equations. However, there is not yet an independent way of recognizing the Einstein bundle. Thus, this is not yet a substantial progress in solving the vacuum equations. Other relevant work on holomorphic ideas appears in Le Brun 1986, where the author proves that, in the case of four-manifolds with self-dual Weyl curvature, solutions of the Yang-Mills equations correspond to holomorphic bundles on an associated analytic space (cf. Ward 1977, Witten 1978, Ward 1981a).

### 5.3 Twistors as Spin $\frac{3}{2}$ Charges

In this section, we describe a recent proposal by Penrose to regard twistors for Ricci-flat space-times as (conserved) charges for massless helicity- $\frac{3}{2}$ fields (Penrose 1990, Penrose 1991a-b-c). The new approach proposed by Penrose is based on the following mathematical results (Penrose 1991b):
(i) A vanishing Ricci tensor provides the consistency condition for the existence and propagation of massless helicity- $\frac{3}{2}$ fields in curved space-time (Buchdahl 1958, Deser and Zumino 1976);
(ii) In Minkowski space-time, the space of charges for such fields is naturally identified with the corresponding twistor space.

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Thus, Penrose points out that if one could find the appropriate definition of charge for massless helicity $-\frac{3}{2}$ fields in a Ricci-flat space-time, this should provide the concept of twistor appropriate for vacuum Einstein equations. The corresponding geometrical program may be summarized as follows:
(1) Define a twistor for Ricci-flat space-time $(M, g)_{R F}$;
(2) Characterize the resulting twistor space $F$;
(3) Reconstruct $(M, g)_{R F}$ from $F$.

We now describe, following Penrose 1990, Penrose 1991a-b-c, properties and problems of this approach to twistor theory in flat and in curved space-times.

### 5.3.1 Massless $\operatorname{Spin} \frac{3}{2}$ Equations in Minkowski Space-Time

Let $(M, \eta)$ be Minkowski space-time with flat connection $D$. In $(M, \eta)$ the gauge-invariant field strength for spin $\frac{3}{2}$ is represented by a totally symmetric spinor field

$$
\begin{equation*}
\psi_{A^{\prime} B^{\prime} C^{\prime}}=\psi_{\left(A^{\prime} B^{\prime} C^{\prime}\right)}, \tag{5.3.1}
\end{equation*}
$$

obeying a massless free-field equation

$$
\begin{equation*}
\mathcal{D}^{A A^{\prime}} \psi_{A^{\prime} B^{\prime} C^{\prime}}=0 \tag{5.3.2}
\end{equation*}
$$

With the conventions of Penrose, $\psi_{A^{\prime} B^{\prime} C^{\prime}}$ describes spin- $\frac{3}{2}$ particles of helicity equal to $\frac{3}{2}$ (rather than $-\frac{3}{2}$ ). The Dirac form of this field strength is obtained by expressing locally $\psi_{A^{\prime} B^{\prime} C^{\prime}}$ in terms of two potentials subject to gauge freedoms involving a primed and an unprimed spinor field. The first potential is a spinor field symmetric in its primed indices

$$
\begin{equation*}
\gamma_{B^{\prime} C^{\prime}}^{A}=\gamma_{\left(B^{\prime} C^{\prime}\right)}^{A} \tag{5.3.3}
\end{equation*}
$$

subject to the differential equation

$$
\begin{equation*}
\mathcal{D}^{B B^{\prime}} \gamma_{B^{\prime} C^{\prime}}^{A}=0 \tag{5.3.4}
\end{equation*}
$$

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and such that

$$
\begin{equation*}
\psi_{A^{\prime} B^{\prime} C^{\prime}}=\mathcal{D}_{A A^{\prime}} \gamma_{B^{\prime} C^{\prime}}^{A} \tag{5.3.5}
\end{equation*}
$$

The second potential is a spinor field symmetric in its unprimed indices

$$
\begin{equation*}
\rho_{C^{\prime}}^{A B}=\rho_{C^{\prime}}^{(A B)} \tag{5.3.6}
\end{equation*}
$$

subject to the equation

$$
\begin{equation*}
\mathcal{D}^{C C^{\prime}} \rho_{C^{\prime}}^{A B}=0 \tag{5.3.7}
\end{equation*}
$$

and it yields the $\gamma_{B^{\prime} C^{\prime}}^{A}$ potential by means of

$$
\begin{equation*}
\gamma_{B^{\prime} C^{\prime}}^{A}=\mathcal{D}_{B B^{\prime}} \rho_{C^{\prime}}^{A B} \tag{5.3.8}
\end{equation*}
$$

If we introduce the spinor fields $v_{C^{\prime}}$ and $x^{B}$ obeying the equations

$$
\begin{gather*}
\mathcal{D}^{A C^{\prime}} \nu_{C^{\prime}}=0  \tag{5.3.9}\\
\mathcal{D}_{A C^{\prime}} \chi^{A}=2 i \nu_{C^{\prime}} \tag{5.3.10}
\end{gather*}
$$

the gauge freedoms for the two potentials enable one to replace them by the potentials

$$
\begin{gather*}
\hat{\gamma}_{B^{\prime} C^{\prime}}^{A} \equiv \gamma_{B^{\prime} C^{\prime}}^{A}+\mathcal{D}_{B^{\prime}}{ }^{A} \nu_{C^{\prime}}  \tag{5.3.11}\\
\hat{\rho}_{C^{\prime}}^{A B} \equiv \rho_{C^{\prime}}^{A B}+\epsilon^{A B} \nu_{C^{\prime}}+i \mathcal{D}_{C^{\prime}}{ }^{A} \chi^{B} \tag{5.3.12}
\end{gather*}
$$

without affecting the theory. Note that the right-hand side of (5.3.12) does not contain antisymmetric parts since, despite the explicit occurrence of the antisymmetric $\in^{A B}$, one finds

$$
\begin{equation*}
\mathcal{D}_{C^{\prime}}{ }^{[A} \chi^{B]}=\frac{\epsilon^{A B}}{2} \mathcal{D}_{L C^{\prime}} \chi^{L}=i \epsilon^{A B} \nu_{C^{\prime}} \tag{5.3.13}
\end{equation*}
$$

by virtue of (5.3.10). Hence (5.3.13) leads to

$$
\begin{equation*}
\hat{\rho}_{C^{\prime}}^{A B}=\rho_{C^{\prime}}^{A B}+i \mathcal{D}_{C^{\prime}}{ }^{(A} \chi^{B)} \tag{5.3.14}
\end{equation*}
$$

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The gauge freedoms are indeed given by Eqs. (5.3.11)-(5.3.12) since in our flat space-time one finds

$$
\begin{equation*}
\mathcal{D}^{A A^{\prime}} \widehat{\gamma}_{A^{\prime} B^{\prime}}^{G}=\mathcal{D}^{A A^{\prime}} \mathcal{D}_{B^{\prime}}^{C} \nu_{A^{\prime}}=\mathcal{D}_{B^{\prime}}^{C} \mathcal{D}^{A A^{\prime}} \nu_{A^{\prime}}=0, \tag{5.3.15}
\end{equation*}
$$

by virtue of (5.3.4) and (5.3.9), and

$$
\begin{align*}
\mathcal{D}^{A A^{\prime}} \hat{\rho}_{A^{\prime}}^{B C} & =\mathcal{D}^{A A^{\prime}} \mathcal{D}_{A^{\prime}}^{C} \chi^{B}=\mathcal{D}^{C A^{\prime}} \mathcal{D}_{A^{\prime}}{ }^{A} \chi^{B} \\
& =\mathcal{D}_{A^{\prime}} \boldsymbol{A}^{\prime} \mathcal{D}^{C A^{\prime}} \chi^{B}=-\mathcal{D}^{A A^{\prime}} \mathcal{D}_{A^{\prime}}^{C} \chi^{B}, \tag{5.3.16a}
\end{align*}
$$

which implies

$$
\begin{equation*}
\mathcal{D}^{A A^{\prime}} \hat{\rho}_{A^{\prime}}^{B C}=0 \tag{5.3.16b}
\end{equation*}
$$

The result (5.3.16b) is a particular case of the application of spinor Ricci identities to flat space-time (cf. sections 6.3 and 8.4).

We are now in a position to show that twistors can be regarded as charges for helicity- $\frac{3}{2}$ massless fields in Minkowski space-time. For this purpose, following Penrose 1991a,c let us suppose that the field $\psi$ satisfying (5.3.1)-(5.3.2) exists in a region $R$ of $(M, \eta)$, surrounding a world-tube which contains the sources for $\psi$. Moreover, we consider a two-sphere $S$ within $R$ surrounding the world-tube. To achieve this we begin by taking a dual twistor, i.e. the pair of spinor fields

$$
\begin{equation*}
W_{\alpha} \equiv\left(\lambda_{A}, \mu^{A^{\prime}}\right) \tag{5.3.17}
\end{equation*}
$$

obeying the differential equations

$$
\begin{gather*}
\mathcal{D}_{A A^{\prime}} \mu^{B^{\prime}}=i \epsilon_{A^{\prime}}^{\boldsymbol{B}^{\prime}} \lambda_{A}  \tag{5.3.18}\\
\mathcal{D}_{A A^{\prime}} \lambda_{B}=0 \tag{5.3.19}
\end{gather*}
$$

Hence $\mu^{B^{\prime}}$ is a solution of the complex-conjugate twistor equation

$$
\begin{equation*}
\mathcal{D}_{A}^{\left(A^{\prime}\right.} \mu^{\left.B^{\prime}\right)}=0 \tag{5.3.20}
\end{equation*}
$$

Thus, defining

$$
\begin{equation*}
\varphi_{A^{\prime} B^{\prime}} \equiv \psi_{A^{\prime} B^{\prime} C^{\prime}} \mu^{C^{\prime}} \tag{5.3.21}
\end{equation*}
$$

## 5. Penrose Transform for Gravitation

one finds, by virtue of (5.3.1)-(5.3.2) and (5.3.20), that $\varphi_{A^{\prime} B^{\prime}}$ is a solution of the self-dual vacuum Maxwell equations

$$
\begin{equation*}
\mathcal{D}^{A A^{\prime}} \varphi_{A^{\prime} B^{\prime}}=0 \tag{5.3.22}
\end{equation*}
$$

Note that (5.3.21) is a particular case of the spin-lowering procedure (Huggett and Tod 1985, Penrose and Rindler 1986). Moreover, $\varphi_{A^{\prime} B^{\prime}}$ enables one to define the self-dual two-form

$$
\begin{equation*}
F \equiv \varphi_{A^{\prime} B^{\prime}} d x_{A}^{A^{\prime}} \wedge d x^{A B^{\prime}} \tag{5.3.23}
\end{equation*}
$$

which leads to the following charge assigned to the world-tube:

$$
\begin{equation*}
Q \equiv \frac{i}{4 \pi} \oint F . \tag{5.3.24}
\end{equation*}
$$

For some twistor

$$
\begin{equation*}
Z^{\alpha} \equiv\left(\omega^{A}, \pi_{A^{\prime}}\right) \tag{5.3.25}
\end{equation*}
$$

the charge $Q$ depends on the dual twistor $W_{\alpha}$ as (see problem 5.3)

$$
\begin{equation*}
Q=Z^{\alpha} W_{\alpha}=\omega^{A} \lambda_{A}+\pi_{A^{\prime}} \mu^{A^{\prime}} \tag{5.3.26}
\end{equation*}
$$

These equations describe the strength of the charge, for the field $\psi$, that should be assigned to the world-tube. Thus, a twistor $Z^{\alpha}$ arises naturally in Minkowski space-time as the charge for a helicity $+\frac{3}{2}$ massless field, whereas a dual twistor $W_{\alpha}$ is the charge for a helicity $-\frac{3}{2}$ massless field (Penrose 1991c).

Interestingly, the potentials $\gamma_{A}^{C} B^{\prime}$ and $\rho_{A^{\prime}}^{B C}$ can be used to obtain a potential for the self-dual Maxwell field strength, since, after defining

$$
\begin{equation*}
\theta_{A^{\prime}}^{C} \equiv \gamma_{A^{\prime} B^{\prime}}^{C} \mu^{B^{\prime}}-i \rho_{A^{\prime}}^{B C} \lambda_{B} \tag{5.3.27}
\end{equation*}
$$

one finds

$$
\begin{align*}
& \mathcal{D}_{C B^{\prime}} \theta_{A A^{\prime}}^{C}=\left(\mathcal{D}_{C B^{\prime}} \gamma_{A^{\prime} D^{\prime}}^{C}\right) \mu^{D^{\prime}}+\gamma_{A^{\prime} D^{\prime}}^{C}\left(\mathcal{D}_{C B^{\prime}} \mu^{D^{\prime}}\right)-i\left(\mathcal{D}_{C B^{\prime}} \rho_{A^{\prime}}^{B C}\right) \lambda_{B} \\
&=\psi_{A^{\prime} B^{\prime} D^{\prime} \mu^{D^{\prime}}+i \epsilon_{B^{\prime}} D^{\prime} \gamma_{A^{\prime} D^{\prime}}^{C} \lambda_{C}-i \gamma_{A^{\prime} B^{\prime}}^{C} \lambda_{C}} \\
&=\psi_{A^{\prime} B^{\prime} D^{\prime}} \mu^{D^{\prime}}=\varphi_{A^{\prime} B^{\prime}} \tag{5.3.28}
\end{align*}
$$

## 5. Penrose Transform for Gravitation

$$
\begin{align*}
\mathcal{D}_{B}^{A^{\prime}} \theta_{A^{\prime}}^{C} & =\left(\mathcal{D}_{B}^{A^{\prime}} \gamma_{A^{\prime} B^{\prime}}^{C}\right) \mu^{B^{\prime}}+\gamma_{A^{\prime} B^{\prime}}^{C}\left(\mathcal{D}_{B}^{A^{\prime}} \mu^{B^{\prime}}\right)-i\left(\mathcal{D}_{B}^{A^{\prime}} \rho_{A^{\prime}}^{D C}\right) \lambda_{D} \\
& -i \rho_{A^{\prime}}^{D C}\left(\mathcal{D}_{B}^{A^{\prime}} \lambda_{D}\right)=0 \tag{5.3.29}
\end{align*}
$$

Eq. (5.3.28) has been obtained by using (5.3.5), (5.3.8) and (5.3.18)-(5.3.19), whereas (5.3.29) holds by virtue of (5.3.3)-(5.3.4), (5.3.7), (5.3.18)-(5.3.19). The one-form corresponding to $\theta_{A^{\prime}}^{C}$ is defined by

$$
\begin{equation*}
A \equiv \theta_{B B^{\prime}} d x^{B B^{\prime}} \tag{5.3.30}
\end{equation*}
$$

which leads to

$$
\begin{equation*}
F=2 d A, \tag{5.3.31}
\end{equation*}
$$

by using (5.3.23) and (5.3.28).
The Rarita-Schwinger form of the field strength does not require the symmetry (5.3.3) in $B^{\prime} C^{\prime}$ as we have done so far, and the $\gamma_{B^{\prime} C^{\prime}}^{A}$ potential is instead subject to the equations (Penrose 1991a-b-c) [cf. (8.6.3)-(8.6.4)]

$$
\begin{gather*}
\epsilon^{B^{\prime} C^{\prime}} \mathcal{D}_{A\left(A^{\prime}\right.} \gamma_{\left.B^{\prime}\right) C^{\prime}}^{A}=0,  \tag{5.3.32}\\
\mathcal{D}^{B^{\prime}(B} \gamma_{B^{\prime} C^{\prime}}^{A)}=0 \tag{5.3.33}
\end{gather*}
$$

Moreover, the spinor field $v_{C^{\prime}}$ in (5.3.11) is no longer taken to be a solution of the Weyl equation (5.3.9).

The potentials $\gamma$ and $\rho$ may or may not be global over $S$. If $\gamma$ is global but $\rho$ is not, one obtains a two-dimensional complex vector space parametrized by the spinor field $\pi_{A^{\prime}}$. The corresponding subspace where $\pi_{A^{\prime}}=0$, parametrized by $\omega^{A}$, is called $\omega$-space. Thus, following Penrose 1991c, we regard $\pi$-space and $\omega$-space as quotient spaces defined as follows:

$$
\begin{align*}
& \pi-\text { space } \equiv \text { space of global } \psi^{\prime} \text { s/space of global } \gamma^{\prime} \text { s }  \tag{5.3.34}\\
& \omega \text { - space } \equiv \text { space of global } \gamma^{\prime} \text { s/space of global } \rho^{\prime} \text { s } \tag{5.3.35}
\end{align*}
$$

## 5. Penrose Transform for Gravitation

### 5.3.2 Massless Spin $\frac{3}{2}$ Field Strengths in Curved Space-Time

The conditions for the local existence of the $\rho_{A}^{B} C^{C}$ potential in curved spacetime are derived by requiring that, after the gauge transformation (5.3.12) (or, equivalently, (5.3.14)), also the $\widehat{\boldsymbol{\rho}}_{\boldsymbol{A}^{\prime}}^{\boldsymbol{B} \boldsymbol{C}}$ potential should obey the equation

$$
\begin{equation*}
\nabla^{A A^{\prime}} \hat{\rho}_{A^{\prime}}^{B C}=0 \tag{5.3.36}
\end{equation*}
$$

where $\nabla$ is the curved connection. By virtue of the spinor Ricci identity (Ward and Wells 1990)

$$
\begin{equation*}
\nabla_{M^{\prime}(A} \nabla_{B)}^{M_{B}^{\prime}} \chi_{C}=\psi_{A B D C} \chi^{D}-2 \Lambda \chi_{(A} \epsilon_{B) C} \tag{5.3.37}
\end{equation*}
$$

the insertion of (5.3.14) into (5.3.36) yields, assuming for simplicity that $v_{C^{\prime}}=0$ in (5.3.10), the following conditions (see (8.4.28)):

$$
\begin{equation*}
\psi_{A B C D}=0 \quad, \quad \Lambda=0 \tag{5.3.38}
\end{equation*}
$$

which imply we deal with a vacuum self-dual (or left-flat) space-time, since the anti-self-dual Weyl spinor has to vanish (Penrose 1991c).

Moreover, in a complex anti-self-dual vacuum space-time one finds (Penrose 1991c) that spin- $\frac{3}{2}$ field strengths $\psi_{A^{\prime} B^{\prime} C^{\prime}}$ can be defined according to (cf. (5.3.5))

$$
\begin{equation*}
\psi_{A^{\prime} B^{\prime} C^{\prime}}=\nabla_{C C^{\prime}} \gamma_{A^{\prime} B^{\prime}}^{C} \tag{5.3.39}
\end{equation*}
$$

are gauge-invariant, totally symmetric, and satisfy the massless free-field equations (cf. (5.3.2))

$$
\begin{equation*}
\nabla^{A A^{\prime}} \psi_{A^{\prime} B^{\prime} C^{\prime}}=0 \tag{5.3.40}
\end{equation*}
$$

In this case there is no obstruction to defining global $\psi$-fields with non-vanishing $\pi$-charge, and a global $\pi$-space can be defined as in (5.3.34). It remains to be seen whether the twistor space defined by $\alpha$-surfaces may then be reconstructed (section 4.2, Penrose 1976a-b, Ward and Wells 1990, Penrose 1991c).

## 5. Penrose Transform for Gravitation

Interestingly, in Penrose 1991b it has been proposed to interpret the primary potential $\gamma$ as providing a bundle connection. In other words, one takes the fibre coordinates to be given by a spinor $\eta_{A^{\prime}}$ and a scalar $\mu$. For a given small $\varepsilon$, one extends the ordinary Levi-Civita connection $\nabla$ on $M$ to bundle-valued quantities according to (Penrose 1991b)

$$
\nabla_{P P^{\prime}}\binom{\eta_{A^{\prime}}}{\mu} \equiv\binom{\nabla_{P P^{\prime}} \eta_{A^{\prime}}}{\nabla_{P P^{\prime}} \mu}-\epsilon\left(\begin{array}{cc}
0 & \gamma_{P P^{\prime} A^{\prime}}  \tag{5.3.41}\\
\gamma_{P P^{\prime}} & 0
\end{array}\right)\binom{\eta_{B^{\prime}}}{\mu}
$$

with gauge transformations given by

$$
\binom{\widehat{\eta}_{A^{\prime}}}{\widehat{\mu}} \equiv\binom{\eta_{A^{\prime}}}{\mu}+\epsilon\left(\begin{array}{cc}
0 & \nu_{A^{\prime}}  \tag{5.3.42}\\
\nu^{B^{\prime}} & 0
\end{array}\right)\binom{\eta_{B^{\prime}}}{\mu}
$$

Note that terms of order $\varepsilon^{2}$ have been neglected in writing (5.3.42). However, such gauge transformations do not close under commutation, and to obtain a theory valid to all orders in $\varepsilon$ one has to generalize to $S L(3, C)$ matrices before the commutators close. Writing $(A)$ for the three-dimensional indices, so that $\eta_{(A)}$ denotes $\binom{\eta_{\boldsymbol{A}^{\prime}}}{\mu}$, one has a connection defined by

$$
\begin{equation*}
\nabla_{P P^{\prime}} \eta_{(A)} \equiv\binom{\nabla_{P P^{\prime}} \eta_{A^{\prime}}}{\nabla_{P P^{\prime}} \mu}-\gamma_{P P^{\prime}(A)}{ }^{(B)} \eta_{(B)} \tag{5.3.43}
\end{equation*}
$$

with gauge transformation

$$
\begin{equation*}
\widehat{\eta}_{(A)} \equiv \eta_{(A)}+\nu_{(A)}^{(B)} \eta_{(B)} \tag{5.3.44}
\end{equation*}
$$

With this notation, the $v_{(A)}{ }^{(B)}$ are $S L(3, C)$-valued fields on $M$, and hence

$$
\begin{equation*}
\mathcal{E}^{(P)(Q)(R)} \nu_{(P)}^{(A)} \nu_{(Q)}^{(B)} \nu_{(R)}^{(C)}=\mathcal{E}^{(A)(B)(C)} \tag{5.3.45}
\end{equation*}
$$

where $\varepsilon^{(P)(Q)(R)}$ are generalized Levi-Civita symbols. The $S L(3, C)$ definition of the primary potentials takes the form (Penrose 1991b)

$$
\gamma_{P P^{\prime}(A)}^{(B)} \equiv\left(\begin{array}{cc}
\alpha_{P P^{\prime}}{ }^{\prime} A^{\prime} & \beta_{P P^{\prime} A^{\prime}}  \tag{5.3.46}\\
\gamma_{P P^{\prime}} & \delta_{P P^{\prime}}
\end{array}\right)
$$

## 5. Penrose Transform for Gravitation

while the curvature is

$$
\begin{equation*}
K_{p q(A)}{ }^{(B)} \equiv 2 \nabla_{[p} \gamma_{q](A)}{ }^{(B)}+2 \gamma_{[p|(A)|}{ }^{(C)} \gamma_{q](C)}{ }^{(B)} . \tag{5.3.47}
\end{equation*}
$$

Penrose has proposed this as a generalizarion of the Rarita-Schwinger structure in Ricci-flat space-times, and he has even speculated that a non-linear generalization of the Rarita-Schwinger equations (5.3.32)-(5.3.33) might be

$$
\begin{gather*}
{ }^{(-)} K_{P Q(A)}^{(B)}=0,  \tag{5.3.48}\\
{ }^{(+)} K_{P^{\prime} Q^{\prime}(A)}{ }^{(B)} \mathcal{E}^{P^{\prime}(A)(C)} \mathcal{E}^{Q^{\prime}}{ }_{(B)(D)}=0, \tag{5.3.49}
\end{gather*}
$$

where ${ }^{(-)} K$ and ${ }^{(+)} K$ are the anti-self-dual and self-dual parts of the curvature respectively, i.e.

$$
\begin{equation*}
K_{p q(A)}{ }^{(B)}=\epsilon_{P^{\prime} Q^{\prime}}{ }^{(-)} K_{P Q(A)}{ }^{(B)}+\epsilon_{P Q}{ }^{(+)} K_{P^{\prime} Q^{\prime}(A)}{ }^{(B)} . \tag{5.3.50}
\end{equation*}
$$

Following Penrose 1991b, one has

$$
\begin{align*}
& \mathcal{E}^{P^{\prime}(A)(C)} \equiv \mathcal{E}^{(P)(A)(C)} e_{(P)}{ }^{P^{\prime}},  \tag{5.3.51}\\
& \mathcal{E}_{Q^{\prime}(B)(D)} \equiv \mathcal{E}_{(Q)(B)(D)} e_{Q^{\prime}}{ }^{(Q)} \tag{5.3.52}
\end{align*}
$$

the $e_{(P)}{ }^{P^{\prime}}$ and $e_{Q^{\prime}}{ }^{(Q)}$ relating the bundle directions with tangent directions in $M$.

PART III:

TORSION AND SUPERSYMMETRY

## COMPLEX SPACE-TIMES WITH TORSION


#### Abstract

Theories of gravity with torsion are relevant since torsion is a naturally occurring geometric property of relativistic theories of gravitation, the gauge theory of the Poincaré group leads to its presence, the constraints are second-class and the occurrence of cosmological singularities can be less generic than in general relativity. In a space-time manifold with non-vanishing torsion, the Riemann tensor has 36 independent real components at each point, rather than 20 as in general relativity. The information of these 36 components is encoded in three spinor fields and in a scalar function, having $5,9,3$ and 1 complex components respectively. If space-time is complex, this means that, with respect to a holomorphic coordinate basis $x^{a}$, the metric is a $4 \times 4$ matrix of holomorphic functions of $x^{a}$, and its determinant is nowhere-vanishing. Hence the connection and Riemann are holomorphic as well, and the Ricci tensor becomes complex-valued.


After a two-component spinor analysis of the curvature and of spinor Ricci identities, the necessary condition for the existence of $\alpha$-surfaces in complex spacetime manifolds with non-vanishing torsion is derived. For these manifolds, Lie brackets of vector fields and spinor Ricci identities contain explicitly the effects of torsion. This leads to an integrability condition for $\alpha$-surfaces which does not involve just the self-dual Weyl spinor, as in complex general relativity, but also the torsion spinor, in a non-linear way, and its covariant derivative. A similar result also holds for four-dimensional, smooth real manifolds with a positive-definite metric. Interestingly, a particular solution of the integrability condition is given by right conformally flat and right-torsion-free space-times.

## 6. Complex Space-Times with Torsion

### 6.1 Introduction

As we know from Part I, over the past 27 years, several efforts have been produced to understand many properties of classical and quantum field theories using twistor theory. Penrose's original idea was that the space-time picture might be inappropriate at the Planck length, whereas a more correct framework for fundamental physics should be a particular complex manifold called twistor space. In other words, concepts such as null lines and null surfaces are more fundamental than space-time concepts, and twistor space provides the precise mathematical description of this idea.

In the course of studying Minkowski space-time, twistors can be defined either via the four-complex-dimensional vector space of solutions to the differential equation (cf. (4.1.5))

$$
\begin{equation*}
\mathcal{D}_{A^{\prime}}{ }^{(A} \omega^{B)}=0 \tag{6.1.1}
\end{equation*}
$$

or via null two-surfaces in complexified compactified Minkowski space CM\#, called a-planes. The $\alpha$-planes (section 4.1) are such that the space-time metric vanishes over them, and their null tangent vectors have the two-component spinor form $\lambda^{A} \pi^{A^{\prime}}$, where $\lambda^{A}$ is varying and $\pi^{A^{\prime}}$ is fixed (i.e. fixed by a well-known differential equation). The latter definition can be generalized to complex or real Riemannian space-times provided the Weyl curvature is anti-self-dual. This leads in turn to a powerful geometric picture, where the study of the Euclidean-time version of the partial differential equations of Einstein's theory is replaced by the problem of finding the holomorphic curves in a complex manifold called deformed (projective) twistor space. This finally enables one to reconstruct the space-time metric (chapter five). From the point of view of gravitational physics, this is the most relevant application of Penrose-transform theory, which is by now a major tool for studying the differential equations of classical field theory (Ward and Wells 1990).

Note that, while in differential geometry the basic ideas of connection and curvature are local, in complex-analytic geometry there is no local information.

## 6. Complex Space-Times with Torsion

Any complex manifold looks locally like $C^{n}$, with no special features, and any holomorphic fibre bundle is locally an analytic product (cf. Atiyah 1988 on page 524 for a more detailed treatment of this non-trivial point). It is worth bearing in mind this difference since the Penrose transform converts problems from differential geometry into problems of complex-analytic geometry. We thus deal with a non-local transform, so that local curvature information is coded into global holomorphic information. More precisely, Penrose theory does not hold for both anti-self-dual and self-dual space-times, so that one only obtains a non-local treatment of complex space-times with anti-self-dual Weyl curvature. However, these investigations are incomplete for at least two reasons:
(a) anti-self-dual (or self-dual) space-times appear a very restricted (although quite important) class of models, and it is not clear how to generalize twistor-space definitions to general vacuum space-times;
(b) the fundamental theory of gravity at the Planck length is presumably different from Einstein's general relativity (Hawking 1979, Esposito 1994).

In this chapter we have thus tried to extend the original analysis appearing in the literature to a larger class of theories of gravity, i.e. space-time models $(M, g)$ with torsion (we are, however, not concerned with supersymmetry). In our opinion, the main motivations for studying these space-time models are as follows.
(1) Torsion is a peculiarity of relativistic theories of gravitation, since the bundle $L(M)$ of linear frames is soldered to the base $B=M$, whereas for gauge theories other than gravitation the bundle $L(M)$ is loosely connected to $M$. The torsion two-form $T$ is then defined as $T \equiv \mathrm{~d} \theta+\omega \Lambda \theta$, where $\theta$ is the soldering form and $\omega$ is a connection one-form on $L(M)$. If $L(M)$ is reduced to the bundle $O(M)$ of orthonormal frames, $\omega$ is called spin-connection.
(2) The gauge theory of the Poincare group naturally leads to theories with torsion.
(3) From the point of view of constrained Hamiltonian systems, theories with torsion are of great interest, since they are theories of gravity with second-class constraints (cf. Esposito 1994 and references therein).

## 6. Complex Space-Times with Torsion

(4) In space-time models with torsion, the occurrence of cosmological singularities can be less generic than in general relativity (Esposito 1992, Esposito 1994).

In the original work by Penrose and Ward, the first (simple) problem is to characterize curved space-time models possessing a-surfaces. As we were saying following Eq. (5.1.1), the necessary and sufficient condition is that space-time be complex, or real Riemannian (i.e. its metric is positive-definite), with anti-self-dual Weyl curvature. This is proved by using Frobenius' theorem, the spinor form of the Riemann curvature tensor, and spinor Ricci identities. Our chapter is thus organized as follows.

Section 6.2 describes Frobenius' theorem and its application to curved complex space-time models with non-vanishing torsion. In particular, if a-surfaces are required to exist, one finds this is equivalent to a differential equation involving two spinor fields $\xi_{A}$ and $\omega_{A B^{\prime}}$, which are completely determined by certain algebraic relations: Section 6.3 describes the spinor form of Riemann and spinor Ricci identities for theories with torsion. Section 6.4 applies the formulae of section 6.3 to obtain the integrability condition for the differential equation derived at the end of section 6.2. The integrability condition for $\alpha$-surfaces is then shown to involve the self-dual Weyl spinor, the torsion spinor and covariant derivatives of torsion. Concluding remarks are presented in section 6.5.

### 6.2 Frobenius' Theorem for Theories with Torsion

Frobenius' theorem is one of the main tools for studying calculus on manifolds. Following Abraham et al. 1983, the geometrical framework and the theorem can be described as follows. Given a manifold $M$, let $E \subset T M$ be a sub-bundle of its tangent bundle. By definition, $E$ is involutive if for any two $E$-valued vector fields $X$ and $Y$ defined on $M$, their Lie bracket is $E$-valued as well. Moreover, $E$ is integrable if $\forall m_{0} \in M$ there is a local submanifold $N \subset M$ through $m_{0}$,

## 6. Complex Space-Times with Torsion

called a local integral manifold of $E$ at $m_{0}$, whose tangent bundle coincides with $E$ restricted to $N$. Frobenius' theorem ensures that a sub-bundle $E$ of $T M$ is involutive if and only if it is integrable.

Given a complex torsion-free space-time $(M, g)$, it is possible to pick out in $M$ a family of holomorphic two-surfaces, called $\alpha$-surfaces, which generalize the $\alpha$-planes of Minkowski space-time described in section 4.1, provided the self-dual Weyl spinor vanishes. In the course of deriving the condition on the curvature enforced by the existence of $\alpha$-surfaces, one begins by taking a totally null twosurface $\hat{\boldsymbol{S}}$ in $M$. By definition, $\hat{\boldsymbol{S}}$ is a two-dimensional complex submanifold of $M$ such that, $\forall p \in \hat{\boldsymbol{S}}_{\text {, }}$, if $x$ and $y$ are any two tangent vectors at $p$, then $g(x, x)=$ $g(y, y)=g(x, y)=0$. Denoting by $X=X^{a} e_{a}$ and $Y=Y^{a} e_{a}$ two vector fields tangent to $\hat{S}$, where $X^{a}$ and $Y^{a}$ have the two-component spinor form $X^{a}=\lambda^{A} \pi^{A^{\prime}}$ and $Y^{a}=\mu^{A} \pi^{A^{\prime}}$, Frobenius' theorem may be used to require that the Lie bracket of $X$ and $Y$ be a linear combination of $X$ and $Y$, so that we write

$$
\begin{equation*}
[X, Y]=\varphi X+\rho Y \tag{6.2.1}
\end{equation*}
$$

where $\varphi$ and $\rho$ are scalar functions. Frobenius' theorem is indeed originally formulated for real manifolds. If the integral submanifolds of complex space-time are holomorphic, there are additional conditions which are not described here. Note also that Eq. (6.2.1) does not depend on additional structures on $M$ (torsion, metric, etc. ...). In the torsion-free case, it turns out that the Lie bracket $[X, Y$ ] can also be written as $\nabla_{X} Y-\nabla_{Y} X$, and this finally leads to a condition which implies the vanishing of the self-dual part of the Weyl curvature, after using the spinorial formula for Riemann and spinor Ricci identities.

However, for the reasons described in section 6.1, we are here interested in models where torsion does not vanish. Even though Frobenius' theorem (cf. (6.2.1)) does not involve torsion, the Lie bracket [ $X, Y$ ] can be also expressed using the definition of the torsion tensor $S$ (see comment following (6.3.3)) :

$$
\begin{equation*}
[X, Y] \equiv \nabla_{X} Y-\nabla_{Y} X-2 S(X, Y) \tag{6.2.2}
\end{equation*}
$$

## 6. Complex Space - Times with Torsion

By comparison, Eqs. (6.2.1)-(6.2.2) lead to

$$
\begin{equation*}
X^{a} \nabla_{a} Y^{b}-Y^{a} \nabla_{a} X^{b}=\varphi X^{b}+\rho Y^{b}+2 S_{c d}^{b} X^{c} Y^{d} \tag{6.2.3}
\end{equation*}
$$

Now, the antisymmetry $S_{a b}{ }^{c}=-S_{b a}{ }^{c}$ of the torsion tensor can be expressed spinorially as

$$
\begin{equation*}
S_{a b}^{c}=\chi_{A B}{ }^{C C^{\prime}} \epsilon_{A^{\prime} B^{\prime}}+\tilde{\chi}_{A^{\prime} B^{\prime}} C^{\prime C^{\prime}} \epsilon_{A B} \tag{6.2.4}
\end{equation*}
$$

where the spinors $x$ and $\tilde{\chi}$ are symmetric in $A B$ and $A^{\prime} B^{\prime}$ respectively, and from now on we use two-component spinor notation (we do not write Infeld-van der Waerden symbols for simplicity of notation). Thus, writing $X^{a}=\lambda^{A} \pi^{A^{\prime}}$ and $Y^{a}=\mu^{A} \pi^{A^{\prime}}$, one finds, using a technique similar to the one in section 9.1 of Ward and Wells 1990, that (6.2.3) is equivalent to

$$
\begin{equation*}
\pi^{A^{\prime}}\left(\nabla_{A A^{\prime}} \pi_{B^{\prime}}\right)=\xi_{A} \pi_{B^{\prime}}+w_{A B^{\prime}} \tag{6.2.5}
\end{equation*}
$$

for some spinor fields $\xi_{A}$ and $\omega_{A B^{\prime}}$, provided the following conditions are imposed:

$$
\begin{gather*}
-\mu^{A} \xi_{A}=\varphi  \tag{6.2.6}\\
\lambda^{A} \xi_{A}=\rho  \tag{6.2.7}\\
\mu_{D} \lambda^{D} w_{B B^{\prime}}=-2 \mu_{D} \lambda^{D} \tilde{\chi}_{C^{\prime} D^{\prime} B B^{\prime}} \pi^{C^{\prime}} \pi^{D^{\prime}} \tag{6.2.8}
\end{gather*}
$$

Note that, since our calculation involves two vector fields $X$ and $Y$ tangent to $\hat{\boldsymbol{S}}$, its validity is only local unless the surface $\hat{\boldsymbol{S}}$ is parallelizable (i.e. the bundle $L(\hat{\boldsymbol{S}})$ admits a cross-section). Moreover, since $\hat{\boldsymbol{S}}$ is holomorphic by hypothesis, this implies also $\varphi$ and $\rho$ are holomorphic (cf. (6.2.1)), and this affects the unprimed spinor part of the null tangent vectors to $\alpha$-surfaces in the light of (6.2.6)-(6.2.7). By virtue of Eq. (6.2.8), one finds

$$
\begin{equation*}
w_{A B^{\prime}}=-2 \pi^{A^{\prime}} \pi^{C^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A C^{\prime}} \tag{6.2.9}
\end{equation*}
$$

which implies (Esposito 1993)

$$
\begin{equation*}
\pi^{A^{\prime}}\left(\nabla_{A A^{\prime}} \pi_{B^{\prime}}\right)=\xi_{A} \pi_{B^{\prime}}-2 \pi^{A^{\prime}} \pi^{C^{\prime}} \widetilde{\chi}_{A^{\prime} B^{\prime} A C^{\prime}} \tag{6.2.10}
\end{equation*}
$$

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Note that, if torsion is set to zero, Eq. (6.2.10) agrees with Eq. (9.1.2) appearing in section 9.1 of Ward and Wells 1990, where complex general relativity is studied. This is the desired necessary condition for the field $\pi_{A^{\prime}}$ to define an $\alpha$-surface in the presence of torsion (and it may be also shown to be sufficient, as in section 4.2). Our next task is to derive the integrability condition for Eq. (6.2.10). For this purpose, following Ward and Wells 1990, we operate with $\pi^{B^{\prime}} \pi^{C^{\prime}} \nabla^{A} C^{\prime}$ on both sides of (6.2.10). This leads to

$$
\begin{equation*}
\pi^{B^{\prime}} \pi^{C^{\prime}} \nabla_{C^{\prime}}^{A}\left[\pi^{A^{\prime}}\left(\nabla_{A A^{\prime}} \pi_{B^{\prime}}\right)\right]=\pi^{B^{\prime}} \pi^{C^{\prime}} \nabla_{C^{\prime}}^{A}\left[\xi_{A} \pi_{B^{\prime}}-2 \pi^{A^{\prime}} \pi^{D^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A D^{\prime}}\right] \tag{6.2.11}
\end{equation*}
$$

Using the Leibniz rule, (6.2.10) and the well-known property $\pi_{A} \pi^{A^{\prime}}=\xi_{A} \xi^{A}=0$, the two terms on the right-hand side of (6.2.11) are found to be

$$
\begin{align*}
& \quad \pi^{B^{\prime}} \pi^{C^{\prime}}\left[\nabla_{C^{\prime}}^{A}\left(\xi_{A} \pi_{B^{\prime}}\right)\right]=2 \xi^{A} \pi^{A^{\prime}} \pi^{B^{\prime}} \pi^{C^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A C^{\prime}}  \tag{6.2.12}\\
& \pi^{B^{\prime}} \pi^{C^{\prime}}\left[\nabla_{C^{\prime}}\left(-2 \pi^{A^{\prime}} \pi^{D^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A D^{\prime}}\right)\right]=-4 \xi^{A} \pi^{A^{\prime}} \pi^{B^{\prime}} \pi^{D^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A D^{\prime}} \\
& +8 \pi^{B^{\prime}} \pi_{F^{\prime}} \pi_{G^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A D^{\prime}} \pi^{\left(A^{\prime}\right.} \tilde{\chi}^{\left.F^{\prime} D^{\prime}\right) A G^{\prime}} \\
& -2 \pi^{A^{\prime}} \pi^{B^{\prime}} \pi^{C^{\prime}} \pi^{D^{\prime}}\left(\nabla_{C^{\prime}}^{A} \tilde{\chi}_{A^{\prime} B^{\prime} A D^{\prime}}\right) \tag{6.2.13}
\end{align*}
$$

where round brackets denote symmetrization over $A^{\prime}$ and $D^{\prime}$ on the second line of (6.2.13).

It now remains to compute the left-hand side of (6.2.11). This is given by

$$
\begin{align*}
\pi^{B^{\prime}} \pi^{C^{\prime}} \nabla_{C^{\prime}}^{A}\left[\pi^{A^{\prime}}\left(\nabla_{A A^{\prime}} \pi_{B^{\prime}}\right)\right] & =\pi^{B^{\prime}} \pi^{C^{\prime}}\left(\nabla_{C^{\prime}} \pi^{A^{\prime}}\right)\left(\nabla_{A A^{\prime}} \pi_{B^{\prime}}\right) \\
& -\pi^{A^{\prime}} \pi^{B^{\prime}} \pi^{C^{\prime}}\left(\square_{C^{\prime} A^{\prime}} \pi_{B^{\prime}}\right) \tag{6.2.14}
\end{align*}
$$

where we have defined $\square \boldsymbol{C}^{\prime} \boldsymbol{A}^{\prime} \equiv \nabla_{\boldsymbol{A}\left(\boldsymbol{C}^{\prime}\right.} \nabla_{\left.\boldsymbol{A}^{\prime}\right)}$ as in section 8.4. Using (6.2.10), the first term on the right-hand side of (6.2.14) is easily found to be

$$
\begin{align*}
\pi^{B^{\prime}} \pi^{C^{\prime}}\left(\nabla_{C^{\prime}} \pi^{A^{\prime}}\right)\left(\nabla_{A A^{\prime}} \pi_{B^{\prime}}\right) & =4 \pi^{B^{\prime}} \pi^{C^{\prime}} \pi_{F^{\prime}} \pi_{G^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A C^{\prime}} \tilde{\chi}^{F^{\prime} A^{\prime} A G^{\prime}} \\
& -2 \xi^{A} \pi^{A^{\prime}} \pi^{B^{\prime}} \pi^{C^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A C^{\prime}} \tag{6.2.15}
\end{align*}
$$

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The second term on the right-hand side of (6.2.14) can only be computed after using some fundamental identities of spinor calculus for theories with torsion, hereafter referred to as $U_{4}$-theories, as in Esposito 1992, Esposito 1994.

### 6.3 Spinor Ricci Identities for Complex $\boldsymbol{U}_{4}$ Theory

Since the results we here describe play a key role in obtaining the integrability condition for $\alpha$-surfaces (cf. section 6.4), we have chosen to summarize the main formulae in this separate section, following Penrose 1983, Penrose and Rindler 1984.

Using abstract-index notation, the symmetric Lorentzian metric $g$ of real Lorentzian $U_{4}$ space-times is still expressed by

$$
\begin{equation*}
g_{a b}=\epsilon_{A B} \epsilon_{A^{\prime} B^{\prime}} . \tag{6.3.1}
\end{equation*}
$$

Moreover, the full connection still obeys the metricity condition $\nabla g=0$, and the corresponding spinor covariant derivative is assumed to satisfy the additional relations

$$
\begin{equation*}
\nabla_{A A^{\prime}} \epsilon_{B C}=0 \quad, \quad \nabla_{A A^{\prime}} \epsilon_{B^{\prime} C^{\prime}}=\mathbf{0} \tag{6.3.2}
\end{equation*}
$$

and is a linear, real operator which satisfies the Leibniz rule. However, since torsion does not vanish, the difference $\left(\nabla_{a} \nabla_{b}-\nabla_{b} \nabla_{a}\right)$ applied to a function $f$ is equal to $2 S_{a}{ }^{c}{ }^{c} \nabla_{c} f \neq 0$. Torsion also appears explicitly in the relation defining the Riemann tensor

$$
\begin{equation*}
\left(\nabla_{a} \nabla_{b}-\nabla_{b} \nabla_{a}-2 S_{a b}^{c} \nabla_{c}\right) V^{d} \equiv R_{a b c}^{d} V^{c} \tag{6.3.3}
\end{equation*}
$$

and leads to a non-symmetric Ricci tensor $R_{a b} \neq R_{b a}$, where $R_{a b} \equiv R_{a c b}{ }^{c}$. Note that in (6.3.3) the factor 2 multiplies $S_{a}{ }_{b}^{c}$ since we are using definition (6.2.2), whereas in Penrose and Rindler 1984 a definition is used where the torsion tensor is $T \equiv 2 S$. The tensor $R_{a b c d}$ has now 36 independent real components at each point,

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rather than 20 as in general relativity. The information of these 36 components is encoded in the spinor fields

$$
\psi_{A B C D}, \Phi_{A B C^{\prime} D^{\prime}}, \Sigma_{A B}
$$

and in the scalar function $\boldsymbol{\Lambda}$, having 5,9,3, and 1 complex components respectively, and such that

$$
\begin{gather*}
\psi_{A B C D}=\psi_{(A B C D)},  \tag{6.3.4}\\
\Phi_{A B C^{\prime} D^{\prime}}=\Phi_{(A B)\left(C^{\prime} D^{\prime}\right)},  \tag{6.3.5a}\\
\Phi_{A B C^{\prime} D^{\prime}}-\bar{\Phi}_{C^{\prime} D^{\prime} A B} \neq 0,  \tag{6.3.5b}\\
\Sigma_{A B}=\Sigma_{(A B)},  \tag{6.3.6a}\\
R_{[a b]}=\Sigma_{A B} \epsilon_{A^{\prime} B^{\prime}}+\bar{\Sigma}_{A^{\prime} B^{\prime}} \epsilon_{A B},  \tag{6.3.6b}\\
\Lambda-\bar{\Lambda} \neq 0 . \tag{6.3.7}
\end{gather*}
$$

In (6.3.4)-(6.3.6), round (square) brackets denote, as usual, symmetrization (antisymmetrization), and overbars denote complex conjugation of spinors or scalars. The spinor $\sum_{A B}$ and the left-hand sides of (6.3.5b) and (6.3.7) are determined directly by torsion and its covariant derivative. The relations (6.3.5b), (6.3.6b) and (6.3.7) express a substantial difference with respect to general relativity, and hold in any real Lorentzian $U_{4}$ space-time.

We are, however, interested in the case of complex $U_{4}$ space-times (or real Riemannian, where the metric is positive-definite), in order to compare the necessary condition for the existence of $\alpha$-surfaces with what holds for complex general relativity. In that case, it is well-known that the spinor covariant derivative still obeys (6.3.2) but is now a linear, complex-holomorphic operator satisfying the Leibniz rule. Moreover, barred spinors are replaced by independent twiddled spinors (e.g. $\widetilde{\Sigma}_{A^{\prime} B^{\prime}}$ ) which are no longer complex conjugates of unbarred (or untwiddled) spinors, since complex conjugation is no longer available. This also holds for real

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Riemannian $U_{4}$ space-times, not to be confused with real Lorentzian $U_{4}$ spacetimes, but of course, in the positive-definite case the spinor covariant derivative is a real, rather than complex-holomorphic operator.

For the sake of clarity, we hereafter write $C U_{4}, R U_{4}, L U_{4}$ to denote complex, real Riemannian or real Lorentzian $U_{4}$-theory respectively. In light of the previous discussion, the spinorial form of Riemann for $C U_{4}$ and $R U_{4}$ theories is

$$
\begin{align*}
R_{a b c d} & =\psi_{A B C D} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}}+\tilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \epsilon_{A B} \epsilon_{C D} \\
& +\Phi_{A B C^{\prime} D^{\prime}} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C D}+\tilde{\Phi}_{A^{\prime} B^{\prime} C D} \epsilon_{A B} \epsilon_{C^{\prime} D^{\prime}} \\
& +\Sigma_{A B} \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C D} \epsilon_{C^{\prime} D^{\prime}}+\tilde{\Sigma}_{A^{\prime} B^{\prime}} \epsilon_{A B} \epsilon_{C D} \epsilon_{C^{\prime} D^{\prime}} \\
& +\Lambda\left(\epsilon_{A C} \epsilon_{B D}+\epsilon_{A D} \epsilon_{B C}\right) \epsilon_{A^{\prime} B^{\prime}} \epsilon_{C^{\prime} D^{\prime}} \\
& +\tilde{\Lambda}\left(\epsilon_{A^{\prime} C^{\prime}} \epsilon_{B^{\prime} D^{\prime}}+\epsilon_{A^{\prime} D^{\prime}} \epsilon_{B^{\prime} C^{\prime}}\right) \epsilon_{A B} \epsilon_{C D} . \tag{6.3.8}
\end{align*}
$$

The spinors $\psi_{A B C D}$ and $\widetilde{\boldsymbol{\psi}}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}$ appearing in (6.3.8) are called anti-self-dual and self-dual Weyl spinors respectively as in general relativity, and they represent the part of Riemann invariant under conformal rescalings of the metric. This property is proved at the end of section 4 of Penrose 1983, following Eq. (49) therein. Note that in Penrose 1983 a class of conformal rescalings is studied such that $\hat{g}=\Omega \bar{\Omega} g$ (where $\Omega$ is a smooth, nowhere-vanishing, complex-valued function), and leading to the presence of torsion. We are, however, not interested in this method for generating torsion, and we only study models where torsion already exists before any conformal rescaling of the metric.

We are now in a position to compute $\square_{C^{\prime} A^{\prime}} \pi_{B^{\prime}}$ appearing in (6.2.14). For this purpose, following the method in section 4.9 of Penrose and Rindler 1984, we define the operator

$$
\begin{equation*}
\square_{a b} \equiv 2 \nabla_{[a} \nabla_{b]}-2 S_{a b}^{c} \nabla_{c} \tag{6.3.9}
\end{equation*}
$$

and the self-dual null bivector

$$
\begin{equation*}
k^{a b} \equiv \kappa^{A} \kappa^{B} \epsilon^{A^{\prime} B^{\prime}} . \tag{6.3.10}
\end{equation*}
$$

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The Ricci identity for $U_{4}$ theories

$$
\begin{equation*}
\square_{a b} k^{c d}=R_{a b e}{ }^{c} k^{e d}+R_{a b e}{ }^{d} k^{c e}, \tag{6.3.11}
\end{equation*}
$$

then yields

$$
\begin{equation*}
2 \epsilon^{E^{\prime} F^{\prime}} \kappa^{(E} \square_{a b} \kappa^{F)}=\left(\epsilon^{E D} \epsilon^{E^{\prime} D^{\prime}} \epsilon^{C^{\prime} F^{\prime}} \kappa^{C} \kappa^{F}+\epsilon^{F D} \epsilon^{F^{\prime} D^{\prime}} \epsilon^{E^{\prime} C^{\prime}} \kappa^{E} \kappa^{C}\right) R_{a b c d} \tag{6.3.12}
\end{equation*}
$$

This is why, using (6.3.8) and the identity

$$
\begin{equation*}
2 \nabla_{[a} \nabla_{b]}=\epsilon_{A^{\prime} B^{\prime}} \square_{A B}+\epsilon_{A B} \square_{A^{\prime} B^{\prime}} \tag{6.3.13}
\end{equation*}
$$

a lengthy calculation of the 16 terms occurring in (6.3.12) yields

$$
\begin{align*}
\kappa^{(C}\left[\epsilon_{A^{\prime} B^{\prime}} \square_{A B}+\epsilon_{A B} \square_{A^{\prime} B^{\prime}}\right. & \left.-2 S_{A A^{\prime} B B^{\prime}}{ }^{H H^{\prime}} \nabla_{H H^{\prime}}\right] \kappa^{D)} \\
& =\epsilon_{A B}\left[\widetilde{\Phi}_{A^{\prime} B^{\prime} E}{ }^{(G} \kappa^{D)} \kappa^{E}+\widetilde{\Sigma}_{A^{\prime} B^{\prime}} \kappa^{(C} \kappa^{D)}\right] \\
& +\epsilon_{A^{\prime} B^{\prime}}\left[\psi_{A B E}{ }^{(C} \kappa^{D)} \kappa^{E}\right. \\
& \left.-2 \Lambda \kappa^{(C} \kappa_{(B} \epsilon_{A)}{ }^{D)}+\Sigma_{A B} \kappa^{(C} \kappa^{D)}\right] \tag{6.3.14}
\end{align*}
$$

We now write explicitly the symmetrizations over $C$ and $D$ occurring in (6.3.14). Thus, using (6.2.4) and comparing left- and right-hand side of (6.3.14), one finds the equations

$$
\begin{gather*}
{\left[\square_{A B}-2 \chi_{A B}{ }^{H H^{\prime}} \nabla_{H H^{\prime}}\right] \kappa^{C}=\psi_{A B E}{ }^{C} \kappa^{E}-2 \Lambda \kappa_{(A} \epsilon_{B)}^{C}+\Sigma_{A B} \kappa^{C}}  \tag{6.3.15}\\
{\left[\square_{A^{\prime} B^{\prime}}-2 \widetilde{\chi}_{A^{\prime} B^{\prime}}{ }^{H H^{\prime}} \nabla_{H H^{\prime}}\right] \kappa^{C}=\widetilde{\Phi}_{A^{\prime} B^{\prime} E}^{C} \kappa^{E}+\widetilde{\Sigma}_{A^{\prime} B^{\prime}} \kappa^{C}} \tag{6.3.16}
\end{gather*}
$$

Eqs. (6.3.15)-(6.3.16) are two of the four spinor Ricci identities for $C U_{4}$ or $R U_{4}$ theories. The remaining spinor Ricci identities are

$$
\begin{equation*}
\left[\square_{A^{\prime} B^{\prime}}-2 \tilde{\chi}_{A^{\prime} B^{\prime}}{ }^{H H^{\prime}} \nabla_{H H^{\prime}}\right] \pi^{C^{\prime}}=\tilde{\psi}_{A^{\prime} B^{\prime} E^{\prime}}{ }^{C^{\prime}} \pi^{E^{\prime}}-2 \tilde{\Lambda} \pi_{\left(A^{\prime} \epsilon_{\left.B^{\prime}\right)}\right.}{ }^{C^{\prime}}+\widetilde{\Sigma}_{A^{\prime} B^{\prime}} \pi^{C^{\prime}} \tag{6.3.17}
\end{equation*}
$$

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$$
\begin{equation*}
\left[\square_{A B}-2 \chi_{A B}{ }^{H H^{\prime}} \nabla_{H H^{\prime}}\right] \pi^{C^{\prime}}=\Phi_{A B E^{\prime}}^{C^{\prime}} \pi^{E^{\prime}}+\Sigma_{A B} \pi^{C^{\prime}} \tag{6.3.18}
\end{equation*}
$$

### 6.4 Integrability Condition for $\alpha$-Surfaces

Since $\pi^{A^{\prime}} \pi_{A^{\prime}}=0$, insertion of (6.3.17) into (6.2.14) and careful use of (6.2.10) yield

$$
\begin{align*}
-\pi^{A^{\prime}} \pi^{B^{\prime}} \pi^{C^{\prime}}\left(\square_{C^{\prime} A^{\prime}} \pi_{B^{\prime}}\right) & =-\pi^{A^{\prime}} \pi^{B^{\prime}} \pi^{C^{\prime}} \pi^{D^{\prime}} \widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \\
& +4 \pi^{B^{\prime}} \pi^{C^{\prime}} \pi_{F^{\prime}} \pi_{G^{\prime}} \tilde{\chi}_{A^{\prime} B^{\prime} A C^{\prime}} \tilde{\chi}^{F^{\prime} G^{\prime} A A^{\prime}} \tag{6.4.1}
\end{align*}
$$

In the light of (6.2.11)-(6.2.15) and (6.4.1), one thus finds the following integrability condition for Eq. (6.2.10) in the case of $C U_{4}$ or $R U_{4}$ theories (Esposito 1993):

$$
\begin{align*}
\tilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} & =-4 \widetilde{\chi}_{A^{\prime} B^{\prime} A L^{\prime}} \tilde{\chi}_{C^{\prime}}{ }^{L^{\prime} A}{ }_{D^{\prime}}+4 \widetilde{\chi}_{L^{\prime} B^{\prime} A C^{\prime}} \widetilde{\chi}_{A^{\prime} D^{\prime}} A L^{\prime} \\
& +2 \nabla_{D^{\prime}}^{A}\left(\tilde{\chi}_{A^{\prime} B^{\prime} A C^{\prime}}\right) . \tag{6.4.2}
\end{align*}
$$

Note that contributions involving $\xi^{A}$ add up to zero.

### 6.5 Concluding Remarks

We have studied complex or real Riemannian space-times with non-vanishing torsion. By analogy with complex general relativity, $\alpha$-surfaces have been defined as totally null two-surfaces whose null tangent vectors have the two-component spinor form $\lambda^{A} \pi^{A^{\prime}}$, with $\lambda^{A}$ varying and $\pi^{A^{\prime}}$ fixed (cf. section 6.1, Ward and Wells 1990). Using Frobenius' theorem, this leads to Eq. (6.2.10), which differs from the equation corresponding to general relativity by the term involving the torsion spinor. The integrability condition for Eq. (6.2.10) is then given by Eq. (6.4.2), which involves the self-dual Weyl spinor (as in complex general relativity),

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terms quadratic in the torsion spinor, and the covariant derivative of the torsion spinor. Our results (6.2.10) and (6.4.2) are quite generic, in that they do not make use of any field equations. We only assumed we were not studying supersymmetric theories of gravity.

A naturally occurring question is whether an alternative way exists to derive our results (6.2.10) and (6.4.2). This is indeed possible, since in terms of the Levi-Civita connection the necessary and sufficient condition for the existence of $\alpha$-surfaces is the vanishing of the self-dual torsion-free Weyl spinor; one has then to translate this condition into a property of the Weyl spinor and torsion of the full $U_{4}$-connection. One then finds that the integrability condition for $\alpha \in$ surfaces, at first expressed using the self-dual Weyl spinor of the Levi-Civita connection, coincides with Eq. (6.4.2).

We believe, however, that the more fundamental geometrical object is the full $U_{4}$-connection with torsion. This point of view is especially relevant when one studies the Hamiltonian form of these theories, and is along the lines of previous work by the author, where other properties of $U_{4}$-theories have been studied working with the complete $U_{4}$-connection (Esposito 1992, Esposito 1994). It was thus our aim to derive Eq. (6.4.2) in a way independent of the use of formulae relating curvature spinors of the Levi-Civita connection to torsion and curvature spinors of the $U_{4}$-connection. We hope our chapter shows this program can be consistently developed.

Interestingly, a particular solution of Eq. (6.4.2) is given by

$$
\begin{align*}
& \widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}=0  \tag{6.5.1}\\
& \tilde{\chi}_{A^{\prime} C^{\prime} A B^{\prime}}=0 \tag{6.5.2}
\end{align*}
$$

This means that the surviving part of torsion is $X_{A B}{ }^{C C^{\prime}} \varepsilon_{A^{\prime} B^{\prime}}$ (cf. (6.2.4)), which does not affect the integrability condition for $\alpha$-surfaces, and that the $U_{4}$ Weyl curvature is anti-self-dual. Note that this is only possible for $C U_{4}$ and $R U_{4}$ models of gravity, since only for these theories Eqs. (6.5.1)-(6.5.2) do not imply the vanishing

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of $X A C B A^{\prime}$ and $\psi_{A B C D}$ (cf. section 6.3). By analogy with complex general relativity, those particular $C U_{4}$ and $R U_{4}$ space-times satisfying Eqs. (6.5.1)-(6.5.2) are here called right conformally flat (in the light of (6.5.1)) and right-torsion-free (in the light of (6.5.2)). Note that our definition does not involve the Ricci tensor, and is therefore different from Eq. (6.2.1) of Ward and Wells 1990 (see (4.2.2)).
P.S. This chapter relies in part on the work appearing in Esposito 1993. I am very grateful to two anonymous referees of the journal General Relativity and Gravitation for correcting numerous mistakes in the original version of that paper.

## CHAPTER SEVEN

## SPIN- $\frac{1}{2}$ FIELDS IN RIEMANNIAN GEOMETRIES


#### Abstract

Local supersymmetry leads to boundary conditions for fermionic fields in one-loop quantum cosmology involving the Euclidean normal ${ }_{e} n_{A}^{A^{\prime}}$ to the boundary and a pair of independent spinor fields $\psi^{A}$ and $\widetilde{\psi}^{A^{\prime}}$. This chapter studies the corresponding classical properties, i.e. the classical boundary-value problem and boundary terms in the variational problem. If $\sqrt{2}{ }_{e} n_{A}{ }^{A^{\prime}} \psi^{A} \mp \widetilde{\psi}^{A^{\prime}} \equiv \Phi^{A^{\prime}}$ is set to zero on a three-sphere bounding flat Euclidean four-space, the modes of the massless spin- $\frac{1}{2}$ field multiplying harmonics having positive eigenvalues for the intrinsic three-dimensional Dirac operator on $S^{3}$ should vanish on $S^{3}$. Remarkably, this coincides with the property of the classical boundary-value problem when spectral. boundary conditions are imposed on $S^{3}$ in the massless case. Moreover, the boundary term in the action functional is proportional to the integral on the boundary of $\Phi^{A^{\prime}} e^{n_{A A^{\prime}}} \psi^{A}$. The existence of self-adjoint extensions of the Dirac operator subject to supersymmetric boundary conditions is then proved. The global theory of the Dirac operator in compact Riemannian manifolds is finally described.


### 7.1 Dirac and Weyl Equations in Two-Component Spinor Form

Dirac's theory of massive and massless spin- $\frac{1}{2}$ particles is still a key element of modern particle physics and field theory. From the point of view of theoretical physics, the description of such particles motivates indeed the whole theory of Dirac operators. We are here concerned with a two-component spinor analysis of the corresponding spin- $\frac{1}{2}$ fields in Riemannian four-geometries $(M, g)$ with boundary. A massive spin- $\frac{1}{2}$ Dirac field is then described by the four independent spinor fields $\phi^{\boldsymbol{A}}, \chi^{\boldsymbol{A}}, \widetilde{\phi}^{A^{\prime}}, \widetilde{\chi}^{A^{\prime}}$, and the action functional takes the form

$$
\begin{equation*}
I \equiv I_{V}+I_{B} \tag{7.1.1}
\end{equation*}
$$

where

$$
\begin{align*}
I_{V} & \equiv \frac{i}{2} \int_{M}\left[\widetilde{\phi}^{A^{\prime}}\left(\nabla_{A A^{\prime}} \phi^{A}\right)-\left(\nabla_{A A^{\prime}} \tilde{\phi}^{A^{\prime}}\right) \phi^{A}\right] \sqrt{\operatorname{det} g} d^{4} x \\
& +\frac{i}{2} \int_{M}\left[\tilde{\chi}^{A^{\prime}}\left(\nabla_{A A^{\prime}} \chi^{A}\right)-\left(\nabla_{A A^{\prime}} \widetilde{\chi}^{A^{\prime}}\right) \chi^{A}\right] \sqrt{\operatorname{det} g} d^{4} x \\
& +\frac{m}{\sqrt{2}} \int_{M}\left[\chi_{A} \phi^{A}+\bar{\phi}^{A^{\prime}} \tilde{\chi}_{A^{\prime}}\right] \sqrt{\operatorname{det} g} d^{4} x \tag{7.1.2}
\end{align*}
$$

and $I_{B}$ is a suitable boundary term, necessary to obtain a well-posed variational problem. Its form is determined once one knows which spinor fields are fixed on the boundary (e.g. section 7.2). With our notation, the occurrence of $i$ depends on conventions for Infeld-van der Waerden symbols (see section 7.2). One thus finds the field equations

$$
\begin{align*}
\nabla_{A A^{\prime}} \phi^{A} & =\frac{i m}{\sqrt{2}} \widetilde{\chi}_{A^{\prime}}  \tag{7.1.3}\\
\nabla_{A A^{\prime}} \chi^{A} & =\frac{i m}{\sqrt{2}} \widetilde{\phi}_{A^{\prime}}  \tag{7.1.4}\\
\nabla_{A A^{\prime}} \widetilde{\phi}^{A^{\prime}} & =-\frac{i m}{\sqrt{2}} \chi_{A} \tag{7.1.5}
\end{align*}
$$

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$$
\begin{equation*}
\nabla_{A A^{\prime}} \tilde{\chi}^{A^{\prime}}=-\frac{i m}{\sqrt{2}} \phi_{A} \tag{7.1.6}
\end{equation*}
$$

Note that this is a coupled system of first-order differential equations, obtained after applying differentiation rules for anti-commuting spinor fields. This means the spinor field acted upon by the $\nabla A^{\prime}$ operator should be always brought to the left, hence leading to a minus sign if such a field was not already on the left. Integration by parts and careful use of boundary terms are also necessary. The equations (7.1.3)-(7.1.6) reproduce the familiar form of the Dirac equation expressed in terms of $\gamma$-matrices. In particular, for massless fermionic fields one obtains the independent Weyl equations

$$
\begin{align*}
& \nabla^{A A^{\prime}} \phi_{A}=0  \tag{7.1.7}\\
& \nabla^{A A^{\prime}} \tilde{\phi}_{A^{\prime}}=0 \tag{7.1.8}
\end{align*}
$$

not related by any conjugation.

### 7.2 Boundary Terms for Massless Fermionic Fields

Locally supersymmetric boundary conditions have been recently studied in quantum cosmology to understand its one-loop properties. They involve the normal to the boundary and the field for spin $\frac{1}{2}$, the normal to the boundary and the spin- $\frac{3}{2}$ potential for gravitinos, Dirichlet conditions for real scalar fields, magnetic or electric field for electromagnetism, mixed boundary conditions for the four-metric of the gravitational field (and in particular Dirichlet conditions on the perturbed three-metric). The aim of this section is to describe the corresponding classical properties in the case of massless spin- $\frac{1}{2}$ fields.

For this purpose, we consider flat Euclidean four-space bounded by a threesphere of radius $a$. The alternative possibility a more involved boundary-value problem, where flat Euclidean four-space is bounded by two concentric threespheres of radii $r_{1}$ and $r_{2}$. The spin- $\frac{1}{2}$ field, represented by a pair of independent

## 7. Spin- $\frac{1}{2}$ Fields in Riemannian Geometries

spinor fields $\psi^{A}$ and $\widetilde{\boldsymbol{\psi}}^{A^{\prime}}$, is expanded on a family of three-spheres centred on the origin as (D'Eath and Halliwell 1987, D'Eath and Esposito 1991a, Esposito 1994)

$$
\begin{align*}
\psi^{A} & =\frac{\tau^{-\frac{3}{2}}}{2 \pi} \sum_{n=0}^{\infty} \sum_{p=1}^{(n+1)(n+2)(n+1)(n+2)} \sum_{q=1}^{p q}\left[m_{n p}(\tau) \rho^{n q A}+\widetilde{r}_{n p}(\tau) \bar{\sigma}^{n q A}\right]  \tag{7.2.1}\\
\widetilde{\psi}^{A^{\prime}} & =\frac{\tau^{-\frac{3}{2}}}{2 \pi} \sum_{n=0}^{\infty} \sum_{p=1}^{(n+1)(n+2)(n+1)(n+2)} \sum_{q=1} \alpha_{n}^{p q}\left[\widetilde{m}_{n p}(\tau) \bar{\rho}^{n q A^{\prime}}+r_{n p}(\tau) \sigma^{n q A^{\prime}}\right] . \tag{7.2.2}
\end{align*}
$$

With our notation, $\tau$ is the Euclidean-time coordinate, the $\alpha_{n}^{p q}$ are block-diagonal matrices with blocks $\left(\begin{array}{cc}1 & 1 \\ 1 & -1\end{array}\right)$, the $\rho$ - and $\sigma$-harmonics obey the identities described in D'Eath and Halliwell 1987, Esposito 1994. Last but not least, the modes $m_{n p}$ and $r_{n p}$ are regular at $\tau=0$, whereas the modes $\widetilde{\boldsymbol{m}}_{n p}$ and $\widetilde{\boldsymbol{r}}_{n p}$ are singular at $\tau=0$ if the spin- $\frac{1}{2}$ field is massless. Bearing in mind that the harmonics $\rho^{n q A}$ and $\sigma^{n g A^{\prime}}$ have positive eigenvalues $\frac{1}{2}\left(n+\frac{3}{2}\right)$ for the three-dimensional Dirac operator on the bounding $S^{3}$ (Esposito 1994), the decomposition (7.2.1)-(7.2.2) can be re-expressed as

$$
\begin{align*}
& \psi^{A}=\psi_{(+)}^{A}+\psi_{(-)}^{A}  \tag{7.2.3}\\
& \widetilde{\psi}^{A^{\prime}}=\tilde{\psi}_{(+)}^{A^{\prime}}+\tilde{\psi}_{(-)}^{A^{\prime}} \tag{7.2.4}
\end{align*}
$$

In (7.2.3)-(7.2.4), the $(+)$ parts correspond to the modes mnp and $r_{n p}$, whereas the (-) parts correspond to the singular modes $\tilde{m}_{n p}$ and $\widetilde{\boldsymbol{r}}_{y p}$, which multiply harmonics having negative eigenvalues $-\frac{1}{2}\left(n+\frac{3}{2}\right)$ for the three-dimensional Dirac operator on $S^{3}$. If one wants to find a classical solution of the Weyl equation which is regular $\forall \tau \in[0, a]$, one is thus forced to set to zero the modes $\tilde{\boldsymbol{m}}_{n p}$ and $\widetilde{r}_{n p} \forall \tau \in[0, a]$ (D'Eath and Halliwell 1987). This is why, if one requires the local boundary conditions (Esposito 1994)

$$
\begin{equation*}
\sqrt{2}{ }_{\mathrm{e}} n_{A}^{A^{\prime}} \psi^{A} \mp \tilde{\psi}^{A^{\prime}}=\Phi^{A^{\prime}} \text { on } S^{3}, \tag{7.2.5}
\end{equation*}
$$

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such a condition can be expressed as

$$
\begin{gather*}
\sqrt{2}{ }_{e} n_{A}^{A^{\prime}} \psi_{(+)}^{A}=\Phi_{1}^{A^{\prime}} \text { on } S^{3}  \tag{7.2.6}\\
\mp \widetilde{\psi}_{(+)}^{A^{\prime}}=\Phi_{2}^{A^{\prime}} \text { on } S^{3} \tag{7.2.7}
\end{gather*}
$$

where $\Phi_{1}{ }^{A^{\prime}}$ and $\Phi_{2}{ }^{A^{\prime}}$ are the parts of the spinor field $\Phi^{A^{\prime}}$ related to the $\overline{\boldsymbol{\rho}}$ - and $\sigma$-harmonics respectively. In particular, if $\phi_{1}^{A^{\prime}}=\phi_{2}^{A^{\prime}}=0$ on $S^{3}$, one finds

$$
\begin{gather*}
\sum_{n=0}^{\infty} \sum_{p=1}^{(n+1)(n+2)(n+1)(n+2)} \sum_{q=1}^{(n q} \alpha_{n}^{p q} m_{n p}(a)_{e} n_{A}^{A^{\prime}} \rho_{n q}^{A}=0,  \tag{7.2.8}\\
\quad \sum_{n=0}^{\infty} \sum_{p=1}^{(n+1)(n+2)(n+1)(n+2)} \sum_{q=1} \alpha_{n}^{p q} r_{n p}(a) \sigma_{n q}^{A^{\prime}}=0, \tag{7.2.9}
\end{gather*}
$$

where $a$ is the three-sphere radius. Since the harmonics appearing in (7.2.8)(7.2.9) are linearly independent, these relations lead to $m_{n p}(a)=r_{n p}(a)=0$ $\forall n, p$. Remarkably, this simple calculation shows that the classical boundary-value problems for regular solutions of the Weyl equation subject to local or spectral conditions on $S^{3}$ share the same property provided $\Phi^{A^{\prime}}$ is set to zero in (7.2.5): the regular modes $m_{n p}$ and $r_{n p}$ should vanish on the bounding $S^{3}$.

To study the corresponding variational problem for a massless fermionic field, we should now bear in mind that the spin- $\frac{1}{2}$ action functional in a Riemannian four-geometry takes the form (D'Eath and Esposito 1991a, Esposito 1994)

$$
\begin{equation*}
I_{E} \equiv \frac{i}{2} \int_{M}\left[\tilde{\psi}^{A^{\prime}}\left(\nabla_{A A^{\prime}} \psi^{A}\right)-\left(\nabla_{A A^{\prime}} \tilde{\psi}^{A^{\prime}}\right) \psi^{A}\right] \sqrt{\operatorname{det} g} d^{4} x+\widehat{I}_{B} \tag{7.2.10}
\end{equation*}
$$

This action is real, and the factor $i$ occurs by virtue of the convention for Infeldvan der Waerden symbols used in D'Eath and Esposito 1991a, Esposito 1994. In (7.2.10) $\widehat{I}_{B}$ is a suitable boundary term, to be added to ensure that $I_{E}$ is stationary under the boundary conditions chosen at the various components of the boundary (e.g. initial and final surfaces, as in D'Eath and Halliwell 1987). Of course, the

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variation $\delta I_{E}$ of $I_{E}$ is linear in the variations $\delta \psi^{A}$ and $\delta \widetilde{\psi}^{A}$. Defining $k \equiv \frac{2}{i}$ and $k \widehat{I}_{B} \equiv I_{B}$, variational rules for anticommuting spinor fields lead to

$$
\begin{align*}
\kappa\left(\delta I_{E}\right) & =\int_{M}\left[2 \delta \widetilde{\psi}^{A^{\prime}}\left(\nabla_{A A^{\prime}} \psi^{A}\right)\right] \sqrt{\operatorname{det} g} d^{4} x-\int_{M}\left[\left(\nabla_{A A^{\prime}} \widetilde{\psi}^{A^{\prime}}\right) 2 \delta \psi^{A}\right] \sqrt{\operatorname{det} g} d^{4} x \\
& -\int_{\partial M}\left[{ }^{4} n_{A A^{\prime}}\left(\delta \widetilde{\psi}^{A^{\prime}}\right) \psi^{A}\right] \sqrt{\operatorname{det} h} d^{3} x+\int_{\partial M}\left[{ }_{c} n_{A A^{\prime}} \widetilde{\psi}^{A^{\prime}}(\delta \psi, A)\right] \sqrt{\operatorname{det} h} d^{3} x \\
& +\delta I_{B}, \tag{7.2.11}
\end{align*}
$$

where $I_{B}$ should be chosen in such a way that its variation $\delta I_{B}$ combines with the sum of the two terms on the second line of (7.2.11) so as to specify what is fixed on the boundary (see below). Indeed, setting $\in \equiv \pm 1$ and using the boundary conditions (7.2.5) one finds

$$
\begin{equation*}
{ }_{e} n_{A A^{\prime}} \tilde{\psi}^{A^{\prime}}=\frac{\epsilon}{\sqrt{2}} \psi_{A}-\epsilon_{e} n_{A A^{\prime}} \Phi^{A^{\prime}} \text { on } S^{3} \tag{7.2.12}
\end{equation*}
$$

Thus, anticommutation rules for spinor fields (D'Eath and Halliwell 1987) show that the second line of Eq. (7.2.11) reads

$$
\begin{align*}
\delta I_{\partial M} & \equiv-\int_{\partial M}\left[\left(\delta \widetilde{\psi}^{A^{\prime}}\right)_{e} n_{A A^{\prime}} \psi^{A}\right] \sqrt{\operatorname{det} h} d^{3} x+\int_{\partial M}\left[{ }_{e} n_{A A^{\prime}} \widetilde{\psi}^{A^{\prime}}\left(\delta \psi^{A}\right)\right] \sqrt{\operatorname{det} h} d^{3} x \\
& =\epsilon \int_{\partial M}{ }_{e} n_{A A^{\prime}}\left[\left(\delta \Phi^{A^{\prime}}\right) \psi^{A}-\Phi^{A^{\prime}}\left(\delta \psi^{A}\right)\right] \sqrt{\operatorname{det} h} d^{3} x \tag{7.2.13}
\end{align*}
$$

Now it is clear that setting

$$
\begin{equation*}
I_{B} \equiv \epsilon \int_{\partial M} \Phi^{A^{\prime}}{ }_{e} n_{A A^{\prime}} \psi^{A} \sqrt{\operatorname{det} h} d^{3} x \tag{7.2.14}
\end{equation*}
$$

enables one to specify $\Phi^{A^{\prime}}$ on the boundary, since

$$
\begin{equation*}
\delta\left[I_{\partial M}+I_{B}\right]=2 \epsilon \int_{\partial M} e^{n_{A A^{\prime}}}\left(\delta \Phi^{A^{\prime}}\right) \psi^{A} \sqrt{\operatorname{det} h} d^{3} x \tag{7.2.15}
\end{equation*}
$$

Hence the action integral (7.2.10) appropriate for our boundary-value problem is (Esposito et al. 1994)

$$
\begin{align*}
I_{E} & =\frac{i}{2} \int_{M}\left[\widetilde{\psi}^{A^{\prime}}\left(\nabla_{A A^{\prime}} \psi^{A}\right)-\left(\nabla_{A A^{\prime}} \widetilde{\psi}^{A^{\prime}}\right) \psi^{A}\right] \sqrt{\operatorname{det} g} d^{4} x \\
& +\frac{i \epsilon}{2} \int_{\partial M} \Phi^{A^{\prime}}{ }_{e} n_{A A^{\prime}} \psi^{A} \sqrt{\operatorname{det} h} d^{3} x \tag{7.2.16}
\end{align*}
$$

Note that, by virtue of (7.2.5), Eq. (7.2.13) may also be cast in the form

$$
\begin{equation*}
\delta I_{\partial M}=\frac{1}{\sqrt{2}} \int_{\partial M}\left[\widetilde{\psi}^{A^{\prime}}\left(\delta \Phi_{A^{\prime}}\right)-\left(\delta \widetilde{\psi}^{A^{\prime}}\right) \Phi_{A^{\prime}}\right] \sqrt{\operatorname{det} h} d^{3} x \tag{7.2.17}
\end{equation*}
$$

which implies that an equivalent form of $I_{B}$ is

$$
\begin{equation*}
I_{B} \equiv \frac{1}{\sqrt{2}} \int_{\partial M} \widetilde{\psi}^{A^{\prime}} \Phi_{A^{\prime}} \sqrt{\operatorname{det} h} d^{3} x \tag{7.2.18}
\end{equation*}
$$

The local boundary conditions studied at the classical level in this section, have been applied to one-loop quantum cosmology in D'Eath and Esposito 1991a, Kamenshchik and Mishakov 1993, Esposito 1994. Interestingly, our work seems to add evidence in favour of quantum amplitudes having to respect the properties of the classical boundary-value problem. In other words, if fermionic fields are massless, their one-loop properties in the presence of boundaries coincide in the case of spectral (D'Eath and Halliwell 1987, D'Eath and Esposito 1991b, Esposito 1994) or local boundary conditions (D'Eath and Esposito 1991a, Kamenshchik and Mishakov 1993, Esposito 1994), while we find that classical modes for a regular solution of the Weyl equation obey the same conditions on a three-sphere boundary with spectral or local boundary conditions, provided the spinor field $\Phi^{A^{\prime}}$ of (7.2.5) is set to zero on $S^{3}$. We also hope that the analysis presented in Eqs. (7.2.10)(7.2.18) may clarify the spin- $\frac{1}{2}$ variational problem in the case of local boundary conditions on a three-sphere (cf. the analysis in Charap and Nelson 1983, York 1986, Hayward 1993 for pure gravity).

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### 7.3 Self-Adjointness of the Boundary-Value Problem

So far we have seen that the framework for the formulation of local boundary conditions involving normals and field strengths or fields is the Euclidean regime, where one deals with Riemannian metrics. Thus, we will pay special attention to the conjugation of $S U(2)$ spinors in Euclidean four-space. In fact such a conjugation will play a key role in proving self-adjointness. For this purpose, it can be useful to recall at first some basic results about $S U(2)$ spinors on an abstract Riemannian three-manifold $(\Sigma, h)$. In that case, one considers a bundle over the three-manifold, each fibre of which is isomorphic to a two-dimensional complex vector space $W$. It is then possible to define a nowhere vanishing antisymmetric $\epsilon_{A B}$ (the usual one of section 2.1) so as to raise and lower internal indices, and a positive-definite Hermitian inner product on each fibre: $(\psi, \phi)=\bar{\psi}^{A^{\prime}} G_{A^{\prime} A} \phi^{A}$. The requirements of Hermiticity and positivity imply respectively that $\bar{G}_{A^{\prime} A}=G_{A^{\prime} A}$, $\bar{\psi}^{A^{\prime}} G_{A^{\prime} A} \psi^{A}>0, \forall \psi^{A} \neq 0$. This $G_{A^{\prime} A}$ converts primed indices to unprimed ones, and it is given by $i \sqrt{2} n_{A A^{\prime}}$. Given the space H of all objects $\alpha_{B}{ }_{B}$ such that $\alpha_{A}^{A}=0$ and $\left(\alpha^{\dagger}\right)^{A}{ }_{B}=-\alpha_{B}^{A}$, one finds there always exists a $S U(2)$ soldering form $\sigma^{a}{ }_{A}^{B}$ (i.e. a global isomorphism) between $H$ and the tangent space on $(\Sigma, h)$ such that $h^{a b}=-\sigma_{A}^{a}{ }^{B} \sigma^{b}{ }_{B}{ }^{A}$. Therefore one also finds $\sigma^{a}{ }_{A}{ }^{A}=0$ and $\left(\sigma^{a}{ }_{A}^{B}\right)^{\dagger}=-\sigma_{A}^{a}$. One then defines $\psi^{A}$ an $S U(2)$ spinor on $(\Sigma, h)$. A basic remark is that $S U(2)$ transformations are those $S L(2, C)$ transformations which preserve $n^{A A^{\prime}}=\mathrm{n}^{a} \sigma_{a}{ }^{A A^{\prime}}$, where $n^{a}=(1,0,0,0)$ is the normal to $\Sigma$. The Euclidean conjugation used here (not to be confused with complex conjugation in Minkowski space-time) is such that (see now section 2.1)

$$
\begin{gather*}
\left(\psi_{A}+\lambda \phi_{A}\right)^{\dagger}=\psi_{A}^{\dagger}+\lambda^{*} \phi_{A}^{\dagger} \quad, \quad\left(\psi_{A}^{\dagger}\right)^{\dagger}=-\psi_{A}  \tag{7.3.1}\\
\epsilon_{A B}^{\dagger}=\epsilon_{A B} \quad, \quad\left(\psi_{A} \phi_{B}\right)^{\dagger}=\psi_{A}^{\dagger} \phi_{B}^{\dagger}  \tag{7.3.2}\\
\left(\psi_{A}\right)^{\dagger} \psi^{A}>0 \quad, \quad \forall \psi_{A} \neq 0 \tag{7.3.3}
\end{gather*}
$$

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In (7.3.1) and in the following pages, the symbol * denotes complex conjugation of scalars. How to generalize this picture to the Euclidean four-space ? For this purpose, let us now focus our attention on states that are pairs of spinor fields, defining

$$
\begin{equation*}
w \equiv\left(\psi^{A}, \widetilde{\psi}^{A^{\prime}}\right) \quad, \quad z \equiv\left(\phi^{A}, \widetilde{\phi}^{A^{\prime}}\right) \tag{7.3.4}
\end{equation*}
$$

on the ball of radius $a$ in Euclidean four-space, subject always to the boundary conditions (7.2.5). $w$ and $z$ are subject also to suitable differentiability conditions, to be specified later. Let us also define the operator $C$

$$
\begin{equation*}
C:\left(\psi^{A}, \widetilde{\psi}^{A^{\prime}}\right) \rightarrow\left(\nabla_{B^{\prime}}^{A} \widetilde{\psi}^{B^{\prime}}, \nabla_{B}^{A^{\prime}} \psi^{B}\right) \tag{7.3.5}
\end{equation*}
$$

and the dagger operation

$$
\begin{equation*}
\left(\psi^{A}\right)^{\dagger} \equiv \epsilon^{A B} \delta_{B A^{\prime}} \bar{\psi}^{A^{\prime}} \quad, \quad\left(\widetilde{\psi}^{A^{\prime}}\right)^{\dagger} \equiv \epsilon^{A^{\prime} B^{\prime}} \delta_{B^{\prime} A} \overline{\widetilde{\psi}}^{A} \tag{7.3.6}
\end{equation*}
$$

The consideration of $C$ is suggested of course by the action (7.2.10). In (7.3.6), $\delta_{B A^{\prime}}$ is an identity matrix playing the same role of $G_{A A^{\prime}}$ for $S U(2)$ spinors on $(\Sigma, h)$, so that $\delta_{B A^{\prime}}$ is preserved by $S U(2)$ transformations. Moreover, the bar symbol $\overline{\psi^{\boldsymbol{A}}}=\overline{\boldsymbol{\psi}}^{\boldsymbol{A}^{\boldsymbol{\prime}}}$ denotes the usual complex conjugation of $\operatorname{SL}(2, C)$ spinors. Hence one finds

$$
\begin{equation*}
\left(\left(\psi^{A}\right)^{\dagger}\right)^{\dagger}=\epsilon^{A C} \delta_{C B^{\prime}} \overline{\left(\psi^{B \dagger}\right)^{\prime}}=\epsilon^{A C} \delta_{C B^{\prime}} \epsilon^{B^{\prime} D^{\prime}} \delta_{D^{\prime} F} \psi^{F}=-\psi^{A} \tag{7.3.7}
\end{equation*}
$$

in view of the definition of $\in^{A B}$. Thus, the dagger operation defined in (7.3.6) is anti-involutory, because, when applied twice to $\psi^{A}$, it yields $-\psi^{A}$.

From now on we study commuting spinors, for simplicity of exposition of the self-adjointness. It is easy to check that the dagger, also called in the literature Euclidean conjugation (section 2.1), satisfies all properties (7.3.1)-(7.3.3). We can now define the scalar product

$$
\begin{equation*}
(w, z) \equiv \int_{M}\left[\psi_{A}^{\dagger} \phi^{A}+\tilde{\psi}_{A^{\prime}}^{\dagger} \tilde{\phi}^{A^{\prime}}\right] \sqrt{g} d^{4} x \tag{7.3.8}
\end{equation*}
$$

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This is indeed a scalar product, because it satisfies all following properties for all vectors $u, v, w$ and $\forall \lambda \in C$ :

$$
\begin{gather*}
(u, u)>0 \quad, \quad \forall u \neq 0  \tag{7.3.9}\\
(u, v+w)=(u, v)+(u, w)  \tag{7.3.10}\\
(u, \lambda v)=\lambda(u, v) \quad, \quad(\lambda u, v)=\lambda^{*}(u, v)  \tag{7.3.11}\\
(v, u)=(u, v)^{*} \tag{7.3.12}
\end{gather*}
$$

We are now aiming to check that $C$ or $i C$ is a symmetric operator, i.e. that $(C z, w)=(z, C w)$ or $(i C z, w)=(z, i C w), \forall z, w$. This will be used in the course of proving further that the symmetric operator has self-adjoint extensions. In order to prove this result it is clear, in view of (7.3.8), we need to know the properties of the spinor covariant derivative acting on $S U(2)$ spinors. In the case of $S L(2, C)$ spinors it is known this derivative is a linear, torsion-free map $\nabla_{A A}$, which satisfies the Leibniz rule, annihilates $\in_{A B}$ and is real (i.e. $\psi=\nabla_{\boldsymbol{A} \boldsymbol{A}^{\prime}} \boldsymbol{\theta} \Rightarrow \overline{\boldsymbol{\psi}}=\nabla_{\boldsymbol{A} \boldsymbol{A}^{\prime}} \overline{\boldsymbol{\theta}}$ ). Moreover, we know that

$$
\begin{equation*}
\nabla^{A A^{\prime}}=e^{A A^{\prime}} \nabla^{\mu}=e_{\mu}^{a} \sigma_{a}^{A A^{\prime}} \nabla^{\mu} \tag{7.3.13}
\end{equation*}
$$

In Euclidean four-space, we use both (7.3.13) and the relation

$$
\begin{equation*}
\sigma_{\mu A C^{\prime}} \sigma_{\nu B} C^{\prime}+\sigma_{\nu B C^{\prime}} \sigma_{\mu A} C^{\prime}=\delta_{\mu \nu} \epsilon_{A B} \tag{7.3.14}
\end{equation*}
$$

where $\delta_{\mu v}$ has signature $(+,+,+,+)$. This implies that $\sigma_{0}=-\frac{i}{\sqrt{2}} I, \sigma_{i}=\frac{\boldsymbol{\Sigma}_{i}}{\sqrt{2}}$, $\forall i=1,2,3$, where $\Sigma_{i}$ are the Pauli matrices. Now, in view of (7.3.5) and (7.3.8) one finds

$$
\begin{equation*}
(C z, w)=\int_{M}\left(\nabla_{A B^{\prime}} \phi^{A}\right)^{\dagger} \widetilde{\psi}^{B^{\prime}} \sqrt{g} d^{4} x+\int_{M}\left(\nabla_{B A^{\prime}} \widetilde{\phi}^{A^{\prime}}\right)^{\dagger} \psi^{B} \sqrt{g} d^{4} x \tag{7.3.15}
\end{equation*}
$$

whereas, using the Leibniz rule to evaluate

$$
\nabla_{B^{\prime}}^{A}\left(\phi_{A}^{\dagger} \tilde{\psi}^{B^{\prime}}\right)
$$

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and

$$
\nabla_{B}^{A^{\prime}}\left(\left(\widetilde{\phi}_{A^{\prime}}\right)^{\dagger} \psi^{B}\right)
$$

and integrating by parts, one finds

$$
\begin{align*}
(z, C w) & =\int_{M}\left(\nabla_{A B^{\prime}} \phi^{A \dagger}\right) \widetilde{\psi}^{B^{\prime}} \sqrt{g} d^{4} x+\int_{M}\left(\nabla_{B A^{\prime}}\left(\widetilde{\phi}^{A^{\prime}}\right)^{\dagger}\right) \psi^{B} \sqrt{g} d^{4} x \\
& -\int_{\theta M}\left({ }_{e} n_{A B^{\prime}}\right) \phi^{A \dagger} \widetilde{\psi}^{B^{\prime}} \sqrt{h} d^{3} x \\
& -\int_{\partial M}\left({ }_{e} n_{B A^{\prime}}\right)\left(\widetilde{\phi}^{A^{\prime}}\right)^{\dagger} \psi^{B} \sqrt{h} d^{3} x \tag{7.3.16}
\end{align*}
$$

Now we use (7.3.6), section 2.1, the identity

$$
\begin{equation*}
\left(e^{A A^{\prime}} \phi_{A}\right)^{\dagger}=\epsilon^{A^{\prime} B^{\prime}} \delta_{B^{\prime} C} \overline{e^{n^{D C^{\prime}}}} \overline{\phi_{D}}=-\epsilon^{A^{\prime} B^{\prime}} \delta_{B^{\prime} C}\left(e^{C D^{\prime}}\right) \bar{\phi}_{D^{\prime}} \tag{7.3.17}
\end{equation*}
$$

and the boundary conditions on $S^{3}: \sqrt{2}{ }_{e} n^{C B^{\prime}} \psi_{C}=\widetilde{\psi^{B^{\prime}}}, \sqrt{2}{ }_{e} n^{A A^{\prime}} \phi_{A}=\widetilde{\phi^{A^{\prime}}}$. In so doing, the sum of the boundary terms in (7.3.16) is found to vanish. This implies in turn that equality of the volume integrands is sufficient to show that $(C z, w)$ and $(z, C w)$ are equal. For example, one finds in flat space, using also (7.3.6): $\left(\nabla_{B A^{\prime}} \widetilde{\phi}^{A^{\prime}}\right)^{\dagger}=\delta_{B F^{\prime}} \bar{\sigma}_{C}^{F^{\prime} a} \partial_{a}\left(\overline{\tilde{\phi}}^{C}\right)$, whereas:

$$
\left(\nabla_{B A^{\prime}}\left(\tilde{\phi}^{A^{\prime}}\right)^{\dagger}\right)=-\delta_{C F^{\prime}} \sigma_{B}^{F^{\prime} a} \partial_{a}\left(\widetilde{\widetilde{\phi}}^{C}\right)
$$

In other words, we are led to study the condition

$$
\begin{equation*}
\delta_{B F^{\prime}} \bar{\sigma}_{C}^{F^{\prime} a}= \pm \delta_{B F^{\prime}} \sigma_{C}^{F^{\prime} a} \tag{7.3.18}
\end{equation*}
$$

$\forall a=0,1,2,3$. Now, using the relations

$$
\begin{align*}
& \sqrt{2} \sigma_{A A^{\prime}}^{0}=\left(\begin{array}{cc}
-i & 0 \\
0 & -i
\end{array}\right) \quad, \quad \sqrt{2} \sigma_{A A^{\prime}}^{1}=\left(\begin{array}{cc}
0 & 1 \\
1 & 0
\end{array}\right),  \tag{7.3.19}\\
& \sqrt{2} \sigma_{A A^{\prime}}^{2}=\left(\begin{array}{cc}
0 & -i \\
i & 0
\end{array}\right) \quad, \quad \sqrt{2} \sigma_{A A^{\prime}}^{3}=\left(\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right), \tag{7.3.20}
\end{align*}
$$

$$
\begin{equation*}
\sigma_{A^{\prime}}{ }^{a}=\epsilon^{A B} \sigma_{B A^{\prime}}{ }^{a} \quad, \quad \sigma_{A} A^{\prime} a=-\sigma_{A B^{\prime}}{ }^{a} \epsilon^{B^{\prime} A^{\prime}}, \tag{7.3.21}
\end{equation*}
$$

one finds that the complex conjugate of $\sigma^{A}{ }_{A^{\prime}}{ }^{a}$ is always equal to $\sigma_{A}{ }^{A^{\prime} a}$, which is not in agreement with the choice of the $(-)$ sign on the right-hand side of (7.3.18). This implies in turn that the symmetric operator we are looking for is $i C$, where $C$ has been defined in (7.3.5). The generalization to a curved four-dimensional Riemannian space is obtained via the relation $e^{\boldsymbol{A} A^{\prime}}{ }_{\mu}=\boldsymbol{e}^{\boldsymbol{a}}{ }_{\mu} \sigma_{a} \boldsymbol{A A ^ { \prime }}$.

Now, it is known that every symmetric operator has a closure, and the operator and its closure have the same closed extensions. Moreover, a closed symmetric operator on a Hilbert space is self-adjoint if and only if its spectrum is a subset of the real axis. To prove self-adjointness for our boundary-value problem, we may recall an important result due to von Neumann (Reed and Simon 1975). This theorem states that, given a symmetric operator $A$ with domain $D(A)$, if a map $F: D(A) \rightarrow D(A)$ exists such that

$$
\begin{gather*}
F(\alpha w+\beta z)=\alpha^{*} F(w)+\beta^{*} F(z),  \tag{7.3.22}\\
(w, w)=(F w, F w)  \tag{7.3.23}\\
F^{2}= \pm I  \tag{7.3.24}\\
F A=A F \tag{7.3.25}
\end{gather*}
$$

then $A$ has self-adjoint extensions. In our case, denoting by $D$ the operator (cf. (7.3.6))

$$
\begin{equation*}
D:\left(\psi^{A}, \widetilde{\psi}^{A^{\prime}}\right) \rightarrow\left(\left(\psi^{A}\right)^{\dagger},\left(\widetilde{\psi}^{A^{\prime}}\right)^{\dagger}\right) \tag{7.3.26}
\end{equation*}
$$

let us focus our attention on the operators $F \equiv i D$ and $A \equiv i C$. The operator $F$ maps indeed $D(A)$ to $D(A)$. In fact, bearing in mind the definitions

$$
\begin{align*}
G & \equiv\left\{\varphi=\left(\phi^{A}, \widetilde{\phi}^{A^{\prime}}\right): \varphi \text { is at least } C^{1}\right\},  \tag{7.3.27}\\
D(A) & \equiv\left\{\varphi \in G: \sqrt{2} e^{e} n^{A A^{\prime}} \phi_{A}=\epsilon \widetilde{\phi}^{A^{\prime}} \text { on } S^{3}\right\}, \tag{7.3.28}
\end{align*}
$$

one finds that $F$ maps $\left(\phi^{A}, \widetilde{\phi}^{A^{\prime}}\right)$ to $\left(\beta^{A}, \widetilde{\beta}^{A^{\prime}}\right)=\left(i\left(\phi^{\boldsymbol{A}}\right)^{\dagger}, i\left(\widetilde{\phi}^{A^{\prime}}\right)^{\dagger}\right)$ such that

$$
\begin{equation*}
\sqrt{2} e^{n^{A A^{\prime}} \beta_{A}}=\gamma \widetilde{\beta}^{A^{\prime}} \text { on } S^{3}, \tag{7.3.29}
\end{equation*}
$$

where $\gamma=\epsilon^{*}$. The boundary condition (7.3.29) is clearly of the type which occurs in (7.3.28) provided $\in$ is real, and the differentiability of $\left(\boldsymbol{\beta}^{\boldsymbol{A}}, \widetilde{\boldsymbol{\beta}}^{\boldsymbol{A}^{\prime}}\right)$ is not affected by the action of $F$ (cf. (7.3.26)). In deriving (7.3.29), we have used the result for $\left({ }_{e} n^{\boldsymbol{A} \boldsymbol{A}^{\prime}} \phi_{A}\right)^{\dagger}$ obtained in (7.3.17). It is worth emphasizing that the requirement of self-adjointness enforces the choice of a real function $\epsilon$, which is a constant in our case. Moreover, in view of (7.3.7), one immediately sees that (7.3.22) and (7.3.24) hold when $F=i D$, provided we write (7.3.24) as $F^{2}=-I$. This is indeed a crucial point which deserves special attention. Condition (7.3.24) is written in Reed and Simon 1975 as $F^{2}=I$, and examples are later given (see page 144 therein) where $F$ is complex conjugation. But we are formulating our problem in the Euclidean regime, where we have seen that the only possible conjugation is the dagger operation, which is anti-involutory on spinors with an odd number of indices. Thus, we are here generalizing von Neumann's theorem in the following way. If $F$ is a map $D(A) \rightarrow D(A)$ which satisfies (7.3.22)-(7.3.25), then the same is clearly true of $\widetilde{\boldsymbol{F}} \equiv-i \boldsymbol{D}=-\boldsymbol{F}$. Hence

$$
\begin{gather*}
-F D(A) \subseteq D(A)  \tag{7.3.30}\\
F D(A) \subseteq D(A) \tag{7.3.31}
\end{gather*}
$$

Acting with $F$ on both sides of (7.3.30), one finds

$$
\begin{equation*}
D(A) \subseteq F D(A) \tag{7.3.32}
\end{equation*}
$$

using the property $F^{2}=-I$. But then the relations (7.3.31)-(7.3.32) imply that F $D(A)=D(A)$, so that $F$ takes $D(A)$ onto $D(A)$ also in the case of the antiinvolutory Euclidean conjugation that we called dagger. Comparison with the proof presented at the beginning of page 144 in Reed and Simon 1975 shows that

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this is all what we need so as to generalize von Neumann's theorem to the Dirac operator acting on $S U(2)$ spinors in Euclidean four-space (one later uses properties (7.3.25), (7.3.22) and (7.3.23) as well in completing the proof).

It remains to verify conditions (7.3.23) and (7.3.25). First, note that

$$
\begin{align*}
(F w, F w) & =(i D w, i D w) \\
& =\int_{M}\left(i \psi_{A}^{\dagger}\right)^{\dagger} i\left(\psi^{A}\right)^{\dagger} \sqrt{g} d^{4} x+\int_{M}\left(i \widetilde{\psi}_{A^{\prime}}^{\dagger}\right)^{\dagger} i\left(\widetilde{\psi}^{A^{\prime}}\right)^{\dagger} \sqrt{g} d^{4} x \\
& =(w, w) \tag{7.3.33}
\end{align*}
$$

where we have used (7.3.7)-(7.3.8) and the commutation property of our spinors. Second, one finds

$$
\begin{align*}
& F A w=(i D)(i C) w=i\left[i\left(\nabla_{B^{\prime}}^{A} \tilde{\psi}^{B^{\prime}}, \nabla_{B}^{A^{\prime}} \psi^{B}\right)\right]^{\dagger}=\left(\nabla_{B^{\prime}}^{A} \tilde{\psi}^{B^{\prime}}, \nabla_{B}^{A^{\prime}} \psi^{B}\right)^{\dagger}  \tag{7.3.34}\\
& A F w=(i C)(i D) w=i C i\left(\psi^{A \dagger},\left(\widetilde{\psi}^{A^{\prime}}\right)^{\dagger}\right)=-\left(\nabla_{B^{\prime}}^{A^{\prime}}\left(\widetilde{\psi}^{B^{\prime}}\right)^{\dagger}, \nabla_{B}^{A^{\prime}} \psi^{B \dagger}\right), \tag{7.3.35}
\end{align*}
$$

which in turn implies that also (7.3.25) holds in view of what we found just before (7.3.18) and after (7.3.21). To sum up, we have proved that the operator $i C$ arising in our boundary-value problem is symmetric and has self-adjoint extensions. Hence the eigenvalues of $i C$ are real, and the eigenvalues $\lambda_{n}$ of $C$ are purely imaginary. This is what we mean by self-adjointness of our boundary-value problem, although it remains to be seen whether there is a unique self-adjoint extension of our firstorder operator.

### 7.4 Global Theory of the Dirac Operator

In this chapter and in other sections of our monograph there are many applications of the Dirac operator relying on two-component spinor formalism. Hence

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it appears necessary to describe some general properties of such an operator, frequently studied in theoretical and mathematical physics.

In Riemannian four-geometries, the total Dirac operator may be defined as a first-order elliptic operator mapping smooth sections of a complex vector bundle to smooth sections of the same bundle. Its action on the sections (i.e. the spinor fields) is given by composition of Clifford multiplication (see appendix A) with covariant differentiation. To understand these statements, we first summarize the properties of connections on complex vector bundles, and we then introduce the basic properties of spin-structures which enable one to understand how to construct the vector bundle relevant for the theory of the Dirac operator.

A complex vector bundle (Chern 1979) is a bundle whose fibres are isomorphic to complex vector spaces. Denoting by $E$ the total space, by $M$ the base space, one has the projection map $\pi: E \rightarrow M$ and the sections $s: M \rightarrow E$ such that the composition of $\pi$ with $s$ yields the identity on the base space: $\pi \cdot s=\mathrm{id}_{M}$. The sections $s$ represent the physical fields in our applications. Moreover, denoting by $T$ and $T^{*}$ the tangent and cotangent bundles of $M$ respectively, a connection $\nabla$ is a map from the space $\Gamma(E)$ of smooth sections of $E$ to the space of smooth sections of the tensor-product bundle $\Gamma\left(T^{*} \otimes E\right)$ :

$$
\nabla: \Gamma(E) \rightarrow \Gamma\left(T^{*} \otimes E\right)
$$

such that the following properties hold:

$$
\begin{gather*}
\nabla\left(s_{1}+s_{2}\right)=\nabla s_{1}+\nabla s_{2}  \tag{7.4.1}\\
\nabla(f s)=d f \otimes s+f \nabla s \tag{7.4.2}
\end{gather*}
$$

where $s_{1}, s_{2}, s \in \Gamma(E)$ and $f$ is any $C^{\infty}$ function. The action of the connection $\nabla$ is expressed in terms of the connection matrix $\theta$ as

$$
\begin{equation*}
\nabla s=\theta \otimes s \tag{7.4.3}
\end{equation*}
$$

If one takes a section $s^{\prime}$ related to $s$ by

$$
\begin{equation*}
s^{\prime}=g s \tag{7.4.4}
\end{equation*}
$$

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in the light of (7.4.2)-(7.4.4) one finds by comparison that

$$
\begin{equation*}
\theta^{\prime} g=d g+g \theta \tag{7.4.5}
\end{equation*}
$$

Moreover, the transformation law of the curvature matrix

$$
\begin{equation*}
\Omega \equiv d \theta-\theta \wedge \theta \tag{7.4.6}
\end{equation*}
$$

is found to be

$$
\begin{equation*}
\Omega^{\prime}=g \Omega g^{-1} \tag{7.4.7}
\end{equation*}
$$

We can now introduce spin-structures and the corresponding complex vector bundle acted upon by the total Dirac operator. Let $X$ be a compact oriented differentiable $n$-dimensional manifold (without boundary) on which a Riemannian metric is introduced. Let $Q$ be the principal tangential $S O(n)$-bundle of $X$. A spin-structure of $X$ is a principal $\operatorname{Spin}(n)$-bundle $P$ over $X$ together with a covering map $\widetilde{\pi}: P \rightarrow Q$ such that the following commutative structure exists (see figure 7.4.1). Given the Cartesian product $P \times \operatorname{Spin}(n)$, one first reaches $P$ by the right action of $\operatorname{Spin}(n)$ on $P$, and one finally arrives at $Q$ by the projection map $\tilde{\pi}$. This is equivalent to first reaching the Cartesian product $Q \times S O(n)$ by the map $\tilde{\pi} \times \rho$, and finally arriving at $Q$ by the right action of $S O(n)$ on $Q$. Of course, by $\rho$ we denote the double covering $\operatorname{Spin}(n) \rightarrow S O(n)$. In other words, $P$ and $Q$ as above are principal fibre bundles over $X$, and one has a commutative diagram with $P \times \operatorname{Spin}(n)$ and $P$ on the top, and $Q \times S O(n)$ and $Q$ on the bottom. The projection map from $P \times \operatorname{Spin}(n)$ to $Q \times S O(n)$ is $\widetilde{\pi} \times \rho$, and the projection map from $P$ to $Q$ is $\tilde{\pi}$. Horizontal arrows should be drawn to denote the right action of $\operatorname{Spin}(n)$ on $P$ on the top, and of $S O(n)$ on $Q$ on the bottom.

The group $\operatorname{Spin}(n)$ has a complex representation space $\sum$ of dimension $2^{n}$ called the spin-representation. If $g \in \operatorname{Spin}(n), x \in R^{n}, u \in \sum$, one has therefore

$$
\begin{equation*}
g(x u)=g x g^{-1} \cdot g(u)=\rho(g) x \cdot g(u) \tag{7.4.8}
\end{equation*}
$$

where $\rho: \operatorname{Spin}(n) \rightarrow S O(n)$ is the covering map as we said before. If $X$ is evendimensional, i.e. $n=2 l$, the representation is the direct sum of two irreducible

## 7. Spin $-\frac{1}{2}$ Fields in Riemannian Geometries

representations $\sum^{ \pm}$of dimension $2^{n-1}$. If $X$ is a $\operatorname{Spin}(2 l)$ manifold with principal bundle $P$, we can form the associated complex vector bundles

$$
\begin{align*}
& E^{+} \equiv P \times \Sigma^{+},  \tag{7.4.9a}\\
& E^{-} \equiv P \times \Sigma^{-},  \tag{7.4.9b}\\
& E \equiv E^{+} \oplus E^{-}, \tag{7.4.10}
\end{align*}
$$

Sections of these vector bundles are spinor fields on $X$.
The total Dirac operator is a first-order elliptic differential operator $D$ : $\Gamma(E) \rightarrow \Gamma(E)$ defined as follows. Recall first that the Riemannian metric defines a natural $S O(2 /)$ connection, and this may be used to give a connection for $P$. One may therefore consider the connection $\nabla$ at the beginning of this section, i.e. a linear map from $\Gamma(E)$ to $\Gamma\left(T^{*} \otimes E\right)$. On the other hand, the tangent and cotangent bundles of $X$ are isomorphic, and one has the map from $\Gamma(T \otimes E) \rightarrow \Gamma(E)$ induced by Clifford multiplication (see Ward and Wells 1990 and our appendix A on Clifford algebras and Clifford multiplication). The total Dirac operator $D$ is defined to be the composition of these two maps. Thus, in terms of an orthonormal base $e_{i}$ of $T$, one has locally

$$
\begin{equation*}
D s=\sum_{i} e_{i}\left(\nabla_{i} s\right) \tag{7.4.11}
\end{equation*}
$$

where $\nabla_{i} s$ is the covariant derivative of $s \in \Gamma(E)$ in the direction $e_{i}$, and $e_{i}()$ denotes Clifford multiplication (cf. (7.3.13)). Moreover, the total Dirac operator $D$ induces two operators

$$
\begin{align*}
& D^{+}: \Gamma\left(E^{+}\right) \rightarrow \Gamma\left(E^{-}\right)  \tag{7.4.12}\\
& D^{-}: \Gamma\left(E^{-}\right) \rightarrow \Gamma\left(E^{+}\right) \tag{7.4.13}
\end{align*}
$$

each of which is elliptic. It should be emphasized that ellipticity of the total and partial Dirac operators only holds in Riemannian manifolds, whereas it does not apply to the Lorentzian manifolds of general relativity and of the original Dirac's theory of spin- $\frac{1}{2}$ particles. This description of the Dirac operator should be compared with the mathematical structures presented in section 2.1.

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Figure 7.4.1

## SPIN- $\frac{3}{2}$ POTENTIALS


#### Abstract

Local boundary conditions involving field strengths and the normal to the boundary, originally studied in anti-de Sitter space-time, have been recently considered in one-loop quantum cosmology. This chapter derives the conditions under which spin-lowering and spin-raising operators preserve these local boundary conditions on a three-sphere for fields of spin $0, \frac{1}{2}, 1, \frac{3}{2}$ and 2 . Moreover, the twocomponent spinor analysis of the four potentials of the totally symmetric and independent field strengths for spin $\frac{3}{2}$ is applied to the case of a three-sphere boundary. It is shown that such boundary conditions can only be imposed in a flat Euclidean background, for which the gauge freedom in the choice of the potentials remains.

The second part of this chapter studies the two-spinor form of the RaritaSchwinger potentials subject to local boundary conditions compatible with BRST invariance and local supersymmetry. The Rarita-Schwinger field equations are studied in an arbitrary four-real-dimensional Riemannian background with boundary. Gauge transformations on the potentials are shown to be compatible with the field equations providing a set of second-order partial differential equations hold. An equivalent, first-order form of the compatibility conditions is also obtained. The boundary conditions do not restrict severely the choice of background fourgeometries, as it happens in the case of Dirac's potentials with reflective boundary conditions on field strengths. The recent construction by Penrose of secondary potentials which supplement the Rarita-Schwinger potentials is then extended from Ricci-flat space-times to arbitrary curved backgrounds. Remarkably, the traces of such secondary potentials are linearly related to the independent spinor fields appearing in the Rarita-Schwinger equations. The resulting set of equations for these secondary potentials is hence ontained.


## 8. Spin- $\frac{3}{2}$ Potentials

### 8.1 Introduction

Recent work in the literature has studied the quantization of gauge theories and supersymmetric field theories in the presence of boundaries, with application to one-loop quantum cosmology (Moss and Poletti 1990, Poletti 1990, D'Eath and Esposito 1991a-b, Barvinsky et al. 1992a-b, Kamenshchik and Mishakov 1992-93-94, Esposito 1994). In particular, in the work described in Esposito 1994, two possible sets of local boundary conditions were studied. One of these, first proposed in anti-de Sitter space-time (Breitenlohner and Freedman 1982, Hawking 1983), involves the normal to the boundary and Dirichlet or Neumann conditions for spin 0 , the normal and the field for massless spin- $\frac{1}{2}$ fermions, and the normal and totally symmetric field strengths for spins $1, \frac{3}{2}$ and 2 . Although more attention has been paid to alternative local boundary conditions motivated by supersymmetry (as in Poletti 1990, D'Eath and Esposito 1991a, Kamenshchik and Mishakov 199394, Esposito 1994), and studied in our sections 8.5-8.8, the analysis of the former boundary conditions remains of mathematical and physical interest by virtue of its links with twistor theory. The aim of the first part of this chapter is to derive the mathematical properties of the corresponding boundary-value problems, since these are relevant for quantum cosmology and twistor theory.

For this purpose, sections 8.2-8.3 derive the conditions under which spinlowering and spin-raising operators preserve local boundary conditions involving field strengths and normals. Section 8.4 applies the two-spinor form of Dirac spin- $\frac{3}{2}$ potentials to Riemannian four-geometries with a three-sphere boundary. Boundary conditions on spinor-valued one-forms describing gravitino fields are studied in sections 8.5-8.9. Concluding remarks and open problems are presented in section 8.10.

## 8. Spin- $\frac{3}{2}$ Potentials

### 8.2 Spin-Lowering Operators in Cosmology

In section 5.7 of Esposito 1994, a flat Euclidean background bounded by a three-sphere was studied. On the bounding $S^{3}$, the following boundary conditions for a spin-s field were required:

$$
\begin{equation*}
2^{s} e^{A A^{\prime} \ldots e^{L L^{\prime}} \phi_{A \ldots L}=\epsilon \widetilde{\phi}^{A^{\prime} \ldots L^{\prime}}, ~} \tag{8.2.1}
\end{equation*}
$$

With our notation, $e^{n^{A A^{\prime}}}$ is the Euclidean normal to $S^{3}$ (D'Eath and Halliwell 1987, Esposito 1994), $\phi_{A \ldots L}=\phi_{(A \ldots L)}$ and $\widetilde{\boldsymbol{\phi}}_{A^{\prime} \ldots L^{\prime}}=\widetilde{\boldsymbol{\phi}}_{\left(A^{\prime} \ldots L^{\prime}\right)}$ are totally symmetric and independent (i.e. not related by any conjugation) field strengths, which reduce to the massless spin- $\frac{1}{2}$ field for $s=\frac{1}{2}$. Moreover, the complex scalar field $\phi$ is such that its real part obeys Dirichlet conditions on $S^{3}$ and its imaginary part obeys Neumann conditions on $S^{3}$, or the other way around, according to the value of the parameter $e \equiv \pm 1$ occurring in (8.2.1).

In flat Euclidean four-space, we write the solutions of the twistor equations

$$
\begin{align*}
& D_{A^{\prime}}^{(A} \omega^{B)}=0  \tag{8.2.2}\\
& D_{A}^{\left(A^{\prime}\right.} \tilde{\omega}^{\left.B^{\prime}\right)}=0 \tag{8.2.3}
\end{align*}
$$

as (cf. section 4.1)

$$
\begin{gather*}
\omega^{A}=\left(\omega^{o}\right)^{A}-i\left(e^{A A^{\prime}}\right) \pi_{A^{\prime}}^{o}  \tag{8.2.4}\\
\tilde{\omega}^{A^{\prime}}=\left(\tilde{\omega}^{o}\right)^{A^{\prime}}-i\left(e x^{A A^{\prime}}\right) \tilde{\pi}_{A}^{o} \tag{8.2.5}
\end{gather*}
$$

Note that, since unprimed and primed spin-spaces are no longer anti-isomorphic in the case of Riemannian four-metrics, Eq. (8.2.3) is not obtained by complex conjugation of Eq. (8.2.2). Hence the spinor field $\widetilde{\omega}^{B^{\prime}}$ is independent of $\omega^{B}$. This leads to distinct solutions (8.2.4)-(8.2.5), where the spinor fields $\boldsymbol{\omega}_{\boldsymbol{A}}^{\boldsymbol{o}}, \bar{\omega}_{\boldsymbol{A}^{\prime}}^{\boldsymbol{o}}, \widetilde{\pi}_{\boldsymbol{A}}^{\boldsymbol{o}}, \boldsymbol{\pi}_{\boldsymbol{A}^{\prime}}^{\boldsymbol{o}}$ are covariantly constant with respect to the flat connection $D$, whose corresponding spinor covariant derivative is here denoted by $D_{A B^{\prime}}$. The following theorem can be now proved:

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Theorem 8.2.1 Let $\omega^{D}$ be a solution of the twistor equation (8.2.2) in flat Euclidean space with a three-sphere boundary, and let $\widetilde{\boldsymbol{\omega}}^{D^{\prime}}$ be the solution of the independent equation (8.2.3) in the same four-geometry with boundary. Then a form exists of the spin-lowering operator which preserves the local boundary conditions on $S^{3}$ :

$$
\begin{gather*}
4 e n^{A A^{\prime}} e_{e} n^{B B^{\prime}} e n^{C C^{\prime}}{ }_{e} n^{D D^{\prime}} \phi_{A B C D}=\epsilon \widetilde{\phi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}},  \tag{8.2.6}\\
2^{\frac{3}{2}} e^{A A^{\prime}}{ }{ }^{n}{ }^{B B^{\prime}}{ }_{e} n^{C C^{\prime}} \phi_{A B C}=\epsilon \widetilde{\phi}^{A^{\prime} B^{\prime} C^{\prime}} . \tag{8.2.7}
\end{gather*}
$$

Of course, the independent field strengths appearing in (8.2.6)-(8.2.7) are assumed to satisfy the corresponding massless free-field equations.

Proof. Multiplying both sides of (8.2.6) by ${ }_{e} n_{F D^{\prime}}$ one gets

$$
\begin{equation*}
-2 e^{n^{A A^{\prime}}}{ }_{e} n^{B B^{\prime}}{ }_{e} n^{C C^{\prime}} \phi_{A B C F}=\epsilon \widetilde{\phi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}{ }_{\mathrm{e}} n_{F D^{\prime}} . \tag{8.2.8}
\end{equation*}
$$

Taking into account the total symmetry of the field strengths, putting $F=D$ and multiplying both sides of (8.2.8) by $\sqrt{2} \omega^{D}$ one finally gets

$$
\begin{gather*}
-2^{\frac{3}{2}} e n^{A A^{\prime}}{ }_{e} n^{B B^{\prime}}{ }_{e} n^{C C^{\prime}} \phi_{A B C D} \omega^{D}=\epsilon \sqrt{2} \widetilde{\phi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}{ }_{e} n_{D D^{\prime}} \omega^{D},  \tag{8.2.9}\\
2^{\frac{3}{2}} e^{A n^{A A^{\prime}}} e^{B n^{B B^{\prime}}{ }_{e} n^{C C^{\prime}} \phi_{A B C D} \omega^{D}=\epsilon \widetilde{\phi}^{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \widetilde{\omega}_{D^{\prime}},} \tag{8.2.10}
\end{gather*}
$$

where (8.2.10) is obtained by inserting into (8.2.7) the definition of the spinlowering operator. The comparison of (8.2.9) and (8.2.10) yields the preservation condition

In the light of (8.2.4)-(8.2.5), equation (8.2.11) is found to imply

$$
\begin{equation*}
\sqrt{2} \mathrm{e}^{n_{D A^{\prime}}}\left(\omega^{o}\right)^{D}-i \sqrt{2} \mathrm{e}_{D A^{\prime}} \mathrm{e}^{D D^{\prime}}=-\tilde{\omega}_{A^{\prime}}^{o}-i e^{x_{D A^{\prime}}}\left(\tilde{\pi}^{o}\right)^{D} \tag{8.2.12}
\end{equation*}
$$

Requiring that (8.2.12) should be identically satisfied, and using the identity $e^{\boldsymbol{n}^{\boldsymbol{A} \boldsymbol{A}^{\prime}}}=\frac{1}{r} e^{\boldsymbol{x}^{\boldsymbol{A} \boldsymbol{A}^{\prime}}}$ on a three-sphere of radius $r$, one finds

$$
\begin{equation*}
\widetilde{\omega}_{A^{\prime}}^{o}=i \sqrt{2} r_{e} n_{D A^{\prime} e} n^{D D^{\prime}} \pi_{D^{\prime}}^{o}=-\frac{i r}{\sqrt{2}} \pi_{A^{\prime}}^{o} \tag{8.2.13}
\end{equation*}
$$

$$
\begin{gather*}
\text { 8. Spin- } \frac{3}{2} \text { Potentials } \\
-\sqrt{2} e_{e_{D A^{\prime}}}\left(\omega^{o}\right)^{D}=\operatorname{ir}_{e^{n_{D A^{\prime}}}}\left(\tilde{\pi}^{o}\right)^{D} . \tag{8.2.14}
\end{gather*}
$$

Multiplying both sides of (8.2.14) by ${ }_{e} n^{B A^{\prime}}$, and then acting with $e_{B A}$ on both sides of the resulting relation, one gets

$$
\begin{equation*}
\omega_{A}^{o}=-\frac{i r}{\sqrt{2}} \tilde{\pi}_{A}^{o} . \tag{8.2.15}
\end{equation*}
$$

The equations (8.2.11), (8.2.13) and (8.2.15) completely solve the problem of finding a spin-lowering operator which preserves the boundary conditions (8.2.6)(8.2.7) on $S^{3}$. Q.E.D.

If one requires local boundary conditions on $S^{3}$ involving field strengths and normals also for lower spins (i.e. spin $\frac{3}{2}$ vs spin 1 , spin 1 vs spin $\frac{1}{2}$, spin $\frac{1}{2}$ vs spin 0 ), then by using the same technique of the theorem just proved, one finds that the preservation condition obeyed by the spin-lowering operator is still expressed by (8.2.13) and (8.2.15).

### 8.3 Spin-Raising Operators in Cosmology

To derive the corresponding preservation condition for spin-raising operators, we begin by studying the relation between spin- $\frac{1}{2}$ and spin- 1 fields. In this case, the independent spin-l field strengths take the form (Penrose and Rindler 1986)

$$
\begin{gather*}
\psi_{A B}=i \widetilde{\omega}^{L^{\prime}}\left(D_{B L^{\prime}} \chi_{A}\right)-2 \chi_{(A} \tilde{\pi}_{B)}^{o}  \tag{8.3.1}\\
\tilde{\psi}_{A^{\prime} B^{\prime}}=-i \omega^{L}\left(D_{L B^{\prime}} \tilde{\chi}_{A^{\prime}}\right)-2 \tilde{\chi}_{\left(A^{\prime}\right.} \pi_{\left.B^{\prime}\right)}^{o} \tag{8.3.2}
\end{gather*}
$$

where the independent spinor fields $\left(\chi_{A}, \widetilde{\chi}_{A^{\prime}}\right)$ represent a massless spin- $\frac{1}{2}$ field obeying the Weyl equations on flat Euclidean four-space and subject to the boundary conditions

$$
\begin{equation*}
\sqrt{2} e^{n^{A A^{\prime}}} \chi_{A}=\epsilon \tilde{\chi}^{A^{\prime}} \tag{8.3.3}
\end{equation*}
$$

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on a three-sphere of radius $r$. Thus, by requiring that (8.3.1) and (8.3.2) should obey (8.2.1) on $S^{3}$ with $s=1$, and bearing in mind (8.3.3), one finds

$$
\begin{align*}
2 \epsilon\left[\sqrt{2} \tilde{\pi}_{A}^{o} \tilde{\chi}^{\left(A^{\prime}\right.} e^{\left.A B^{\prime}\right)}-\tilde{\chi}^{\left(A^{\prime}\right.} \pi^{\left.o B^{\prime}\right)}\right] & =i\left[2 e^{A A^{\prime}} e^{B B^{\prime}} \tilde{\omega}^{L^{\prime}} D_{L^{\prime}(B} \chi_{A)}\right. \\
& \left.+\epsilon \omega^{L} D_{L}^{\left(B^{\prime}\right.} \tilde{\chi}^{\left.A^{\prime}\right)}\right] \tag{8.3.4}
\end{align*}
$$

on the bounding $S^{3}$. It is now clear how to carry out the calculation for higher spins. Denoting by $s$ the spin obtained by spin-raising, and defining $n \equiv 2 s$, one finds

$$
\begin{align*}
& n \epsilon\left[\sqrt{2} \tilde{\pi}_{A}^{o} e^{A\left(A^{\prime}\right.} \tilde{\chi}^{\left.B^{\prime} \ldots K^{\prime}\right)}-\tilde{\chi}^{\left(A^{\prime} \ldots D^{\prime}\right.} \pi^{\left.o K^{\prime}\right)}\right] \\
& =i\left[2^{\frac{\pi}{2}} e n^{A A^{\prime} \ldots e} n^{K K^{\prime}} \tilde{\omega}^{L^{\prime}} D_{L^{\prime}(K} \chi_{A \ldots D)}+\epsilon \omega^{L} D_{L}{ }^{\left(K^{\prime}\right.} \tilde{\chi}^{\left.A^{\prime} \ldots D^{\prime}\right)}\right] \tag{8.3.5}
\end{align*}
$$

on the three-sphere boundary. In the comparison spin-0 vs spin- $\frac{1}{2}$, the preservation condition is not obviously obtained from (8.3.5). The desired result is here found by applying the spin-raising operators to the independent scalar fields $\phi$ and $\widetilde{\phi}$ (see below) and bearing in mind (8.2.4)-(8.2.5) and the boundary conditions

$$
\begin{gather*}
\phi=\epsilon \bar{\phi} \text { on } S^{3},  \tag{8.3.6}\\
e^{n^{A A^{\prime}} D_{A A^{\prime}} \phi}=-\epsilon_{e} n^{B B^{\prime}} D_{B B^{\prime}} \tilde{\phi} \text { on } S^{3} \tag{8.3.7}
\end{gather*}
$$

This leads to the following condition on $S^{3}$ (cf. equation (5.7.23) of Esposito 1994):

$$
\begin{align*}
0 & =i \phi\left[\frac{\tilde{\pi}_{A}^{o}}{\sqrt{2}}-\pi_{A^{\prime} e^{o} n_{A} A^{\prime}}\right]-\left[\frac{\tilde{\omega}^{K^{\prime}}}{\sqrt{2}}\left(D_{A K^{\prime}} \phi\right)-\frac{\omega_{A}}{2} e_{C} n_{C}^{K^{\prime}}\left(D_{K^{\prime}}^{C} \phi\right)\right] \\
& +\epsilon_{e} n_{\left(A^{A^{\prime}}\right.} \omega^{B} D_{B) A^{\prime}} \tilde{\phi} . \tag{8.3.8}
\end{align*}
$$

Note that, while the preservation conditions (8.2.13) and (8.2.15) for spin-lowering operators are purely algebraic, the preservation conditions (8.3.5) and (8.3.8) for spin-raising operators are more complicated, since they also involve the value at the boundary of four-dimensional covariant derivatives of spinor fields or scalar

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fields. Two independent scalar fields have been introduced, since the spinor fields obtained by applying the spin-raising operators to $\phi$ and $\widetilde{\phi}$ respectively are independent as well in our case.

### 8.4 Dirac's Spin $\frac{3}{2}$ Potentials in Cosmology

In this section we focus on the totally symmetric field strengths $\phi_{A B C}$ and $\widetilde{\phi}_{A^{\prime} B^{\prime} C^{\prime}}$ for spin- $\frac{3}{2}$ fields, and we express them in terms of their potentials, rather than using spin-raising (or spin-lowering) operators. The corresponding theory in Minkowski space-time (and curved space-time) is described in Penrose 1990, Penrose 1991a-b-c, and adapted here to the case of flat Euclidean four-space with flat connection $D$. It turns out that $\tilde{\phi}_{A^{\prime} B^{\prime} C^{\prime}}$ can then be obtained locally from two potentials defined as follows. The first potential satisfies the properties (section 5.3, Penrose 1990, Penrose 1991a-b-c, Esposito and Pollifrone 1994)

$$
\begin{gather*}
\gamma_{A^{\prime} B^{\prime}}^{C}=\gamma_{\left(A^{\prime} B^{\prime}\right)}^{C},  \tag{8.4.1}\\
D^{A A^{\prime}} \gamma_{A^{\prime} B^{\prime}}^{C}=0,  \tag{8.4.2}\\
\widetilde{\phi}_{A^{\prime} B^{\prime} C^{\prime}}^{C}=D_{C C^{\prime}} \gamma_{A^{\prime} B^{\prime}}^{C}, \tag{8.4.3}
\end{gather*}
$$

with the gauge freedom of replacing it by

$$
\begin{equation*}
\widehat{\gamma}_{A^{\prime} B^{\prime}}^{C} \equiv \gamma_{A^{\prime} B^{\prime}}^{C}+D_{B^{\prime}}^{C} \widetilde{\nu}_{A^{\prime}} \tag{8.4.4}
\end{equation*}
$$

where $\boldsymbol{\nu}_{A^{\prime}}$ satisfies the positive-helicity Weyl equation

$$
\begin{equation*}
D^{A A^{\prime}} \tilde{\nu}_{A^{\prime}}=0 \tag{8.4.5}
\end{equation*}
$$

The second potential is defined by the conditions

$$
\begin{equation*}
\rho_{A^{\prime}}^{B C}=\rho_{A^{\prime}}^{(B C)} \tag{8.4.6}
\end{equation*}
$$

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$$
\begin{gather*}
D^{A A^{\prime}} \rho_{A^{\prime}}^{B C}=0,  \tag{8.4.7}\\
\gamma_{A^{\prime} B^{\prime}}^{C}=D_{B B^{\prime}} \rho_{A^{\prime}}^{B C} \tag{8.4.8}
\end{gather*}
$$

with the gauge freedom of being replaced by

$$
\begin{equation*}
\hat{\rho}_{A^{\prime}}^{B C} \equiv \rho_{A^{\prime}}^{B C}+D_{A^{\prime}}^{C} \chi^{B}, \tag{8.4.9}
\end{equation*}
$$

where $\chi^{B}$ satisfies the negative-helicity Weyl equation

$$
\begin{equation*}
D_{B B^{\prime}} \chi^{B}=0 \tag{8.4.10}
\end{equation*}
$$

Moreover, in flat Euclidean four-space the field strength $\phi_{A B C}$ is expressed locally in terms of the potential $\Gamma_{A B}^{\prime}=\Gamma_{(A B)}^{C^{\prime}}$, independent of $\gamma_{A^{\prime} B^{\prime}}^{C}$, as

$$
\begin{equation*}
\phi_{A B C}=D_{C C}, \Gamma_{A B}^{C^{\prime}}, \tag{8.4.11}
\end{equation*}
$$

with gauge freedom

$$
\begin{equation*}
\widehat{\Gamma}_{A B}^{C_{B}^{\prime}} \equiv \Gamma_{A B}^{C_{B}^{\prime}}+D_{B}^{C_{B}^{\prime}} \nu_{A} . \tag{8.4.12}
\end{equation*}
$$

Thus, if we insert (8.4.3) and (8.4.11) into the boundary conditions (8.2.1) with $s=\frac{3}{2}$, and require that also the gauge-equivalent potentials (8.4.4) and (8.4.12) should obey such boundary conditions on $S^{3}$, we find that

$$
\begin{equation*}
\underline{2}^{\frac{3}{2}} e^{n^{A}}{ }_{A^{\prime} e^{\prime}} n_{B^{\prime} e^{B}} n_{C^{\prime}}^{C} D_{C L^{\prime}} D_{B}^{L^{\prime}} \nu_{A}=\epsilon D_{L C^{\prime}} D_{B^{\prime}}^{L} \widetilde{\nu}_{A^{\prime}} \tag{8.4.13}
\end{equation*}
$$

on the three-sphere. Note that, from now on (as already done in (8.3.5) and (8.3.8)), covariant derivatives appearing in boundary conditions are first taken on the background and then evaluated on $S^{3}$. In the case of our flat background, (8.4.13) is identically satisfied since $D_{C L^{\prime}} D_{B}^{L^{\prime}} \nu_{A}$ and $D_{L C^{\prime}} D_{B^{\prime}}^{L} \widetilde{\nu}_{A^{\prime}}$ vanish by virtue of spinor Ricci identities. In a curved background, however, denoting by $\nabla$ its curved connection, and defining $\square_{A B} \equiv \nabla_{M^{\prime}(\boldsymbol{A}} \nabla_{B)}^{M_{B}^{\prime}}, \square_{\boldsymbol{A}^{\prime} \boldsymbol{B}^{\prime}} \equiv$ $\boldsymbol{\nabla}_{\boldsymbol{X}\left(\boldsymbol{A}^{\prime}\right.} \boldsymbol{\nabla}_{\left.\boldsymbol{B}^{\prime}\right)}$, since the spinor Ricci identities we need are (Ward and Wells 1990)

$$
\begin{equation*}
\square_{A B} \nu_{C}=\psi_{A B D C} \nu^{D}-2 \Lambda \nu_{(A} \epsilon_{B) C} \tag{8.4.14}
\end{equation*}
$$

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$$
\begin{equation*}
\square_{A^{\prime} B^{\prime}} \widetilde{\nu}_{C^{\prime}}=\widetilde{\psi}_{A^{\prime} B^{\prime} D^{\prime} C^{\prime}} \widetilde{\nu}^{D^{\prime}}-2 \tilde{\Lambda} \widetilde{\nu}_{\left(A^{\prime}\right.} \epsilon_{\left.B^{\prime}\right) C^{\prime}}, \tag{8.4.15}
\end{equation*}
$$

one finds that the corresponding boundary conditions

$$
\begin{equation*}
2^{\frac{3}{2}}{ }_{e} n_{A^{\prime}}^{A} e^{B} B_{B^{\prime}}{ }_{e} n_{C^{\prime}}^{C} \nabla_{C L^{\prime}} \nabla_{L_{B}^{\prime}}^{L_{B}} \nu_{A}=\epsilon \nabla_{L C^{\prime}} \nabla_{B^{\prime}}^{L} \tilde{\nu}_{A^{\prime}} \tag{8.4.16}
\end{equation*}
$$

are identically satisfied if and only if one of the following conditions holds: (i) $v_{A}=\widetilde{\boldsymbol{\nu}}_{A^{\prime}}=0$; (ii) the Weyl spinors $\boldsymbol{\psi}_{A B C D}, \widetilde{\boldsymbol{\psi}}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}$ and the scalars $\boldsymbol{\Lambda}, \tilde{\boldsymbol{\Lambda}}$ vanish everywhere. However, since in a curved space-time with vanishing $\Lambda, \tilde{\Lambda}$, the potentials with the gauge freedoms (8.4.4) and (8.4.12) only exist provided $D$ is replaced by $\nabla$ and the trace-free part $\boldsymbol{\Phi}_{a b}$ of the Ricci tensor vanishes as well (Buchdahl 1958), the background four-geometry is actually flat Euclidean fourspace. Note that we require that (8.4.16) should be identically satisfied to avoid, after a gauge transformation, obtaining more boundary conditions than the ones originally imposed. The curvature of the background should not, itself, be subject to a boundary condition.

The same result can be derived by using the potential $\rho_{A^{\prime}}^{B C}$ and its independent counterpart $\boldsymbol{\Lambda}_{\boldsymbol{A}}^{\boldsymbol{B}^{\prime} C^{\prime}}$. This spinor field yields the $\boldsymbol{\Gamma}_{\boldsymbol{A} \boldsymbol{B}}^{\boldsymbol{C}^{\prime}}$ potential by means of

$$
\begin{equation*}
\Gamma_{A B}^{C^{\prime}}=D_{B B} \Lambda_{A}^{B^{\prime} C^{\prime}} \tag{8.4.17}
\end{equation*}
$$

and has the gauge freedom

$$
\begin{equation*}
\widehat{\Lambda}_{A}^{B^{\prime} C^{\prime}} \equiv \Lambda_{A}^{B^{\prime} C^{\prime}}+D_{A}^{C^{\prime}} \widetilde{\chi}^{B^{\prime}}, \tag{8.4.18}
\end{equation*}
$$

where $\tilde{\chi}^{B^{\prime}}$ satisfies the positive-helicity Weyl equation

$$
\begin{equation*}
D_{B F^{\prime}} \tilde{\chi}^{F^{\prime}}=0 \tag{8.4.19}
\end{equation*}
$$

Thus, if also the gauge-equivalent potentials (8.4.9) and (8.4.18) have to satisfy the boundary conditions (8.2.1) on $S^{3}$, one finds

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on the three-sphere. In our flat background, covariant derivatives commute, hence (8.4.20) is identically satisfied by virtue of (8.4.10) and (8.4.19). However, in the curved case the boundary conditions (8.4.20) are replaced by

$$
\begin{equation*}
2^{\frac{3}{2}} e_{e} n_{A^{\prime}} e n_{B^{\prime}}^{B} e^{C} n_{C^{\prime}} \nabla_{C L^{\prime}} \nabla_{B F^{\prime}} \nabla_{A}^{L^{\prime}} \tilde{\chi}^{F^{\prime}}=\epsilon \nabla_{L C^{\prime}} \nabla_{M B^{\prime}} \nabla_{A^{\prime}}^{L} \chi^{M} \tag{8.4.21}
\end{equation*}
$$

on $S^{3}$, if the local expressions of $\phi_{A B C}$ and $\widetilde{\phi}_{A^{\prime} B^{\prime} C^{\prime}}$ in terms of potentials still hold (Penrose 1990, Penrose 1991a-b-c). By virtue of (8.4.14)-(8.4.15), where $v_{C}$ is replaced by $\chi_{C}$ and $\tilde{\boldsymbol{\nu}}_{C^{\prime}}$ is replaced by $\tilde{\chi}_{C^{\prime}}$, this means that the Weyl spinors $\psi_{A B C D}, \widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}$ and the scalars $\Lambda, \tilde{\Lambda}$ should vanish, since one should find

$$
\begin{equation*}
\nabla^{A A^{\prime}} \hat{\rho}_{A^{\prime}}^{B C}=0 \quad, \quad \nabla^{A A^{\prime}} \hat{\Lambda}_{A}^{B^{\prime} C^{\prime}}=0 \tag{8.4.22}
\end{equation*}
$$

If we assume that $\nabla_{B F^{\prime}} \tilde{\boldsymbol{\chi}}^{F^{\prime}}=0$ and $\nabla_{M B^{\prime}} \quad \chi^{M}=0$, we have to show that (8.4.21) differs from (8.4.20) by terms involving a part of the curvature that is vanishing everywhere. This is proved by using the basic rules of two-spinor calculus and spinor Ricci identities. Thus, bearing in mind that

$$
\begin{align*}
& \square^{A B} \bar{\chi}_{B^{\prime}}=\Phi_{L^{\prime} B^{\prime}}^{A B} \widetilde{\chi}^{L^{\prime}}  \tag{8.4.23}\\
& \square^{A^{\prime} B^{\prime}} \chi_{B}=\widetilde{\Phi}_{A_{B}^{\prime} B^{\prime}} \chi^{L} \tag{8.4.24}
\end{align*}
$$

one finds

$$
\begin{align*}
\nabla^{B B^{\prime}} \nabla^{C A^{\prime}} \chi_{B} & =\nabla^{\left(B B^{\prime}\right.} \nabla^{C) A^{\prime}} \chi_{B}+\nabla^{\left[B B^{\prime}\right.} \nabla^{C] A^{\prime}} \chi_{B} \\
& =-\frac{1}{2} \nabla_{B}^{B^{\prime}} \nabla^{C A^{\prime}} \chi^{B}+\frac{1}{2} \widetilde{\Phi}^{A^{\prime} B^{\prime} L C} \chi_{L} \tag{8.4.25}
\end{align*}
$$

Thus, if $\tilde{\boldsymbol{\Phi}}^{A^{\prime} B^{\prime} L C}$ vanishes, also the left-hand side of (8.4.25) has to vanish since this leads to the equation $\nabla^{\boldsymbol{B} \boldsymbol{B}^{\prime}} \nabla^{\boldsymbol{C} \boldsymbol{A}^{\prime}} \chi_{\boldsymbol{B}}=\frac{1}{2} \nabla^{\boldsymbol{B} \boldsymbol{B}^{\prime}} \nabla^{\boldsymbol{C} \boldsymbol{A}^{\prime}} \chi_{\boldsymbol{B}}$. Hence (8.4.25) is identically satisfied. Similarly, the left-hand side of (8.4.21) can be made to vanish identically provided the additional condition $\Phi^{C D F^{\prime} M^{\prime}}=0$ holds. The conditions

$$
\begin{equation*}
\Phi^{C D F^{\prime} M^{\prime}}=0 \quad, \quad \tilde{\Phi}^{A^{\prime} B^{\prime} C L}=0 \tag{8.4.26}
\end{equation*}
$$

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when combined with the conditions

$$
\begin{equation*}
\psi_{A B C D}=\tilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}=0 \quad, \quad \Lambda=\tilde{\Lambda}=0 \tag{8.4.27}
\end{equation*}
$$

arising from (8.4.22) for the local existence of $\rho_{A^{\prime}}^{B}{ }^{C}$ and $\Lambda_{A}^{B^{\prime} C^{\prime}}$ potentials, imply that the whole Riemann curvature should vanish. Hence, in the boundary-value problems we are interested in, the only admissible background four-geometry (of the Einstein type (Besse 1987)) is flat Euclidean four-space.

Note that (8.4.25) is not an identity, since we have already set $\Lambda$ to zero by requiring that

$$
\begin{equation*}
\nabla^{A A^{\prime}} \hat{\rho}_{A^{\prime}}^{B C}=-\psi_{F}^{A B C} \chi^{F}+\Lambda\left(\chi^{A} \epsilon^{C B}+3 \chi^{B} \epsilon^{A C}+\chi^{C} \epsilon^{A B}\right) \tag{8.4.28}
\end{equation*}
$$

should vanish. In general, for any solution $\chi_{B}$ of the Weyl equation, by virtue of the corresponding identity $\square \chi_{B}=-6 \Lambda \chi_{B}$ (see problem 2.7), one finds

$$
\begin{equation*}
\nabla^{B B^{\prime}} \nabla^{C A^{\prime}} \chi_{B}=\frac{1}{2} \nabla^{B B^{\prime}} \nabla^{C A^{\prime}} \chi_{B}+\frac{1}{2} \tilde{\Phi}^{A^{\prime} B^{\prime} L C} \chi_{L}+\frac{3}{2} \Lambda \epsilon^{B^{\prime} A^{\prime}} \chi^{C} . \tag{8.4.29}
\end{equation*}
$$

As the reader may check, the action of the $\square \equiv \nabla_{C A}{ }^{\prime} \nabla^{\text {CA' }}$ operator on $\chi_{B}$ is obtained by acting with the spinor covariant derivative $\nabla_{A A^{\prime}}$ on the Weyl equation $\nabla{ }_{B}^{A^{\prime}} X^{B}=0$.

### 8.5 Boundary Conditions in Supergravity

The boundary conditions studied in the previous sections are not appropriate if one studies supergravity multiplets and supersymmetry transformations at the boundary (Esposito 1994). By contrast, it turns out one has to impose another set of locally supersymmetric boundary conditions, first proposed in Luckock and Moss 1989. These are in general mixed, and involve in particular Dirichlet conditions for the transverse modes of the vector potential of electromagnetism, a mixture of Dirichlet and Neumann conditions for scalar fields, and local boundary conditions

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for the spin- $\frac{1}{2}$ field and the spin- $\frac{3}{2}$ potential. Using two-component spinor notation for supergravity (D'Eath 1984), the spin- $\frac{3}{2}$ boundary conditions take the form

$$
\begin{equation*}
\sqrt{2}{ }_{e} n_{A}^{A^{\prime}} \psi_{i}^{A}=\epsilon \widetilde{\psi}_{i}^{A^{\prime}} \quad \text { on } \quad S^{3} \tag{8.5.1}
\end{equation*}
$$

With our notation, $\in \equiv \pm 1, e_{A}^{A^{\prime}}$ is the Euclidean normal to $S^{3}$, and $\left(\psi_{i}^{\boldsymbol{A}}, \widetilde{\psi}_{i}^{\boldsymbol{A}^{\prime}}\right)$ are the independent (i.e. not related by any conjugation) spatial components (hence $i=1,2,3$ ) of the spinor-valued one-forms appearing in the action functional of Euclidean supergravity (D'Eath 1984, Esposito 1994).

It appears necessary to understand whether the analysis in the previous section and in Esposito and Pollifrone 1994 can be used to derive restrictions on the classical boundary-value problem corresponding to (8.5.1). For this purpose, we study a Riemannian background four-geometry, and we use the decompositions of the spinor-valued one-forms in such a background, i.e.

$$
\begin{align*}
& \psi_{i}^{A}=h^{-\frac{1}{4}}\left[\chi^{(A B) B^{\prime}}+\epsilon^{A B} \tilde{\phi}^{B^{\prime}}\right] e_{B B^{\prime} i}  \tag{8.5.2}\\
& \widetilde{\psi}_{i}^{A^{\prime}}=h^{-\frac{1}{4}}\left[\tilde{\chi}^{\left(A^{\prime} B^{\prime}\right) B}+\epsilon^{A^{\prime} B^{\prime}} \phi^{B}\right] e_{B B^{\prime} i} \tag{8.5.3}
\end{align*}
$$

where $h$ is the determinant of the three-metric on $S^{3}$, and $e_{B B^{\prime} i}$ is the spatial component of the tetrad, written in two-spinor language. If we now reduce the classical theory of simple supergravity to its physical degrees of freedom by imposing the gauge conditions (Esposito 1994)

$$
\begin{align*}
& e_{A A^{\prime}}^{i} \psi_{i}^{A}=0  \tag{8.5.4}\\
& e_{A A^{\prime}}^{i} \widetilde{\psi}_{i}^{A_{i}^{\prime}}=0 \tag{8.5.5}
\end{align*}
$$

we find that the expansions of (8.5.2)-(8.5.3) on a family of three-spheres centred on the origin take the forms (Esposito 1994)

$$
\begin{equation*}
\psi_{i}^{A}=\frac{h^{-\frac{1}{4}}}{2 \pi} \sum_{n=0}^{\infty} \sum_{p, q=1}^{(n+1)(n+4)} \alpha_{n}^{p q}\left[m_{n p}^{(\beta)}(\tau) \beta^{n q A B B^{\prime}}+\widetilde{r}_{n p}^{(\mu)}(\tau) \bar{\mu}^{n q A B B^{\prime}}\right] e_{B B^{\prime} i} \tag{8.5.6}
\end{equation*}
$$

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$$
\begin{equation*}
\widetilde{\psi}_{i}^{A^{\prime}}=\frac{h^{-\frac{1}{4}}}{2 \pi} \sum_{n=0}^{\infty} \sum_{p, \alpha-1}^{(n+1)(n+4)} \alpha_{n}^{p q}\left[\tilde{m}_{n p}^{(\beta)}(\tau) \bar{\beta}^{n q A^{\prime} B^{\prime} B}+r_{r p}^{(\mu)}(\tau) \mu^{n q A^{\prime} B^{\prime} B}\right] e_{B B^{\prime} i} \tag{8.5.7}
\end{equation*}
$$

With our notation, $\alpha_{n}^{p q}$ are block-diagonal matrices with blocks $\left(\begin{array}{cc}1 & 1 \\ 1 & -1\end{array}\right)$, and the $\beta$ - and $\mu$-harmonics on $S^{3}$ are given by (Esposito 1994)

$$
\begin{gather*}
\beta_{A C C^{\prime}}^{n q}=\rho_{(A C D)}^{n q} n_{C^{\prime}}^{D}  \tag{8.5.8}\\
\mu_{A^{\prime} B^{\prime} B}^{n q}=\sigma_{\left(A^{\prime} B^{\prime} C^{\prime}\right)}^{n q} n_{B}^{C^{\prime}} \tag{8.5.9}
\end{gather*}
$$

In the light of (8.5.6)-(8.5.9), one gets the following physical-degrees-of-freedom form of the spinor-valued one-forms of supergravity (cf. D'Eath 1984):

$$
\begin{gather*}
\psi_{i}^{A}=h^{-\frac{1}{4}} \phi^{(A B C)} e_{C} n_{C}^{B^{\prime}} e_{B B^{\prime} i}  \tag{8.5.10}\\
\tilde{\psi}_{i}^{A^{\prime}}=h^{-\frac{1}{4}} \widetilde{\phi}^{\left(A^{\prime} B^{\prime} C^{\prime}\right)} e^{n^{B}} C_{C^{\prime}} e_{B B^{\prime} i} \tag{8.5.11}
\end{gather*}
$$

where $\phi^{(A B C)}$ and $\bar{\phi}^{\left(A^{\prime} B^{\prime} C^{\prime}\right)}$ are totally symmetric and independent spinor fields.
Within this framework, a sufficient condition for the validity of the boundary conditions (8.5.1) on $S^{3}$ is

$$
\begin{equation*}
\sqrt{2} e_{e} n_{A}^{A^{\prime}} e^{n_{C}}{ }^{B^{\prime}} \phi^{(A B C)}=\epsilon_{e} n_{C^{\prime}}^{B} \widetilde{\phi}^{\left(A^{\prime} B^{\prime} C^{\prime}\right)} \tag{8.5.12}
\end{equation*}
$$

However, our construction does not prove that such $\phi^{(A B C)}$ and $\widetilde{\phi}^{\left(A^{\prime} B^{\prime} C\right)}$ are solutions of massless free-field equations, and hence it is unclear whether one can try to express them in terms of four potentials as in Esposito and Pollifrone 1994.

It should be emphasized that our analysis, although motivated by quantum cosmology, is entirely classical. Hence we have not discussed ghost modes. The theory has been reduced to its physical degrees of freedom to make a comparison with the results in Esposito and Pollifrone 1994, but totally symmetric field strengths do not enable one to recover the full physical content of simple supergravity. Hence the four-sphere background studied in Poletti 1990 is not ruled out by the work in this section, and a more careful analysis is in order.

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### 8.6 Rarita-Schwinger Potentials and Their Gauge Transformations

For the reasons described in section 8.5 , we are here interested in the independent spatial components $\left(\psi_{i}^{A}, \widetilde{\boldsymbol{H}_{i}^{\prime}}\right)$ of the gravitino field in Riemannian backgrounds. In terms of the spatial components $e_{A B^{\prime} i}$ of the tetrad, and of spinor fields, they can be expressed as

$$
\begin{gather*}
\psi_{A i}=\Gamma_{A B}^{C^{\prime}} e_{C^{\prime} i}^{B}  \tag{8.6.1}\\
\widetilde{\psi}_{A^{\prime} i}=\gamma_{A^{\prime} B^{\prime}}^{C} e_{C}^{B^{\prime}} \tag{8.6.2}
\end{gather*}
$$

A first important difference with respect to the problem studied in Esposito and Pollifrone 1994 is that the spinor fields $\Gamma^{C^{\prime}}{ }_{A B}$ and $\gamma_{A^{\prime} B^{\prime}}$ are no longer symmetric in the second and third index. From now on, they will be referred to as spin- $\frac{3}{2}$ potentials. They obey the differential equations (see appendix B and cf. Aichelburg and Urbantke 1981, Penrose 1991a-b-c)

$$
\begin{gather*}
\epsilon^{B^{\prime} C^{\prime}} \nabla_{A\left(A^{\prime}\right.} \gamma_{\left.B^{\prime}\right) C^{\prime}}=-3 \Lambda \tilde{\alpha}_{A^{\prime}},  \tag{8.6.3}\\
\nabla^{B^{\prime}(B} \gamma_{B^{\prime} C^{\prime}}^{A)}=\Phi^{A B L^{\prime}} \tilde{C}^{\prime} \tilde{\alpha}_{L^{\prime}},  \tag{8.6.4}\\
\epsilon^{B C} \nabla_{A^{\prime}(A} \Gamma_{B) C}^{A^{\prime}}=-3 \Lambda \alpha_{A}  \tag{8.6.5}\\
\nabla^{B\left(B^{\prime}\right.} \Gamma_{B C}^{\left.A^{\prime}\right)}=\widetilde{\Phi}^{A^{\prime} B^{\prime} L} \alpha_{L} \tag{8.6.6}
\end{gather*}
$$

where $\nabla_{A B^{\prime}}$ is the spinor covariant derivative corresponding to the curved connection $\nabla$ of the background, and $\alpha_{A}, \widetilde{\boldsymbol{\alpha}}_{A^{\prime}}$ are a pair of independent spinor fields, corresponding to the Majorana field of the Lorentzian regime. Moreover, the potentials are subject to the gauge transformations (cf. Penrose 1991b-c)

$$
\begin{gather*}
\widehat{\gamma}_{B^{\prime} C^{\prime}}^{A}=\gamma_{B^{\prime} C^{\prime}}^{A}+\nabla_{C^{\prime}}^{A} \lambda_{B^{\prime}}  \tag{8.6.7}\\
\widehat{\Gamma}_{B C}^{A^{\prime}}=\Gamma_{B C}^{A^{\prime}}+\nabla_{C}^{A^{\prime}} \nu_{B} \tag{8.6.8}
\end{gather*}
$$

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A second important difference with respect to the analysis in Esposito and Pollifrone 1994 is that the spinor fields $v_{B}$ and $\lambda_{B^{\prime}}$ are no longer taken to be solutions of the Weyl equation.

### 8.7 Compatibility Conditions

Our task is now to derive compatibility conditions, by requiring that equations (8.6.3)-(8.6.6) should also be satisfied by the gauge-transformed potentials appearing on the left-hand side of equations (8.6.7)-(8.6.8). For this purpose, after defining the operators

$$
\begin{align*}
& \square_{A B} \equiv \nabla_{M^{\prime}(A} \nabla_{B)}^{M^{\prime}}  \tag{8.7.1}\\
& \square_{A^{\prime} B^{\prime}} \equiv \nabla_{F\left(A^{\prime}\right.} \nabla_{\left.B^{\prime}\right)}^{F} \tag{8.7.2}
\end{align*}
$$

we need the standard identity

$$
\begin{equation*}
\Omega_{[A B]}=\frac{1}{2} \epsilon_{A B} \Omega_{C}^{C} \tag{8.7.3}
\end{equation*}
$$

and the spinor Ricci identities (section 8.4)

$$
\begin{gather*}
\square_{A B} \nu_{C}=\psi_{A B C D} \nu^{D}-2 \Lambda \nu_{(A} \epsilon_{B) C}  \tag{8.7.4}\\
\square_{A^{\prime} B^{\prime}} \lambda_{C^{\prime}}=\widetilde{\psi}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}} \lambda^{D^{\prime}}-2 \tilde{\Lambda} \lambda_{\left(A^{\prime} \epsilon_{\left.B^{\prime}\right) C^{\prime}}\right.},  \tag{8.7.5}\\
\square^{A B} \lambda_{B^{\prime}}=\Phi_{M^{\prime} B^{\prime}}^{A B} \lambda^{M^{\prime}}  \tag{8.7.6}\\
\square^{A^{\prime} B^{\prime}} \nu_{B}=\widetilde{\Phi}_{A^{\prime} B_{B}^{\prime}}^{\prime} \nu^{M} \tag{8.7.7}
\end{gather*}
$$

Thus, on using the equations (8.6.3)-(8.6.8) and (8.7.1)-(8.7.7), the basic rules of two-spinor calculus lead to the compatibility equations (hereafter $\square \equiv$ $\left.\nabla_{C F^{\prime}} \nabla^{C F^{\prime}}\right)$

$$
\begin{equation*}
\square \lambda_{A^{\prime}}=-2 \widetilde{\Lambda} \lambda_{A^{\prime}} \tag{8.7.8}
\end{equation*}
$$

## 8. Spin- $\frac{3}{2}$ Potentials

$$
\begin{gather*}
\nabla^{\left(A \left(B^{\prime}\right.\right.} \nabla^{\left.\left.C^{\prime}\right) B\right)} \lambda_{B^{\prime}}=\frac{1}{2} \Phi^{A B}{ }_{M}^{\prime} C^{\prime} \lambda^{M^{\prime}},  \tag{8.7.9}\\
\square \nu_{A}=-2 \Lambda \nu_{A},  \tag{8.7.10}\\
\nabla^{\left(A^{\prime}(B\right.} \nabla^{\left.C) B^{\prime}\right)} \nu_{B}=\frac{1}{2} \tilde{\Phi}^{A^{\prime} B_{M}^{\prime} C} \nu^{M}, \tag{8.7.11}
\end{gather*}
$$

on the background four-geometry. Moreover, we have to require that the gauge transformations (8.6.7)-(8.6.8) should not lead to boundary conditions on the curvature of the background (cf. Esposito and Pollifrone 1994). The boundary conditions on $S^{3}$ resulting from (8.6.7)-(8.6.8) are

$$
\begin{equation*}
\sqrt{2} \mathrm{e} n_{A}^{A^{\prime}}\left(\nabla^{B B^{\prime}} \nu^{A}\right) e_{B B^{\prime} i}=\epsilon\left(\nabla^{B B^{\prime}} \lambda^{A^{\prime}}\right) e_{B B^{\prime} i} . \tag{8.7.12}
\end{equation*}
$$

### 8.8 Admissible Background Four-Geometries

The system of equations (8.7.8)-(8.7.11), despite its elegance, is very complicated. One can, however, obtain an equivalent system which only involves first-order covariant derivatives. For this purpose, we point out that, since $\lambda_{A^{\prime}}$ is not a solution of the Weyl equation, a (sufficiently smooth) non-vanishing spinor fiel $d \phi^{A}$ exists such that

$$
\begin{equation*}
\nabla^{A A^{\prime}} \lambda_{A^{\prime}} \equiv \phi^{A} \tag{8.8.1}
\end{equation*}
$$

By virtue of (8.7.5), (8.7.8) and of the reality condition $\Lambda=\widetilde{\Lambda}$ one thus finds

$$
\begin{equation*}
\nabla_{A B^{\prime}} \phi^{A}=-\square_{B^{\prime} A^{\prime}} \lambda^{A^{\prime}}-\frac{1}{2} \epsilon_{B^{\prime} A^{\prime}} \square \lambda^{A^{\prime}}=2 \Lambda \lambda_{B^{\prime}} \tag{8.8.2}
\end{equation*}
$$

Moreover, after writing down explicitly the four terms on the left-hand side of (8.7.9), the application of (8.7.6), (8.8.1) and of the identity

$$
\begin{equation*}
\nabla_{B E^{\prime}} \nabla_{C F^{\prime}}-\nabla_{C F^{\prime}} \nabla_{B E^{\prime}}=\epsilon_{B C} \square_{E^{\prime} F^{\prime}}+\epsilon_{E^{\prime} F^{\prime}} \square_{B C}, \tag{8.8.3}
\end{equation*}
$$

## 8. Spin- $-\frac{3}{2}$ Potentials

enables one to write (8.7.9) as

$$
\begin{equation*}
\nabla^{\left(A C^{\prime}\right.} \phi^{B)}=\frac{1}{2 \Lambda} \Phi^{A B} L^{\prime} C^{\prime} \nabla_{M}{ }^{L^{\prime}} \phi^{M} \tag{8.8.4}
\end{equation*}
$$

After solving for $\phi^{B}$ this first-order equation, the spinor field appearing in the gauge freedom of the Rarita-Schwinger potential is then obtained from equation (8.8.2) as

$$
\begin{equation*}
\lambda_{B^{\prime}}=\frac{1}{2 \Lambda} \nabla_{A B^{\prime}} \phi^{A} \tag{8.8.5}
\end{equation*}
$$

Note that, to avoid having a spinor field $\lambda_{B^{\prime}}$ solving the Weyl equation in a vacuum space-time with vanishing cosmological constant, and to avoid finding singular solutions of (8.8.4), the parameter $\Lambda=\frac{R}{24}$ should never vanish. Thus, so far, our analysis of the gauge freedom for Rarita-Schwinger potentials applies to any Riemannian four-manifold with non-vanishing cosmological constant. Moreover, on setting

$$
\begin{equation*}
\sigma^{A^{\prime}} \equiv \nabla^{A A^{\prime}} \nu_{A} \tag{8.8.6}
\end{equation*}
$$

a similar analysis yields

$$
\begin{align*}
\nabla^{\left(A^{\prime} C\right.} \sigma^{\left.B^{\prime}\right)} & =\frac{1}{2 \Lambda} \tilde{\Phi}_{L}^{A^{\prime} B^{\prime} C} \nabla_{M^{\prime}}^{L} \sigma^{M^{\prime}}  \tag{8.8.7}\\
\nu_{B} & =\frac{1}{2 \Lambda} \nabla_{B A^{\prime}} \sigma^{A^{\prime}} \tag{8.8.8}
\end{align*}
$$

We now consider the boundary conditions (8.7.12). With our notation, after defining

$$
\begin{equation*}
\Omega_{A^{\prime}}^{B B^{\prime}} \equiv \nabla^{B B^{\prime}} \lambda_{A^{\prime}} \tag{8.8.9}
\end{equation*}
$$

a sufficient condition for their validity is

$$
\begin{equation*}
\left.\sigma^{B^{\prime}}\right|_{\theta M}=-\left.\epsilon \sqrt{2}{ }_{e} n_{B}^{A^{\prime}} \Omega_{A^{\prime}}^{B B^{\prime}}\right|_{\partial M} . \tag{8.8.10}
\end{equation*}
$$

Remarkably, this boundary condition does not lead to restrictions on the curvature of the background. Hence the gauge freedom for Rarita-Schwinger potentials only

## 8. Spin- $\frac{3}{2}$ Potentials

leads to well-posed boundary-value problems for the spinor fields $v_{B}$ and $\lambda_{B^{\prime}}$ (see section 8.10).

### 8.9 Secondary Potentials in Curved Riemannian Backgrounds

As shown in Penrose 1994, in a Ricci-flat space-time the Rarita-Schwinger potentials may be supplemented by secondary potentials. Here we prove that such a construction can be generalized to the curved backgrounds of section 8.8. For this purpose, we introduce secondary potentials for the $\gamma$-potentials by requiring that locally

$$
\begin{equation*}
\gamma_{A^{\prime} B^{\prime}} \equiv \equiv \nabla_{B B^{\prime}} \rho_{A^{\prime}}{ }^{C B} \tag{8.9.1}
\end{equation*}
$$

Of course, special attention should be payed to the index ordering in (8.9.1), since the primary and secondary potentials are not symmetric as in section 8.4. On inserting (8.9.1) into (8.6.3), a repeated use of symmetrizations and antisymmetrizations leads to the equation

$$
\begin{align*}
& \frac{1}{2} \epsilon_{F L} \nabla_{A A^{\prime}} \nabla^{B^{\prime}(F} \rho_{B^{\prime}}{ }^{A) L}+\frac{1}{4} \nabla^{A} A^{\prime} \nabla^{B^{\prime} M} \rho_{B^{\prime}(A M)} \\
& +\frac{1}{2} \square_{A M} \rho_{A^{\prime}}{ }^{(A M)}+\frac{3}{16} \square \rho_{A^{\prime}}-\frac{3}{8} \widetilde{\Lambda} \rho_{A^{\prime}}=-3 \tilde{\Lambda} \widetilde{\alpha}_{A^{\prime}} \tag{8.9.2}
\end{align*}
$$

where, following Penrose 1994, we have defined

$$
\begin{equation*}
\rho_{A^{\prime}} \equiv \rho_{A^{\prime}}{ }_{C}^{C} \tag{8.9.3}
\end{equation*}
$$

Thus, if the following equations hold (cf. Penrose 1994):

$$
\begin{gather*}
\nabla^{B^{\prime}(F} \rho_{B^{\prime}}^{A) L}=0  \tag{8.9.4}\\
\nabla^{B^{\prime} M} \rho_{B^{\prime}(A M)}=\frac{3}{2} \nabla_{A}^{F^{\prime}} \rho_{F^{\prime}} \tag{8.9.5}
\end{gather*}
$$

equation (8.9.2) may be cast in the form

$$
\begin{equation*}
\square_{A M} \rho_{A^{\prime}}{ }^{(A M)}-3 \tilde{\Lambda} \rho_{A^{\prime}}=-6 \tilde{\Lambda} \tilde{\alpha}_{A^{\prime}} \tag{8.9.6}
\end{equation*}
$$

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A very useful identity resulting from equation (4.9.13) of Penrose and Rindler 1984 enables one to show that

$$
\begin{equation*}
\square \square_{A M} \rho_{A^{\prime}}{ }^{(A M)}=-\Phi_{A M A^{\prime}} L^{\prime} \rho_{L^{\prime}}{ }^{(A M)} \tag{8.9.7}
\end{equation*}
$$

Hence equation (8.9.6) may be written as

$$
\begin{equation*}
-\Phi^{A}{ }_{M A^{\prime}}^{L^{\prime}} \rho_{L^{\prime} A^{\prime}}+3 \Lambda \rho_{A^{\prime}}=6 \Lambda \widetilde{\boldsymbol{\alpha}}_{A^{\prime}} \tag{8.9.8}
\end{equation*}
$$

since $\Lambda=\widetilde{\Lambda}$ in our real background (Penrose and Rindler 1986). Moreover, we have to insert (8.9.1) into the field equation (8.6.4) for $\gamma$-potentials. By virtue of (8.8.3), (8.9.4) and of the identities (cf. Penrose and Rindler 1986)

$$
\begin{align*}
& \square^{B M} \rho_{B^{\prime} M}^{A}=-\psi^{A B L M} \rho_{(L M) B^{\prime}}-\Phi^{B M_{B^{\prime}} D^{\prime}} \rho_{M D^{\prime}}^{A}+4 \Lambda \rho_{B^{\prime}}^{(A B)},  \tag{8.9.9}\\
& \square^{B^{\prime} F^{\prime}} \rho_{B^{\prime}}^{(A B)}=3 \tilde{\Lambda} \rho^{(A B) F^{\prime}}+\widetilde{\Phi}_{B^{\prime} F^{\prime}}{ }^{A} \rho_{B^{\prime}}^{(L B)}+\tilde{\Phi}^{B^{\prime} F^{\prime} B} \rho_{B^{\prime}}^{(A L)} \tag{8.9.10}
\end{align*}
$$

this leads to the equation

$$
\begin{align*}
& -\psi^{A B L M} \rho_{(L M) C^{\prime}-\Phi^{(A|M|}{ }_{C^{\prime}}^{D^{\prime}} \rho_{M D^{\prime}}^{B)}} \\
& +\Lambda \rho_{C^{\prime}}^{(A B)}-\Phi_{C^{\prime} L}^{B^{\prime}} \rho_{B^{\prime}}^{(B L)}-\Phi_{C^{\prime}}^{B^{\prime}}{ }_{L}^{B} \rho_{B^{\prime}}^{(A L)} \\
& =\Phi^{A B L^{\prime}} \widetilde{\alpha}_{L^{\prime}} . \tag{8.9.11}
\end{align*}
$$

Note that we have used in (8.9.11) the reality condition for the scalar curvature and for the trace-free part of the Ricci spinor (Penrose and Rindler 1986).

Moreover, secondary potentials supplementing $\Gamma$-potentials may also be constructed locally. On defining

$$
\begin{align*}
\Gamma_{A B} C^{\prime} & \equiv \nabla_{B^{\prime} B} \theta_{A}^{C^{\prime} B^{\prime}}  \tag{8.9.12}\\
\theta_{A} & \equiv \theta_{A C^{\prime}} \tag{8.9.13}
\end{align*}
$$

and requiring that (Penrose 1994)

$$
\begin{equation*}
\nabla^{B\left(F^{\prime}\right.} \theta_{B}^{\left.A^{\prime}\right) L^{\prime}}=0 \tag{8.9.14}
\end{equation*}
$$

## 8. Spin $\frac{3}{2}$ Potentials

$$
\begin{equation*}
\nabla^{B M^{\prime}} \theta_{B\left(A^{\prime} M^{\prime}\right)}=\frac{3}{2} \nabla_{A^{\prime}}^{F} \theta_{F}, \tag{8.9.15}
\end{equation*}
$$

a similar calculation yields the equations

$$
\begin{equation*}
-\Phi^{A^{\prime}} M^{\prime} A^{L} \theta_{L A^{\prime}}^{M^{\prime}}+3 \Lambda \theta_{A}=6 \Lambda \alpha_{A}, \tag{8.9.16}
\end{equation*}
$$

$$
\begin{align*}
& -\widetilde{\psi}^{A^{\prime} B^{\prime} L^{\prime} M^{\prime}} \theta_{\left(L^{\prime} M^{\prime}\right) C}-\Phi^{\left(A^{\prime}\left|M^{\prime}\right|_{C}^{D} \theta_{M^{\prime} D}^{\left.B^{\prime}\right)}\right.} \\
& \left.+\Lambda \theta^{\left(A^{\prime} B^{\prime}\right)}-\Phi_{C L}-\Phi_{C L^{A^{\prime}}} \theta^{\left(B^{\prime} L^{\prime}\right)}\right)_{B}-\Phi_{C}^{B} B_{L^{\prime}}, \theta^{\left(A^{\prime} L^{\prime}\right)}{ }_{B} \\
& =\Phi^{A^{\prime} B^{\prime}{ }_{C}} \alpha_{L} . \tag{8.9.17}
\end{align*}
$$

It should be emphasized that (8.9.4)-(8.9.5), (8.9.8), (8.9.11) and (8.9.14)-(8.9.17) are a complicated set of equations for secondary potentials which may or may not have a solution for a given choice of background. In the particular and relevant case of Einstein backgrounds, where the trace-free part of the Ricci spinor vanishes, equations (8.9.8), (8.9.11) and (8.9.16)-(8.9.17) reduce to

$$
\begin{gather*}
\rho_{A^{\prime}}=2 \widetilde{\alpha}_{A^{\prime}},  \tag{8.9.18}\\
\psi^{A B L M} \rho_{(L M) C^{\prime}}-\Lambda \rho_{C^{\prime}}^{(A B)}=0,  \tag{8.9.19}\\
\theta_{A}=2 \alpha_{A},  \tag{8.9.20}\\
\widetilde{\psi}^{A^{\prime} B^{\prime} L^{\prime} M^{\prime}} \theta_{\left(L^{\prime} M^{\prime}\right) C}-\Lambda \theta_{C}^{\left(A^{\prime} B^{\prime}\right)}=0 \tag{8.9.21}
\end{gather*}
$$

### 8.10 Results and Open Problems

Following Esposito 1994 and Esposito and Pollifrone 1994, we have derived the conditions (8.2.13), (8.2.15), (8.3.5), and (8.3.8) under which spin-lowering and spin-raising operators preserve the local boundary conditions studied in Breitenlohner and Freedman 1982, Hawking 1983, Esposito 1994. Note that, for spin 0, we have introduced a pair of independent scalar fields on the real Riemannian section

## 8. Spin $\frac{3}{2}$ Potentials

of a complex space-time, following Hawking 1979, rather than a single scalar field, as done in Esposito 1994. Setting $\phi \equiv \phi_{1}+i \phi_{2}, \tilde{\phi} \equiv \phi_{3}+i \phi_{4}$, this choice leads to the boundary conditions

$$
\begin{align*}
\phi_{1} & =\epsilon \phi_{3} \text { on } S^{3},  \tag{8.10.1}\\
\phi_{2} & =\epsilon \phi_{4} \text { on } S^{3},  \tag{8.10.2}\\
e^{n^{A A^{\prime}} D_{A A^{\prime}} \phi_{1}} & =-\epsilon e_{e} n^{A A^{\prime}} D_{A A^{\prime}} \phi_{3} \text { on } S^{3}  \tag{8.10.3}\\
e^{n^{A A^{\prime}} D_{A A^{\prime}} \phi_{2}} & =-\epsilon_{e} n^{A A^{\prime}} D_{A A^{\prime}} \phi_{4} \text { on } S^{3} \tag{8.10.4}
\end{align*}
$$

and it deserves further study.
We have then focused on the Dirac potentials for spin- $\frac{3}{2}$ field strengths in flat or curved Riemannian four-space bounded by a three-sphere. Remarkably, it turns out that local boundary conditions involving field strengths and normals can only be imposed in a flat Euclidean background, for which the gauge freedom in the choice of the potentials remains. In Penrose 1991c it was found that $\rho$ potentials exist locally only in the self-dual Ricci-flat case, whereas $\gamma$ potentials may be introduced in the anti-self-dual case. Our result may be interpreted as a further restriction provided by (quantum) cosmology. What happens is that the boundary conditions (8.2.1) fix at the boundary a spinor field involving both the field strength $\phi_{A B C}$ and the field strength $\widetilde{\phi}_{A^{\prime} B^{\prime} C^{\prime}}$. The local existence of potentials for the field strength $\phi_{A B C}$, jointly with the occurrence of a boundary, forces half of the Riemann curvature of the background to vanish. Similarly, the remaining half of such Riemann curvature has to vanish on considering the field strength $\widetilde{\phi}_{A^{\prime} B^{\prime} C^{\prime}}$. Hence the background four-geometry can only be flat Euclidean space. This is different from the analysis in Penrose 1990, Penrose 1991a-b, since in that case one is not dealing with boundary conditions forcing us to consider both $\phi_{A B C}$ and $\tilde{\phi}_{A^{\prime} B^{\prime} C^{\prime}}$.

A naturally occurring question is whether the potentials studied in this chapter can be used to perform one-loop calculations for spin- $\frac{3}{2}$ field strengths subject to (8.2.1) on $S^{3}$. This problem may provide another example (cf. Esposito 1994) of the fertile interplay between twistor theory and quantum cosmology, and its

## 8. Spin $\frac{3}{2}$ Potentials

solution might shed new light on one-loop quantum cosmology and on the quantization program for gauge theories in the presence of boundaries. For this purpose, as shown in recent papers (Kamenshchik and Mishakov 1994), it is necessary to study Riemannian background four-geometries bounded by two concentric threespheres (cf. sections 8.2-8.5). Moreover, the consideration of non-physical degrees of freedom of gauge fields, set to zero in our classical analysis, is necessary to achieve a covariant quantization scheme.

Sections 8.6-8.9 have studied Rarita-Schwinger potentials in four-dimensional Riemannian backgrounds with boundary, to complement the analysis of Dirac's potentials appearing in section 8.4. Our results are as follows.
(1) The gauge transformations (8.6.7)-(8.6.8) are compatible with the RaritaSchwinger equations (8.6.3)-(8.6.6) providing the second-order equations (8.7.8)(8.7.11) hold. In the light of the definitions (8.8.1) and (8.8.6), an equivalent form of such a system takes the first-order form (8.8.4)-(8.8.5) jointly with (8.8.7)(8.8.8).
(2) The boundary conditions (8.5.1) do not restrict severely the class of admissible background four-geometries. A sufficient condition for their validity is given by (8.8.10).
(3) The Penrose construction of secondary potentials for Ricci-flat space-times may be extended to arbitrary curved backgrounds providing the equations (8.9.2), (8.9.4)-(8.9.5), (8.9.8), (8.9.11) and (8.9.14)-(8.9.17) hold. Remarkably, equations (8.9.8) and (8.9.16) tell us that, on taking traces of such secondary potentials, one obtains spinor fields proportional to the spinor fields corresponding to the Majorana field in the Lorentzian version of (8.6.3)-(8.6.6). Moreover, equations (8.9.19) and (8.9.21) show that, in Einstein backgrounds, the symmetric parts of the secondary potentials are related to the conformal curvature and to the cosmological constant. Hence the secondary potentials supplementing the RaritaSchwinger potentials have a very clear physical meaning.

## 8. Spin $\frac{3}{2}$ Potentials

It therefore appears that the consideration of background four-geometries belonging to the class of Einstein spaces, where equations (8.9.18)-(8.9.21) hold, may be put on very solid mathematical grounds. Thus, despite the very restrictive results obtained in section 8.4 for Dirac potentials, it is legitimate to study the mode-by-mode form of semi-classical quantum amplitudes for Rarita-Schwinger fields about curved backgrounds. Remarkably, a formalism originally motivated by twistor theory (Frauendiener 1994, Mason and Penrose 1994, Penrose 1994) has been generalized within the framework of classical boundary-value problems relevant for one-loop quantum cosmology.

We also think the following property should be emphasixed once again. In the case of reflective boundary conditions (8.2.1) on field strengths expressed locally in terms of Dirac's potentials, a gauge transformation on such potentials leads to additional conditions at the boundary involving the curvature of the background (section 8.4). To avoid having such extra boundary conditions, one has then to set to zero everywhere a part of the curvature of the background. In the second part of our chapter, however, since the boundary conditions (8.5.1) involve the potentials (rather than field strengths), the gauge transformations (8.6.7)-(8.6.8) lead instead to the additional boundary conditions (8.7.12). These involve only first-order covariant derivatives of the spinor fields occurring in the gauge freedom of the problem, and hence can be satisfied without having to set to zero everywhere a part of the curvature of the background.

Last, but not least, many interesting problems have not yet been studied, i.e.
(i) To obtain the explicit solution of equations (8.8.4) and (8.8.7) subject to the conditions (8.8.10) at the boundary, for a given choice of background fourgeometry.
(ii) To derive necessary conditions for the validity of (8.7.12).
(iii) To solve for $\alpha_{A}$ and $\widetilde{\boldsymbol{\alpha}}_{A^{\prime}}$ after inserting Eq. (B.4) into the supergravity field equations in a background with non-vanishing cosmological constant. This would

## 8. Spin $\frac{3}{2}$ Potentials

lead in turn to the determination of the secondary potentials, on using Eqs. (8.9.8), (8.9.11), (8.9.16)-(8.9.17).
(iv) To determine the effect of gauge transformations for secondary potentials on the analysis of our elliptic boundary-value problem (cf. Penrose 1994).
(v) Is there an underlying global theory ? What parts of the curvature are the obstructions to defining a global theory ?
(vi) What are the key features of the global theory (if it exists)?
(vii) Can one define twistors as charges for spin $\frac{3}{2}$ in our backgrounds with nonvanishing cosmological constant ?
(viii) Can one reconstruct the Riemannian four-world from the twistor space, or from whatever is going to replace twistor space ?

To help the reader, we conclude this chapter with tables 8.10.1 and 8.10.2, where the Dirac and Rarita-Schwinger forms of primary and secondary potentials are described.

## 8. Spin $\frac{3}{2}$ Potentials

TABLE 8.10.1

|  | Dirac Potentials | Gauge Freedom |
| :---: | :---: | :---: |
| Primary | $\phi_{A B C}=\nabla_{C C^{\prime}} \Gamma^{C^{\prime}}{ }_{A B}$ | $\widehat{\Gamma}^{C^{\prime}}{ }_{A B} \equiv \Gamma_{A B}{ }^{\prime}+\nabla_{B}{ }^{\prime} \nu_{A}$ |
| Primary | $\bar{\phi}_{A^{\prime} B^{\prime} C^{\prime}}=\nabla_{C C^{\prime}} \gamma_{A^{\prime} B^{\prime}}$ | $\widehat{\gamma}_{A^{\prime} B^{\prime}}^{C} \equiv \gamma_{A^{\prime} B^{\prime}}+\nabla^{C} B^{\prime} \tilde{\nu}_{A^{\prime}}$ |
| Secondary | $\Gamma_{A B}^{C^{\prime}}=\nabla_{B B^{\prime}} \Lambda_{A}^{B^{\prime} C^{\prime}}$ | $\widehat{\Lambda}_{A}^{B^{\prime} C^{\prime}} \equiv \Lambda_{A}^{B^{\prime} C^{\prime}}+\nabla_{A}^{C^{\prime}} \bar{\chi}^{B^{\prime}}$ |
| Secondary | $\gamma_{A^{\prime} B^{\prime}}=\nabla_{B B^{\prime}} \rho_{A^{\prime}}{ }^{B C}$ | $\hat{\rho}_{A^{\prime}}{ }^{B C} \equiv \rho_{A^{\prime}}{ }^{B C}+\nabla^{C}{ }_{A^{\prime}} \chi^{B}$ |

TABLE 8.10.2

|  | Rarita-Schwinger Potentials | Gauge Freedom |
| :---: | :---: | :---: |
| Primary | $\psi_{A \mu}=\Gamma^{C^{\prime}}{ }_{A B} e^{B}{ }_{C}{ }_{\mu}$ | $\widehat{\Gamma}^{A^{\prime}}{ }_{B C} \equiv \Gamma^{A^{\prime}}{ }_{B C}+\nabla^{A^{\prime}} \nu_{B}$ |
| Primary | $\tilde{\psi}_{A^{\prime} \mu}=\gamma^{C}{ }_{A^{\prime} B^{\prime}}{ }^{\prime} C_{C}{ }^{B^{\prime}}{ }_{\mu}$ | $\widehat{\gamma}_{B^{\prime} C^{\prime}}{ }^{\prime}=\gamma^{A}{ }_{B^{\prime} C^{\prime}}+\nabla^{A} C^{\prime} \lambda_{B^{\prime}}$ |
| Secondary | $\Gamma_{A B}{ }^{C^{\prime}}=\nabla_{B^{\prime} B_{B}} \theta_{A}{ }^{\prime \prime} B^{\prime}$ | $\widehat{\theta}_{A}{ }^{\prime} B^{\prime} \equiv \theta_{A}{ }^{A^{\prime} B^{\prime}}+\nabla_{A^{A^{\prime}}} \mu^{B^{\prime}}$ |
| Secondary | $\gamma_{A^{\prime} B^{\prime}}{ }^{C}=\nabla_{B B^{\prime}} \rho_{A^{\prime}}{ }^{\prime B}$ | $\widehat{\rho}_{A^{\prime}}{ }^{\prime B} \equiv \rho_{A^{\prime}}{ }^{A B}+\nabla_{A^{\prime}}{ }^{A} \xi^{B}$ |

## PART IV:

MATHEMATICAL FOUNDATIONS

## UNDERLYING MATHEMATICAL STRUCTURES


#### Abstract

This chapter begins with a review of four definitions of twistors in curved space-time proposed by Penrose in the seventies, i.e. local twistors, global null twistors, hypersurface twistors and asymptotic twistors. The Penrose transform for gravitation is then re-analyzed, with emphasis on the double-fibration picture. Double fibrations are also used to introduce the ambitwistor correspondence, and the Radon transform in complex analysis is mentioned. Attention is then focused on the Ward picture of massless fields as bundles, which has motivated the recent analysis by Penrose of secondary potentials which supplement the Rarita-Schwinger potentials in curved space-time (see chapter eight). The boundary conditions studied in chapters seven and eight have been recently applied in the quantization program of field theories. Hence the chapter ends with a review of progress made in studying bosonic fields subject to boundary conditions respecting BRST invariance and local supersymmetry. Interestingly, it remains to be seen whether the Atiyah-Patodi-Singer theory of Riemannian four-manifolds can be applied to obtain an explicit proof of gauge invariance of quantum amplitudes.


## 9. Underlying Mathematical Structures

### 9.1 Introduction

This review chapter is written for those readers who are more interested in the mathematical foundations of twistor theory (see appendices C and D ). In Minkowski space-time, twistors are defined as the elements of the vector space of solutions of the differential equation (4.1.5), or as $\alpha$-planes. The latter concept, more geometrical, has been extended to curved space-time through the totally null surfaces called $\alpha$-surfaces, whose integrability condition (in the absence of torsion) is the vanishing of the self-dual Weyl spinor. To avoid having to set to zero half of the conformal curvature of complex space-time, yet another definition of twistors, i.e. charges for massless spin- $\frac{3}{2}$ fields in Ricci-flat space-times, has been proposed by Penrose.

The first part of this chapter supplements these efforts by describing various definitions of twistors in curved space-time. Each of these ideas has its merits and its drawbacks. To compare local twistors at different points of space-time one is led to introduce local twistor transport (cf. section 4.3) along a curve, which moves the point with respect to which the twistor is defined, but not the twistor itself.

On studying the space of null twistors, a closed two-form and a one-form are naturally obtained, but their definition cannot be extended to non-null twistors unless one studies Minkowski space-time. In other words, one deals with a symplectic structure which remains invariant, since a non-rotating congruence of null geodesics remains non-rotating in the presence of curvature. However, the attempt to obtain an invariant complex structure fails, since a shear-free congruence of null geodesics acquires shear in the presence of conformal curvature.

If an analytic space-time with analytic hypersurface $S$ in it are given, one can, however, construct an hypersurface twistor space relative to $S$. The differential equations describing the geometry of hypersurface twistors encode, by construction, the information on the complex structure, which here retains a key role. The
differential forms introduced in the theory of global null twistors, can also be expressed in the language of hypersurface twistors. However, the whole construction relies on the choice of some analytic (spacelike) hypersurface in curved space-time.

To overcome this difficulty, asymptotic twistors are introduced in asymptotically flat space-times. One is thus led to combine the geometry of future and past null infinity, which are null hypersurfaces, with the differential equations of hypersurface twistors and with the local twistor description. Unfortunately, it is unclear how to achieve such a synthesis in a generic space-time.

The second part of this chapter begins by focusing on the geometry of conformally invariant operators, and on the description of the Penrose transform in a more abstract mathematical language, i.e. in terms of a double fibration of the projective primed spin-bundle over twistor space and space-time respectively. The ambitwistor correspondence of Le Brun is then introduced, in terms of a holomorphic double fibration, and a mention is made of the Radon transform, i.e. an integral transform which associates to a real-valued function on $R^{2}$ its integral along a straight line in $R^{2}$. Such a mathematical object is very relevant for modern twistor theory, by virtue of its links with the abstract theory of the Penrose transform.

Ward's construction of twisted photons and massless fields as bundles is described in section 9.9, since it enables one to understand the geometrical structures underlying the theory of spin- $\frac{3}{2}$ potentials used in section 8.9. In particular, Eq. (8.9.4) is related to a class of integrability conditions arising from the generalization of Ward's construction, as recently shown in Penrose 1994. Remarkably, this sheds new light on the differential equations describing the local theory of primary and secondary potentials (cf. section 8.9).

Since the boundary conditions of chapters seven and eight are relevant for the elliptic boundary-value problems occurring in modern attempts to obtain a mathematically consistent formulation of quantum field theories in the presence of boundaries, recent progress on these problems is summarized in section 9.10. While the conformal anomalies for gauge fields in Riemannian manifolds with

## 9. Underlying Mathematical Structures

boundaries have been correctly evaluated after many years of dedicated work by several authors, it remains to be seen whether the explicit (i.e. not formal) proof of gauge invariance of quantum amplitudes can be obtained. It appears exciting that gauge invariance of quantum amplitudes might be related to the invariance under homotopy of the residue of a meromorphic function, obtained from the eigenvalues of the elliptic operators of the problem.

### 9.2 Local Twistors

A local twistor $Z^{\alpha}$ at $P \in M$ is represented by a pair of spinors $\omega^{A}, \pi_{A^{\prime}}$ at $P$ :

$$
\begin{equation*}
Z^{\alpha} \longleftrightarrow\left(\omega^{A}, \pi_{A^{\prime}}\right) \tag{9.2.1}
\end{equation*}
$$

with respect to the metric $g$ on $M$. After a conformal rescaling $\widehat{g} \equiv \Omega^{2} g$ of the metric, the representation of $Z^{\alpha}$ changes according to the rule

$$
\begin{equation*}
\left(\widehat{\omega}^{A}, \widehat{\pi}_{A^{\prime}}\right)=\left(\omega^{A}, \pi_{A^{\prime}}+i T_{A A^{\prime}} \omega^{A}\right) \tag{9.2.2}
\end{equation*}
$$

where $T_{A A^{\prime}} \equiv \nabla_{A A^{\prime}} \log (\Omega)$. The comparison of local twistors at different points of $M$ makes it necessary to introduce the local twistor transport along a curve $\tau$ in $M$ with tangent vector $t$. This does not lead to a displacement of the twistor along $\tau$, but moves the point with respect to which the twistor is defined. On defining the spinor

$$
\begin{equation*}
P_{A A^{\prime} B B^{\prime}} \equiv \frac{1}{12} R g_{A A^{\prime} B B^{\prime}}-\frac{1}{2} R_{A A^{\prime} B B^{\prime}}, \tag{9.2.3}
\end{equation*}
$$

the equations of local twistor transport are (cf. (4.3.20)-(4.3.21))

$$
\begin{gather*}
t^{B B^{\prime}} \nabla_{B B^{\prime}} \omega^{A}=-i t^{A B^{\prime}} \pi_{B^{\prime}}  \tag{9.2.4}\\
t^{B B^{\prime}} \nabla_{B B^{\prime}} \pi_{A^{\prime}}=-i P_{B B^{\prime} A A^{\prime}} t^{B B^{\prime}} \omega^{A} . \tag{9.2.5}
\end{gather*}
$$

## 9. Underlying Mathematical Structures

A more general concept is the one of covariant derivative in the $t$-direction of a local twistor field on $M$ according to the rule

$$
\begin{align*}
& t^{B B^{\prime}} \nabla_{B B^{\prime}} Z^{\alpha} \longleftrightarrow\left(t^{B B^{\prime}} \nabla_{B B^{\prime}} \omega^{A}+i t^{A B^{\prime}} \pi_{B^{\prime}}\right. \\
&\left.t^{B B^{\prime}} \nabla_{B B^{\prime}} \pi_{A^{\prime}}+i P_{B B^{\prime} A A^{\prime}} t^{B B^{\prime}} \omega^{A}\right) \tag{9.2.6}
\end{align*}
$$

After a conformal rescaling of the metric, both $Z^{\alpha}$ and its covariant derivative change according to (9.2.2). In particular, this implies that local twistor transport is conformally invariant.

The presence of conformal curvature is responsible for a local twistor not returning to its original state after being carried around a small loop by local twistor transport. In fact, as shown in Penrose 1975, denoting by $[t, u]$ the Lie bracket of $t$ and $u$, one finds

$$
\begin{equation*}
\left[t^{p} \nabla_{p}, u^{q} \nabla_{q}\right] Z^{\beta}-[t, u]^{p} \nabla_{p} Z^{\beta} \longleftrightarrow t^{P P^{\prime}} u^{Q Q^{\prime}}\left\{S_{P P^{\prime} Q Q^{\prime}}^{B}, V_{P P^{\prime} Q Q^{\prime} B^{\prime}}\right\} \tag{9.2.7}
\end{equation*}
$$

where

$$
\begin{gather*}
S_{P P^{\prime} Q Q^{\prime}}^{B} \equiv \epsilon_{P^{\prime} Q^{\prime}} \psi_{P Q A}^{B} \omega^{A},  \tag{9.2.8}\\
V_{P P^{\prime} Q Q^{\prime} B^{\prime}} \equiv-i\left(\epsilon_{P Q} \nabla_{A A^{\prime}} \tilde{\psi}_{B^{\prime} P^{\prime} Q^{A^{\prime}}}+\epsilon_{P^{\prime} Q^{\prime}} \nabla_{B B^{\prime}} \psi_{A P Q}{ }^{B}\right) \omega^{A} \\
-\epsilon_{P Q} \widetilde{\psi}_{P^{\prime} Q^{\prime} B^{\prime}} A^{\prime} \pi_{A^{\prime}} . \tag{9.2.9}
\end{gather*}
$$

Eq. (9.2.7) implies that, for these twistors to be defined globally on space-time, our $(M, g)$ should be conformally flat.

In a Lorentzian space-time $(M, g)_{L}$, one can define local twistor transport of dual twistors $W_{\alpha}$ by complex conjugation of Eqs. (9.2.4)-(9.2.5). On reinterpreting the complex conjugate of $\omega^{A}$ (resp. $\pi_{A^{\prime}}$ ) as some spinor $\pi^{A^{\prime}}$ (resp. $\omega_{A}$ ), this leads to

$$
\begin{gather*}
t^{B B^{\prime}} \nabla_{B B^{\prime}} \pi^{A^{\prime}}=i t^{B A^{\prime}} \omega_{B},  \tag{9.2.10}\\
t^{B B^{\prime}} \nabla_{B B^{\prime}} \omega_{A}=i P_{B B^{\prime} A A^{\prime}} t^{B B^{\prime}} \pi^{A^{\prime}} . \tag{9.2.11}
\end{gather*}
$$

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Moreover, in $(M, g)_{L}$ the covariant derivative in the $t$-direction of a local dual twistor field is also obtained by complex conjugation of (9.2.6), and leads to

$$
\begin{gather*}
t^{B B^{\prime}} \nabla_{B B^{\prime}} W_{\alpha} \longleftrightarrow\left(t^{B B^{\prime}} \nabla_{B B^{\prime}} \omega_{A}-i P_{B B^{\prime} A A^{\prime}} t^{B B^{\prime}} \pi^{A^{\prime}},\right. \\
\left.t^{B B^{\prime}} \nabla_{B B^{\prime}} \pi^{A^{\prime}}-i t^{B A^{\prime}} \omega_{B}\right) \tag{9.2.12}
\end{gather*}
$$

One thus finds

$$
\begin{equation*}
t^{b} \nabla_{b}\left(Z^{\alpha} W_{\alpha}\right)=Z^{\alpha} t^{b} \nabla_{b} W_{\alpha}+W_{\alpha} t^{b} \nabla_{b} Z^{\alpha} \tag{9.2.13}
\end{equation*}
$$

where the left-hand side denotes the ordinary derivative of the scalar $Z^{\alpha} W_{\alpha}$ along $\tau$. This implies that, if local twistor transport of $Z^{\alpha}$ and $W_{\alpha}$ is preserved along $\tau$, their scalar product is covariantly constant along $\tau$.

### 9.3 Global Null Twistors

To define global null twistors one is led to consider null geodesics $Z$ in curved space-time, and the $\pi_{A^{\prime}}$ spinor parallelly propagated along $Z$. The corresponding momentum vector $p_{A A^{\prime}}=\bar{\pi}_{A} \pi_{A^{\prime}}$ is then tangent to $Z$. Of course, we want the resulting space $N$ of null twistors to be physically meaningful. Following Penrose 1975, the space-time $(M, g)$ is taken to be globally hyperbolic to ensure that $N$ is a Hausdorff manifold (see section 1.2). Since the space of unscaled null geodesics is five-dimensional, and the freedom for $\pi_{A^{\prime}}$ is just a complex multiplying factor, the space of null twistors turns out to be seven-dimensional. Global hyperbolicity of $M$ is indeed the strongest causality assumption, and it ensures that Cauchy surfaces exist in $M$ (Hawking and Ellis 1973, Esposito 1994, and references therein).

On $N$ a closed two-form $\omega$ exists, i.e.

$$
\begin{equation*}
\omega \equiv d p_{a} \wedge d x^{a} . \tag{9.3.1}
\end{equation*}
$$

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Although $\omega$ is initially defined on the cotangent bundle $T^{*} M$, it actually yields a two-form on $N$ if it is taken to be constant under the rescaling

$$
\begin{equation*}
\pi_{\boldsymbol{A}^{\prime}} \rightarrow e^{i \theta} \pi_{\boldsymbol{A}^{\prime}}, \tag{9.3.2}
\end{equation*}
$$

with real parameter $\theta$. Such a two-form may be viewed as the rotation of a congruence, since it can be written as

$$
\begin{equation*}
\omega=\nabla_{[b} p_{c]} d x^{b} \wedge d x^{c}, \tag{9.3.3}
\end{equation*}
$$

where $\nabla_{[b} p_{c]}$ yields the rotation of the field $p$ on $M$, for a congruence of geodesics. Our two-form $\omega$ may be obtained by exterior differentiation of the one-form

$$
\begin{equation*}
\phi \equiv p_{a} d x^{a} \tag{9.3.4}
\end{equation*}
$$

i.e.

$$
\begin{equation*}
\omega=d \phi \tag{9.3.5}
\end{equation*}
$$

Note that $\phi$ is defined on the space of null twistors and is constant under the rescaling (9.3.2). Penrose has proposed an interpretation of $\phi$ as measuring the time-delay in a family of scaled null geodesics (Penrose 1975).

The main problem is how to extend these definitions to non-null twistors. Indeed, this is possible in Minkowski space-time, where

$$
\begin{gather*}
\omega=i d Z^{\alpha} \wedge d \bar{Z}_{\alpha}  \tag{9.3.6}\\
\phi=i Z^{\alpha} d \bar{Z}_{\alpha} \tag{9.3.7}
\end{gather*}
$$

It is clear that Eqs. (9.3.6)-(9.3.7), if regarded as definitions, do not depend on the twistor $Z^{\alpha}$ being null (in Minkowski). Alternative choices for $\phi$ are

$$
\begin{gather*}
\phi_{1} \equiv-i \bar{Z}_{\alpha} d Z^{\alpha}  \tag{9.3.8}\\
\phi_{2} \equiv \frac{i}{2}\left(Z^{\alpha} d \bar{Z}_{\alpha}-\bar{Z}_{\alpha} d Z^{\alpha}\right) \tag{9.3.9}
\end{gather*}
$$

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The invariant structure of (flat) twistor space is then given by the one-form $\phi$, the two-form $\omega$, and the scalar $s \equiv \frac{1}{2} Z^{\alpha} \bar{Z}_{\alpha}$. Although one might be tempted to consider only $\phi$ and $s$ as basic structures, since exterior differentiation yields $\omega$ as in (9.3.5), the two-form $\omega$ is very important since it provides a symplectic structure for flat twistor space. However, if one restricts $\omega$ to the space of null twistors, one first has to factor out the phase circles

$$
\begin{equation*}
Z^{\beta} \rightarrow e^{i \theta} Z^{\beta} \tag{9.3.10}
\end{equation*}
$$

$\theta$ being real, to obtain again a symplectic structure. On restriction to $N$, the triple $(\omega, \phi, s)$ has an invariant meaning also in curved space-time, hence its name.

Suppose now that there are two regions $M_{1}$ and $M_{2}$ of Minkowski space-time separated by a region of curved space-time (Penrose 1975). In each flat region, one can define $\omega$ and $\phi$ on twistor space according to (9.3.6)-(9.3.7), and then re-express them as in (9.3.1), (9.3.4) on the space $N$ of null twistors in curved space-time. If there are regions of $N$ where both definitions are valid, the flat-twistor-space definitions should agree with the curved ones in these regions of $N$. However, it is unclear how to carry a non-null twistor from $M_{1}$ to $M_{2}$, if in between them there is a region of curved space-time.

It should be emphasized that, although one has a good definition of invariant structure on the space $N$ of null twistors in curved space-time, with the corresponding symplectic structure, such a construction of global null twistors does not enable one to introduce a complex structure. The underlying reason is that a nonrotating congruence of null geodesics remains non-rotating on passing through a region of curved space-time. By contrast, a shear-free congruence of null geodesics acquires shear on passing through a region of conformal curvature. This is why the symplectic structure is invariant, while the complex structure is not invariant and is actually affected by the conformal curvature.

Since twistor theory relies instead on holomorphic ideas and complex structures in a conformally invariant framework, it is necessary to introduce yet another

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definition of twistors in curved space-time, where the complex structure retains its key role. This problem is studied in the following section.

### 9.4 Hypersurface Twistors

Given some hypersurface $S$ in space-time, we are going to construct a twistor space $T(S)$, relative to $S$, with an associated complex structure. On going from $S$ to a different hypersurface $S^{\prime}$, the corresponding twistor space $T\left(S^{\prime}\right)$ turns out to be a complex manifold different from $T(S)$. For any $T(S)$, its elements are the hypersurface twistors. To construct these mathematical structures, we follow again Penrose 1975 and we focus on an analytic space-time $M$, with analytic hypersurface $S$ in $M$. These assumptions enable one to consider the corresponding complexifications $C M$ and $C S$. We know from chapter four that any twistor $Z^{\alpha}$ in $M$ defines a totally null plane $C Z$ and a spinor $\pi_{A^{\prime}}$ such that the tangent vector to $C Z$ takes the form $\xi^{A} \pi^{A^{\prime}}$. Since $\pi_{A^{\prime}}$ is constant on $C Z$, it is also constant along the complex curve $\gamma$ giving the intersection $C Z \cap C S$. The geometrical objects we are interested in are the normal $n$ to $C S$ and the tangent $t$ to $\gamma$. Since, by construction, $t$ has to be orthogonal to $n$ :

$$
\begin{equation*}
n_{A A^{\prime}} t^{A A^{\prime}}=0 \tag{9.4.1}
\end{equation*}
$$

it can be written in the form

$$
\begin{equation*}
t^{A A^{\prime}}=n^{A B^{\prime}} \pi_{B^{\prime}} \pi^{A^{\prime}} \tag{9.4.2}
\end{equation*}
$$

which clearly satisfies (9.4.1) by virtue of the identity $\pi_{B^{\prime}} \pi^{B^{\prime}}=0$. Thus, for $\pi_{A}$, to be constant along $\gamma$, the following equation should hold:

$$
\begin{equation*}
t^{A A^{\prime}} \nabla_{A A^{\prime}} \pi_{C^{\prime}}=n^{A B^{\prime}} \pi_{B^{\prime}} \pi^{A^{\prime}} \nabla_{A A^{\prime}} \pi_{C^{\prime}}=0 \tag{9.4.3}
\end{equation*}
$$

Note that (9.4.3) also provides a differential equation for $\gamma($ i.e., for a given normal, the direction of $\gamma$ is fixed by (9.4.2)), and the solutions of (9.4.3) on $C S$ are the

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elements of the hypersurface twistor space $T(S)$. Remarkably, since no complex conjugation is involved in deriving Eq. (9.4.3), the resulting $T(S)$ is a complex manifold (see section 3.3).

It is now helpful to introduce some notation. We write $Z^{(h)}$ for any element of $T(S)$, and we remark that if $Z^{(h)} \in T(S)$ corresponds to $\pi_{A}$ along $\gamma$ satisfying (9.4.3), then $\rho Z^{(h)} \in T(S)$ corresponds to $\rho \pi_{A}$ 'along the same curve $\gamma, \forall \rho \in C$ (Penrose 1975). This means one may consider the space $P T(S)$ of equivalence classes of proportional hypersurface twistors, and regard it as the space of curves $\gamma$ defined above. The zero-element $0^{(h)} \in T(S)$, however, does not correspond to any element of $P T(S)$. For each $Z^{(h)} \in T(S), 0 Z^{(h)}$ is defined as $0^{(h)} \in T(S)$. If the curve $\gamma$ contains a real point of $S$, the corresponding hypersurface twistor $Z^{(h)} \in T(S)$ is said to be null. Of course, one may well ask how many real points of $S$ can be found on $\gamma$. It turns out that, if the complexification $C S$ of $S$ is suitably chosen, only one real point of $S$ can lie on each of the curves $\gamma$. The set $P N(S)$ of such curves is five-real-dimensional, and the corresponding set $N(S)$, i.e. the $\gamma$-curves with $\pi_{A^{\prime}}$ spinor, is seven-real-dimensional. Moreover, the hypersurface twistor space is four-complex-dimensional, and the space $P T(S)$ of equivalence classes defined above is three-complex-dimensional.

The space $N(S)$ of null hypersurface twistors has two remarkable properties:
(i) $N(S)$ may be identified with the space $N$ of global null twistors defined in section 9.3. To prove this one points out that the spinor $\pi_{A}$, at the real point of $\gamma\left(\right.$ for $\left.Z^{(h)} \in N(S)\right)$ defines a null geodesic in $M$. Such a null geodesic passes through that point in the real null direction given by $v^{A A^{\prime}} \equiv \bar{\pi}^{A} \pi^{A}$. Parallel propagation of $\pi_{A}$ 'along this null geodesic yields a unique element of $N$. On the other hand, each global null twistor in $N$ defines a null geodesic and a $\pi_{A}$. Such a null geodesic intersects $S$ at a unique point. A unique $\gamma$-curve in $C S$ exists, passing through this point $x$ and defined uniquely by $\pi_{A^{\prime}}$ at $x$.
(ii) The hypersurface $S$ enables one to supplement the elements of $N(S)$ by some non-null twistors, giving rise to the four-complex-dimensional manifold $T(S)$. Unfortunately, the whole construction depends on the particular choice of (spacelike Cauchy) hypersurface in $(M, g)$.

The holomorphic operation

$$
Z^{(h)} \rightarrow \rho Z^{(h)} \quad, \quad Z^{(h)} \in T(S)
$$

enables one to introduce homogeneous holomorphic functions on $T(S)$. Setting to zero these functions gives rise to regions of $C T(S)$ corresponding to congruences of $\gamma$-curves on $S$. A congruence of null geodesics in $M$ is defined by $\gamma$-curves on $S$ having real points. Consider now $\pi_{A^{\prime}}$ as a spinor field on $C(S)$, subject to the scaling $\pi_{A^{\prime}} \rightarrow \rho \pi_{A^{\prime}}$. On making this scaling, the new field $\beta_{A^{\prime}} \equiv \rho \pi_{A^{\prime}}$ no longer solves Eq. (9.4.3), since the following term survives on the left-hand side:

$$
\begin{equation*}
E_{C^{\prime}} \equiv n^{A B^{\prime}} \pi_{B^{\prime}} \pi_{C^{\prime}} \pi^{A^{\prime}} \nabla_{A A^{\prime}} \rho \tag{9.4.4}
\end{equation*}
$$

This suggests to consider the weaker condition

$$
\begin{equation*}
n^{A B^{\prime}} \pi_{B^{\prime}}\left(\pi^{A^{\prime}} \pi^{C^{\prime}} \nabla_{A A^{\prime}} \pi_{C^{\prime}}\right)=0 \quad \text { on } \quad \mathcal{S} \tag{9.4.5}
\end{equation*}
$$

since $\pi^{C^{\prime}}$ has a vanishing contraction with $E_{C^{\prime}}$. Eq. (9.4.5) should be regarded as an equation for the spinor field $\pi_{A^{\prime}}$ restricted to $S$. Following Penrose 1975, round brackets have been used to emphasize the role of the spinor field

$$
B_{A} \equiv \pi^{A^{\prime}} \pi^{C^{\prime}} \nabla_{A A^{\prime}} \pi_{C^{\prime}}
$$

whose vanishing leads to a shear-free congruence of null geodesics with tangent vector $v^{A A^{\prime}} \equiv \bar{\pi} \quad \pi^{A^{\prime}}$.

A careful consideration of extensions and restrictions of spinor fields enables one to write an equivalent form of Eq. (9.4.5). In other words, if we extend $\pi_{A^{\prime}}$ to a spinor field on the whole of $M$, Eq. (9.4.5) holds if we replace $n^{A B^{\prime}} \pi_{B^{\prime}}$ by $\overline{\boldsymbol{\pi}}^{A}$.

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This implies that the same equation holds on $S$ if we omit $n^{A B^{\prime}} \pi_{B^{\prime}}$. Hence one eventually deals with the equation

$$
\begin{equation*}
\pi^{A^{\prime}} \pi^{C^{\prime}} \nabla_{A A^{\prime}} \pi_{C^{\prime}}=0 \tag{9.4.6}
\end{equation*}
$$

Since it is well-known in general relativity that conformal curvature is responsible for a shear-free congruence of null geodesics to acquire shear, the previous analysis proves that the complex structure of hypersurface twistor space is affected by the particular choice of $S$ unless the space-time is conformally flat.

The dual hypersurface twistor space $T^{*}(S)$ may be defined by interchanging primed and unprimed indices in (9.4.3), i.e.

$$
\begin{equation*}
n^{B A^{\prime}} \tilde{\pi}_{B} \widetilde{\pi}^{A} \nabla_{A A^{\prime}} \tilde{\pi}_{C}=0 . \tag{9.4.7}
\end{equation*}
$$

In agreement with the notation used in our monograph and proposed by Penrose, the tilde symbol denotes spinor fields not obtained by complex conjugation of the spinor fields living in the complementary spin-space, since, in a complex manifold, complex conjugation is not invariant under holomorphic coordinate transformations. Hence the complex nature of $T(S)$ and $T^{*}(S)$ is responsible for the spinor fields in (9.4.3) and (9.4.7) being totally independent. Eq. (9.4.7) defines a unique complex curve $\tilde{\boldsymbol{\gamma}}$ in $C S$ through each point of $C S$. The geometrical interpretation of $n^{B A}{ }^{\prime} \tilde{\boldsymbol{\pi}}_{\boldsymbol{B}} \tilde{\boldsymbol{\pi}}^{\boldsymbol{A}}$ is in terms of the tangent direction to the curve $\widetilde{\boldsymbol{\gamma}}$ for any choice of $\tilde{\boldsymbol{\pi}}_{A}$.The curve $\widetilde{\boldsymbol{\gamma}}$ and the spinor field $\widetilde{\boldsymbol{\pi}}_{A}$ solving Eq. (9.4.7) define a dual hypersurface twistor $\widetilde{\boldsymbol{Z}}_{\mid(h)} \in T^{*}(S)$. Indeed, the complex conjugate $\overline{\boldsymbol{Z}}_{(h)}$ of the hypersurface twistor $Z^{(h)} \in T(S)$ may also be defined if the following conditions hold:

$$
\begin{equation*}
\tilde{\pi}_{\boldsymbol{A}}=\bar{\pi}_{\boldsymbol{A}} \quad, \quad \tilde{\gamma}=\gamma \tag{9.4.8}
\end{equation*}
$$

The incidence between $Z^{(h)} \in T(S)$ and $\widetilde{Z}_{(h)} \in T^{*}(S)$ is instead defined by the condition

$$
\begin{equation*}
Z^{(h)} \tilde{Z}_{(h)}=0 \tag{9.4.9}
\end{equation*}
$$

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where ( $h$ ) is not an index, but a label to denote hypersurface twistors (instead of the dot used in Penrose 1975). Eq. (9.4.9) means that $\gamma$ and $\widetilde{\gamma}$ have a point of $C S$ in common. Null hypersurface twistors are then defined by the condition

$$
\begin{equation*}
Z^{(h)} \bar{Z}_{(h)}=0 \tag{9.4.10}
\end{equation*}
$$

However, it is hard to make sense of the (scalar) product $Z^{(h)} \tilde{Z}_{(h)}$ for arbitrary elements of $T(S)$ and $T^{*}(S)$ respectively.

We are now interested in holomorphic maps

$$
\begin{equation*}
F: T^{*}(\mathcal{S}) \times T(\mathcal{S}) \rightarrow C \tag{9.4.11}
\end{equation*}
$$

Since $T(S)$ and $T^{*}(S)$ are both four-complex-dimensional, the space $T^{*}(S) \times T(S)$ is eight-complex-dimensional. A seven-complex dimensional subspace $\tilde{N}(S)$ can be singled out in $T^{*}(S) \times T(S)$, on considering those pairs $\left(\tilde{Z}_{(h)}, Z^{(h)}\right)$ such that Eq. (9.4.9). holds. One may want to study these holomorphic maps in the course of writing contour-integral formulae for solutions of the massless free-field equations, where the integrand involves a homogeneous function $F$ acting on twistors and dual twistors. Omitting the details (see Penrose 1975), we only say that, when the space-time point $y$ under consideration does not lie on $C S$, one has to reinterpret $F$ as a function of $U_{(h)} \in T^{*}\left(S^{\prime}\right), X^{(h)} \in T\left(S^{\prime}\right)$, where the hypersurface $S^{\prime}$, or $C S^{\prime}$, is chosen to pass through the point $y$.

A naturally occurring question is how to deal with the one-form $\phi$ and the two-form $\omega$ introduced in section 9.3. Indeed, if the space-time is analytic, such forms $\phi$ and $\omega$ can be complexified. On making a complexification, two one-forms $\phi$ and $\widetilde{\phi}$ are obtained, which take the same values on $C N$, but whose functional forms are different. For $Z^{(h)} \in T(S), W_{(h)} \in T^{*}(S), X^{(h)} \in T(S), U_{(h)} \in T^{*}(S)$, $S$ and $S^{\prime}$ being two different hypersurfaces in $M$, one has (cf. Penrose 1975)

$$
\begin{equation*}
\omega=i d Z^{(h)} \wedge d W_{(h)}=i d X^{(h)} \wedge d U_{(h)} \tag{9.4.12}
\end{equation*}
$$

$$
\begin{equation*}
\phi=i Z^{(h)} d W_{(h)}=i X^{(h)} d U_{(h)} \tag{9.4.13}
\end{equation*}
$$

$$
\begin{equation*}
\tilde{\phi}=-i W_{(h)} d Z^{(h)}=-i U_{(h)} d X^{(h)} . \tag{9.4.14}
\end{equation*}
$$

Hence one is led to ask wether the passage from a $\left(W_{(h)}, Z^{(h)}\right)$ description on $S$ to a $\left(U_{(h)}, X^{(h)}\right)$ description on $S^{\prime}$ can be regarded as a canonical transformation. This is achieved on introducing the equivalence relations (Penrose 1975)

$$
\begin{align*}
& \left(W_{(h)}, Z^{(h)}\right) \equiv\left(\rho^{-1} W_{(h)}, \rho Z^{(h)}\right)  \tag{9.4.15}\\
& \left(U_{(h)}, X^{(h)}\right) \equiv\left(\sigma^{-1} U_{(h)}, \sigma X^{(h)}\right) \tag{9.4.16}
\end{align*}
$$

which yield a six-complex-dimensional space $S_{6}$ (see problem 9.2).

### 9.5 Asymptotic Twistors

Although in the theory of hypersurface twistors the complex structure plays a key role, their definition depends on an arbitrary hypersurface $S$, and the attempt to define the scalar product $Z^{(h)} W_{(h)}$ faces great difficulties. The concept of asymptotic twistor tries to overcome these limitations by focusing on asymptotically flat space-times. Hence the emphasis is on null hypersurfaces, i.e. SCRI ${ }^{+}$ and $\mathrm{SCRI}^{-}$(cf. section 3.5), rather than on spacelike hypersurfaces. Since the construction of hypersurface twistors is independent of conformal rescalings of the metric, while future and past null infinity have well-known properties (Hawking and Ellis 1973), the theory of asymptotic twistors appears well-defined. Its key features are as follows.

First, one complexifies future null infinity $I^{+}$to get $C I^{+}$. Hence its complexified metric is described by complexified coordinates $\eta \tilde{\eta}, u$, where $\eta$ and $\tilde{\eta}$ are totally independent (cf. section 3.5). The corresponding planes $\eta=$ constant, $\tilde{\eta}=$ constant, are totally null planes (in that the complexified metric of $\mathrm{CI}^{+}$ vanishes over them) with a topological twist (Penrose 1975).

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Second, note that for any null hypersurface, its normal has the spinor form

$$
\begin{equation*}
n^{A A^{\prime}}=\iota^{A} \tau^{A^{\prime}} \tag{9.5.1}
\end{equation*}
$$

Thus, if $\tau^{B^{\prime}} \pi_{B^{\prime}} \neq 0$, the insertion of (9.5.1) into (9.4.3) yields

$$
\begin{equation*}
\iota^{A} \pi^{A^{\prime}} \nabla_{A A^{\prime}} \pi_{C^{\prime}}=0 \tag{9.5.2}
\end{equation*}
$$

Similarly, if $\imath^{B} \tilde{\boldsymbol{\pi}}_{B} \neq 0$, the insertion of (9.5.1) into the Eq. (9.4.7) for dual hypersurface twistors leads to

$$
\begin{equation*}
\tilde{\pi}^{A} \tilde{\iota}^{A^{\prime}} \nabla_{A A^{\prime}} \tilde{\pi}_{C}=0 \tag{9.5.3}
\end{equation*}
$$

These equations tell us that the $\gamma$-curves are null geodesics on $C I^{+}$, lying entirely in the $\tilde{\boldsymbol{\eta}}=$ constant planes, while the $\bar{\gamma}$ curves are null geodesics lying in the $\eta=$ constant planes.

By definition, an asymptotic twistor is an element $Z^{(a)} \in T\left(I^{+}\right)$, and corresponds to a null geodesic $\gamma$ in $C I^{+}$with tangent vector $\mathrm{l}^{A} \pi^{A^{\prime}}$, where $\pi_{A^{\prime}}$ undergoes parallel propagation along $\gamma$. By contrast, a dual asymptotic twistor is an element $\widetilde{\boldsymbol{Z}}_{(a)} \in T^{*}\left(I^{+}\right)$, and corresponds to a null geodesic $\widetilde{\gamma}$ in $C I^{+}$with tangent vector $\tilde{\boldsymbol{\pi}}^{\boldsymbol{A}} \boldsymbol{\tau}^{\boldsymbol{A}^{\prime}}$, where $\tilde{\boldsymbol{\pi}}_{A}$ undergoes parallel propagation along $\overline{\boldsymbol{\gamma}}$.

It now remains to be seen how to define the scalar product $Z^{(a)} \widetilde{\boldsymbol{Z}}_{(a)}$. For this purpose, denoting by $\lambda$ the intersection of the $\tilde{\boldsymbol{\eta}}=$ constant plane containing $\gamma$ with the $\eta=$ constant plane containing $\bar{\gamma}$, we assume for simplicity that $\lambda$ intersects $C I^{+}$in such a way that a continuous path $\beta$ exists in $\gamma \cup \lambda \cup \tilde{\gamma}$, unique up to homotopy, connecting $Q \in \gamma$ to $\widetilde{Q} \in \tilde{\boldsymbol{\gamma}}$. One then gives a local twistor description of $Z^{(a)}$ as $\left(0, \pi_{A^{\prime}}\right)$ at $Q$, and one carries this along $\beta$ by local twistor transport (section 9.2) to $\widetilde{Q}$. At the point $\widetilde{Q}_{1}$ the local twistor obtained in this way has the usual scalar product with the local twistor description $\left(\tilde{\boldsymbol{\pi}}_{A}, 0\right)$ at $\widetilde{\boldsymbol{Q}}$ of $\tilde{\boldsymbol{Z}}_{(a)}$. By virtue of Eqs. (9.2.4)-(9.2.5) and (9.2.13), such a definition of scalar product is independent of the choice made to locate $Q$ and $\widetilde{Q}$, and it also applies on going from $\widetilde{Q}$ to $Q$. Thus, the theory of asymptotic twistors combines in an

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essential way the asymptotic structure of space-time with the properties of local twistors and hypersurface twistors. Note also that $Z^{(a)} \tilde{\boldsymbol{Z}}_{(a)}$ has been defined as a holomorphic function on some open subset of $T\left(I^{+}\right) \times T^{*}\left(I^{+}\right)$containing $C N\left(I^{+}\right)$. Hence one can take derivatives with respect to $Z^{(a)}$ and $\widetilde{\boldsymbol{Z}}_{(a)}$ so as to obtain the differential forms in (9.4.12)-(9.4.14). If $W_{(a)} \in T^{*}\left(\mathcal{I}^{+}\right), Z^{(a)} \in T\left(\mathcal{I}^{+}\right)$, $U_{(a)} \in T^{*}\left(\mathcal{I}^{-}\right), X^{(a)} \in T\left(\mathcal{I}^{-}\right)$, one can write

$$
\begin{gather*}
\omega=i d Z^{(a)} \wedge d W_{(a)}=i d X^{(a)} \wedge d U_{(a)}  \tag{9.5.4}\\
\phi=i Z^{(a)} d W_{(a)}=i X^{(a)} d U_{(a)}  \tag{9.5.5}\\
\tilde{\phi}=-i W_{(a)} d Z^{(a)}=-i U_{(a)} d X^{(a)} \tag{9.5.6}
\end{gather*}
$$

The asymptotic twistor space at future null infinity is also very useful in that its global complex structure enables one to study the outgoing radiation field arising from gravitation (Penrose 1975).

### 9.6 Penrose Transform

As we know from chapter four, on studying the massless free-field equations in Minkowski space-time, the Penrose transform provides the homomorphism (Eastwood 1990)

$$
\begin{equation*}
\mathcal{P}: H^{1}(V, \mathcal{O}(-n-2)) \rightarrow \Gamma\left(U, Z_{n}\right) \tag{9.6.1}
\end{equation*}
$$

With the notation in (9.6.1), $U$ is an open subset of compactified complexified Minkowski space-time, $V$ is the corresponding open subset of projective twistor space, $O(-n-2)$ is the sheaf of germs (appendix D$)$ of holomorphic functions homogeneous of degree $-n-2, Z_{n}$ is the sheaf of germs of holomorphic solutions of the massless free-field equations of helicity $\frac{n}{2}$. Although the Penrose transform may be viewed as a geometric way of studying the partial differential equations of mathematical physics, the main problem is to go beyond flat space-time and

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reconstruct a generic curved space-time out of its twistor space or out of some more general structures. Here, following Eastwood 1990, we study a four-complexdimensional conformal manifold $M$, which is assumed to be geodesically convex. For a given choice of spin-structure on $M$, let $F$ be the projective primed spinbundle over $M$ with local coordinates $x^{a}, \pi_{A^{\prime}}$. After choosing a metric in the conformal class, the corresponding metric connection is lifted horizontally to a differential operator $\nabla_{A L^{\prime}}$ on spinor fields on $F$.

Denoting by $\phi_{B}$ a spinor field on $M$ of conformal weight $w$, a conformal rescaling $\widehat{g}=\Omega^{2} g$ of the metric leads to a change of the operator according to the rule

$$
\begin{equation*}
\widehat{\nabla}_{A L^{\prime}} \phi_{B}=\nabla_{A L^{\prime}} \phi_{B}-Y_{B L^{\prime}} \phi_{A}+w Y_{A L^{\prime}} \phi_{B}+\pi_{L^{\prime}} Y_{A B^{\prime}} \frac{\partial \phi_{B}}{\partial \pi_{B^{\prime}}} \tag{9.6.2}
\end{equation*}
$$

where $Y_{A L^{\prime}} \equiv \Omega^{-1} \nabla_{A L^{\prime}} \Omega$. In particular, on functions of weight $w$ one finds

$$
\begin{equation*}
\widehat{\nabla}_{A L^{\prime}} \phi=\nabla_{A L^{\prime}} \phi+w Y_{A L^{\prime}} \phi+\pi_{L^{\prime}} Y_{A B^{\prime}} \frac{\partial \phi}{\partial \pi_{B^{\prime}}} \tag{9.6.3}
\end{equation*}
$$

Thus, if the conformal weight vanishes, acting with $\pi^{A^{\prime}}$ on both sides of (9.6.3) and defining

$$
\begin{equation*}
\nabla_{A} \equiv \pi^{A^{\prime}} \nabla_{A A^{\prime}} \tag{9.6.4}
\end{equation*}
$$

one obtains

$$
\begin{equation*}
\hat{\nabla}_{\boldsymbol{A}} \phi=\nabla_{\boldsymbol{A}} \phi . \tag{9.6.5}
\end{equation*}
$$

This means that $\nabla_{A}$ is a conformally invariant operator on ordinary functions and hence may be regarded as an invariant distribution on the projective spin-bundle $F$ (Eastwood 1990). From chapters four and six we know that such a distribution is integrable if and only if the self-dual Weyl spinor $\widetilde{\boldsymbol{\psi}}_{A^{\prime} B^{\prime} C^{\prime} D^{\prime}}$ vanishes. One can then integrate the distribution on $F$ to give a new space $P$ as the space of leaves. This leads to the double fibration familiar to the mathematicians working on twistor theory:

$$
\begin{equation*}
P \stackrel{\mu}{\stackrel{\mu}{\leftrightarrows}} \underset{\xrightarrow{\nu} M}{ } \text {. } \tag{9.6.6}
\end{equation*}
$$

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In (9.6.6) $P$ is the twistor space of $M$, and the submanifolds $v\left(\mu^{-1}(z)\right)$ of $M$, for $z \in P$, are the $\alpha$-surfaces in $M$ (cf. chapter four). Each point $x \in M$ is known to give rise to a line $L_{x} \equiv \mu\left(v^{-1}(x)\right)$ in $P$, whose points correspond to the $\alpha$-surfaces through $x$ as described in chapter four. The conformally anti-self-dual complex space-time $M$ with its conformal structure is then recovered from its twistor space $P$, and an explicit construction has been given in section 5.1.

To get a deeper understanding of this non-linear-graviton construction, we now introduce the Einstein bundle $E$. For this purpose, let us consider a function $\phi$ of conformal weight 1. Eq. (9.6.3) implies that, under a conformal rescaling of the metric, $\nabla_{A} \phi$ rescales as

$$
\begin{equation*}
\hat{\nabla}_{A} \phi=\nabla_{A} \phi+Y_{A} \phi . \tag{9.6.7}
\end{equation*}
$$

Thus, the transformation rule for $\nabla_{A} \nabla_{B} \phi$ is

$$
\begin{equation*}
\hat{\nabla}_{A} \hat{\nabla}_{B} \phi=\nabla_{A} \hat{\nabla}_{B} \phi-Y_{B} \hat{\nabla}_{A} \phi=\nabla_{A} \nabla_{B} \phi+\left[\left(\nabla_{A} Y_{B}\right)-Y_{B} Y_{A}\right] \phi . \tag{9.6.8}
\end{equation*}
$$

Although $\nabla_{A} \nabla_{B} \phi$ is not conformally invariant, Eq. (9.6.8) suggests how to modify our operator to make it into a conformally invariant operator. For this purpose, denoting by $\Phi_{A B A^{\prime} B^{\prime}}$ the trace-free part of the Ricci spinor, and defining

$$
\begin{equation*}
\Phi_{A B} \equiv \pi^{A^{\prime}} \pi^{B^{\prime}} \Phi_{A B A^{\prime} B^{\prime}} \tag{9.6.9}
\end{equation*}
$$

we point out that, under a conformal rescaling, $\Phi_{A B}$ transforms as

$$
\begin{equation*}
\widehat{\Phi}_{A B}=\Phi_{A B}-\nabla_{A} Y_{B}+Y_{A} Y_{B} . \tag{9.6.10}
\end{equation*}
$$

Eqs. (9.6.8) and (9.6.10) imply that the conformally invariant operator we are looking for is (Eastwood 1990)

$$
\begin{equation*}
D_{A B} \equiv \nabla_{A} \nabla_{B}+\Phi_{A B} \tag{9.6.11}
\end{equation*}
$$

acting on functions of weight 1 . In geometrical language, $\nabla_{A}$ and $D_{A B}$ act along the fibres of $\mu$. A vector bundle $E$ over $P$ is then obtained by considering the vector

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space of functions defined on $\mu^{-1} Z$ such that $D_{A B} \phi=0$ and having conformal weight 1 . Such a space is indeed three-dimensional, since $\alpha$-surfaces inherit from the conformal structure on $M$ a flat projective structure and $D_{A B}$ in (9.6.11) is a projectively invariant differential operator (Eastwood 1990, and earlier analysis by Bailey cited therein).

Remarkably, the Penrose transform establishes an isomorphism between the space of smooth sections $\Gamma(P, E)$ ( $E$ being our Einstein bundle on $P$ ) and the space of functions $\phi$ of conformal weight 1 on $M$ such that

$$
\begin{equation*}
\nabla_{(A}^{\left(A^{\prime}\right.} \nabla_{B)}^{\left.B^{\prime}\right)} \phi+\Phi_{A B}^{A^{\prime} B^{\prime}} \phi=0 \tag{9.6.12}
\end{equation*}
$$

The proof is obtained by first pointing out that, in the light of the definition of $E, \Gamma(P, E)$ is isomorphic to the space of functions $\phi$ of conformal weight 1 on the spin-bundle $F$ such that

$$
\begin{equation*}
\nabla_{A} \nabla_{B} \phi+\Phi_{A B} \phi=0 \tag{9.6.13}
\end{equation*}
$$

The next step is the remark that the fibres of $v: F \rightarrow M$ are Riemann spheres and hence are compact, which implies that $\phi\left(x^{a}, \pi_{A}\right)$ is a function of $x^{a}$ only. The resulting equation on the spin-bundle $F$ is

$$
\begin{equation*}
\pi^{A^{\prime}} \pi^{B^{\prime}} \nabla_{A A^{\prime}} \nabla_{B B^{\prime}} \phi+\pi^{A^{\prime}} \pi^{B^{\prime}} \Phi_{A B A^{\prime} B^{\prime}} \phi=0 \tag{9.6.14}
\end{equation*}
$$

At this stage, the contribution of $\pi^{A^{\prime}} \pi^{B^{\prime}}$ has been factorized, which implies we are left with Eq. (9.6.12). Conformal invariance of the equation on $M$ is guaranteed by the use of the conformally invariant operator $D_{A B}$.

From the point of view of gravitational physics, what is remarkable is the resulting isomorphism between nowhere vanishing sections of $E$ over $P$ and Einstein metrics in the conformal class on $M$. Of course, the Einstein condition means that the Ricci tensor is proportional to the metric, and hence the trace-free part of Ricci vanishes: $\Phi_{a b}=0$. To prove this basic property one points out that, since $\phi$ may be chosen to be nowhere vanishing, $\widehat{\phi}$ can be set to 1 , so that (9.6.13)

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implies $\widehat{\boldsymbol{\Phi}}_{a b}=0$, which is indeed the Einstein condition. The converse also holds (Eastwood 1990).

Moreover, a pairing between solutions of differential equations can be established. To achieve this, note first that the tangent bundle of $P$ corresponds to solutions of the differential equation (Eastwood 1990)

$$
\begin{equation*}
\nabla_{(A} \omega_{B)}=0 \tag{9.6.15}
\end{equation*}
$$

where $\omega_{B}$ is homogeneous of degree 1 in $\pi_{A^{\prime}}$ and has conformal weight 1 . Now the desired pairing is between solutions of (9.6.15) where $\omega_{B} \in \mathcal{O}_{\mathrm{B}}(-1)$ [1] as above, and solutions of

$$
\begin{equation*}
\nabla_{A} \nabla_{B} \phi+\Phi_{A B} \phi=0 \quad \phi \in \mathcal{O}[1] . \tag{9.6.16}
\end{equation*}
$$

Following again Eastwood 1990, we now consider a function $f$ which is conformally invariant, and constant along the fibres of $\mu: F \rightarrow P$. Since $f$ is defined as

$$
\begin{equation*}
f=2 \omega^{A} \nabla_{A} \phi-\phi \nabla_{A} \omega^{A}, \tag{9.6.17}
\end{equation*}
$$

its conformal invariance is proved by inserting (9.6.7) into the transformation rule

$$
\begin{equation*}
\widehat{f}=2 \omega^{A} \widehat{\nabla}_{A} \phi-\phi \widehat{\nabla}_{A} \omega^{A} \tag{9.6.18}
\end{equation*}
$$

The constancy of $f$ along the fibres of $\mu$ is proved in two steps. First, the Leibniz rule, Eq. (8.7.3) and Eq. (9.6.15) imply that

$$
\begin{equation*}
\nabla_{B} f=2 \omega^{A} \nabla_{B} \nabla_{A} \phi-\phi \nabla_{B} \nabla_{A} \omega^{A} . \tag{9.6.19}
\end{equation*}
$$

Second, using an identity for $\nabla_{B} \nabla_{A} \omega^{A}$ and then applying again (9.6.15) one finds (Eastwood 1990)

$$
\begin{equation*}
\nabla_{B} \nabla_{A} \omega^{A}=\epsilon_{B A} \Phi_{C}^{A} \omega^{C}+\frac{1}{2} \nabla_{A} \delta_{B}^{A} \nabla_{C} \omega^{C} \tag{9.6.20}
\end{equation*}
$$

which implies

$$
\begin{equation*}
\nabla_{B} \nabla_{A} \omega^{A}=-2 \Phi_{A B} \omega^{A} \tag{9.6.21}
\end{equation*}
$$

Thus, Eqs. (9.6.16), (9.6.19) and (9.6.21) lead to

$$
\begin{equation*}
\nabla_{B} f=2 \omega^{A}\left(\nabla_{A} \nabla_{B}+\Phi_{A B}\right) \phi=0 \tag{9.6.22}
\end{equation*}
$$

Q.E.D.

The results presented so far may be combined to show that an Einstein metric in the given conformal class on $M$ corresponds to a nowhere vanishing one-form $\tau$ on twistor space $P$, homogeneous of degree two (cf. chapter four). One then considers $\tau \Lambda d \tau$, which can be written as $2 \Lambda \rho$ for some function $\Lambda$. This $\Lambda$ is indeed the cosmological constant, since the holomorphic functions in $P$ are necessarily constant.

### 9.7 Ambitwistor Correspondence

In this section we consider again a complex space-time $(M, g)$, where $M$ is a four-complex-dimensional complex manifold, and $g$ is a holomorphic nondegenerate symmetric two-tensor on $M$ (i.e. a complex-Riemannian metric). A family of null geodesics can be associated to $(M, g)$ by considering those inextendible, connected, one-dimensional complex submanifolds $\gamma \subset M$ such that any tangent vector field $v \in \Gamma(\gamma, O(T \gamma))$ satisfies (Le Brun 1990)

$$
\begin{gather*}
\nabla_{v} v=\sigma v  \tag{9.7.1}\\
g(v, v)=0 \tag{9.7.2}
\end{gather*}
$$

where $\sigma$ is a proportionality parameter and $\nabla$ is the Levi-Civita connection of $g$. These curves determine completely the conformal class of the complex metric $g$, since a vector is null if and only if it is tangent to some null geodesic $\gamma$. Conversely, the conformal class determines the set of null geodesics (Le Brun 1990). We now

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denote by $N$ the set of null geodesics of $(M, g)$, and by $Q$ the hypersurface of null covectors defined by

$$
\begin{equation*}
\mathcal{Q} \equiv\left\{[\phi] \in P T^{*} \mathcal{M}: g^{-1}(\phi, \phi)=0\right\} \tag{9.7.3}
\end{equation*}
$$

A quotient map $q: Q \rightarrow N$ can be given as the map assigning, to each point of $Q$, the leaf through it. If $N$ is equipped with the quotient topology, and if $(M, g)$ is geodesically convex, $N$ is then Hausdorff and has a unique complex structure making $q$ a holomorphic map of maximal rank. The corresponding complex manifold $N$ is, by definition, the ambitwistor space of $(M, g)$.

Denoting by $p: Q \rightarrow M$ the restriction to $Q$ of the canonical projection $\pi: P T^{*} M \rightarrow M$, one has a holomorphic double fibration

$$
\begin{equation*}
\mathcal{N} \stackrel{q}{q}^{\mathcal{Q}} \xrightarrow{p} \mathcal{M} \tag{9.7.4}
\end{equation*}
$$

the ambitwistor correspondence, which relates complex space-time to its space of null geodesics. For example, in the case of the four-quadric $\mathrm{Q}_{4} \subset P_{5}$, obtained by conformal compactification of

$$
\left(C^{4}, \sum_{j=1}^{4}\left(d z^{j}\right)^{\otimes 2}\right)
$$

the corresponding ambitwistor space is (Le Brun 1990)

$$
\begin{equation*}
\mathcal{A} \equiv\left\{\left(\left[Z^{\alpha}\right],\left[W_{\alpha}\right]\right) \in P_{3} \times P_{3}: \sum_{\alpha=1}^{4} Z^{\alpha} W_{\alpha}=0\right\} \tag{9.7.5}
\end{equation*}
$$

Ambitwistor space has been used as an attempt to go beyond the space of $\alpha$ surfaces, i.e. twistor space (chapter four). However, we prefer to limit ourselves to a description of the main ideas, to avoid becoming too technical. Hence the reader is referred to Le Brun's original papers appearing in the bibliography for a thorough analysis of ambitwistor geometry.

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### 9.8 Radon Transform

In the mathematical literature, the analysis of the Penrose transform is frequently supplemented by the study of the Radon transform, and the former is sometimes referred to as the Radon-Penrose transform. Indeed, the transform introduced in Radon 1917 associates to a real-valued function $f$ on $R^{2}$ the following integral:

$$
\begin{equation*}
(R f)(L) \equiv \int_{L} f \tag{9.8.1}
\end{equation*}
$$

where $L$ is a straight line in $R^{2}$. On inverting the Radon and Penrose transforms, however, one appreciates there is a substantial difference between them (Bailey et al. 1994). In other words, (9.8.1) is invertible in that the value of the original function at a particular point may be recovered from its integrals along all cycles passing near that point. By contrast, in the Penrose transform, the original data in a neighbourhood of a particular cycle can be recovered from the transform restricted to that neighbourhood. Hence the Radon transform is globally invertible, while the Penrose transform may be inverted locally. [I am grateful to Mike Eastwood for making it possible for me to study the unfinished work appearing in Bailey et al. 1994. No original result obtained in Bailey et al. 1994 has been even mentioned in this section]

### 9.9 Massless Fields as Bundles

In the second part of chapter eight, motivated by our early work on one-loop quantum cosmology, we have studied secondary potentials for gravitino fields in curved Riemannian backgrounds with non-vanishing cosmological constant. Our analysis is a direct generalization of the work in Penrose 1994, where the author studies the Ricci-flat case and relies on the analysis of twisted photons appearing in

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Ward 1979. Thus, we here review the mathematical foundations of these potentials in the simpler case of Maxwell theory.

With the notation in Ward 1979, $B$ is the primed spin-bundle over space-time, and $\left(x^{a}, \pi_{A^{\prime}}\right)$ are coordinates on $B$. Of course, $x^{a}$ are space-time coordinates and $\pi_{A^{\prime}}$ are coordinates on primed spin-space. Moreover, we introduce the Euler vector field on $B$ :

$$
\begin{equation*}
T \equiv \pi^{A^{\prime}} \frac{\partial}{\partial \pi_{A^{\prime}}} \tag{9.9.1}
\end{equation*}
$$

A function $f$ on $B$ such that $T f=0$ is homogeneous of degree zero in $\pi_{A^{\prime}}$ and hence is defined on the projective spin-bundle. We are now interested in the twodimensional distribution spanned by the two vector fields $\pi^{A^{\prime}} \nabla_{\boldsymbol{A} A^{\prime}}$. The integral surfaces of such a distribution are the elements of non-projective twistor space $T$. To deform $T$ without changing $P T$, Ward replaced $\pi^{A^{\prime}} \boldsymbol{\nabla}_{\boldsymbol{A} \boldsymbol{A}^{\prime}}$ by $\boldsymbol{\pi}^{A^{\prime}} \boldsymbol{\nabla}_{\boldsymbol{A} \boldsymbol{A}^{\prime}-\boldsymbol{\psi}_{\boldsymbol{A}}} \boldsymbol{T}, \boldsymbol{\psi}_{\mathbf{0}}$ and $\psi_{1}$ being two functions on $B$. By virtue of Frobenius' theorem (cf. section 6.2), the necessary and sufficient condition for the integrability of the new distribution is the validity of the equation

$$
\begin{equation*}
\pi^{A^{\prime}} \nabla_{A A^{\prime}} \psi^{A}-\psi_{A} T \psi^{A}=0, \tag{9.9.2}
\end{equation*}
$$

for all values of $\pi^{A^{\prime}}$. In geometrical language, if (9.9.2) holds $\forall \pi^{\boldsymbol{A}^{\prime}}$, a fourdimensional space $T^{\prime}$ of integral surfaces exists, and $T^{\prime}$ is a holomorphic bundle over projective twistor space $P T$. One can also say that $T^{\prime}$ is a deformation of flat twistor space $T$. If $\psi_{A}$ takes the form

$$
\begin{equation*}
\psi_{A}\left(x, \pi_{A^{\prime}}\right)=i \Phi_{A} A^{\prime} \ldots L^{\prime}(x) \pi_{A^{\prime}} \ldots \pi_{L^{\prime}} \tag{9.9.3}
\end{equation*}
$$

then Eq. (9.9.2) becomes

$$
\begin{equation*}
\nabla^{A\left(A^{\prime}\right.} \Phi_{A}^{\left.B^{\prime} \ldots M^{\prime}\right)}=0 \tag{9.9.4}
\end{equation*}
$$

Thus, the spinor field $\boldsymbol{\Phi}_{\boldsymbol{A}} \boldsymbol{A}^{\boldsymbol{A}^{\prime} \ldots \boldsymbol{L}^{\prime}}$ is a potential for a massless free field

$$
\begin{equation*}
\phi_{A B \ldots M} \equiv \nabla_{(B}^{B^{\prime}} \ldots \nabla_{M}^{M^{\prime}} \Phi_{A) B^{\prime} \ldots M^{\prime}} \tag{9.9.5}
\end{equation*}
$$

since the massless free-field equations

$$
\begin{equation*}
\nabla^{A A^{\prime}} \phi_{A B \ldots M}=0 \tag{9.9.6}
\end{equation*}
$$

result from Eq. (9.9.4).
In the particular case of Maxwell theory, suppose that

$$
\begin{equation*}
\psi_{A}=i \Phi_{A}^{A^{\prime}}(x) \pi_{A^{\prime}} \tag{9.9.7}
\end{equation*}
$$

with (cf. (8.9.4))

$$
\begin{equation*}
\nabla^{A\left(A^{\prime}\right.} \Phi_{A}^{\left.B^{\prime}\right)}=0 \tag{9.9.8}
\end{equation*}
$$

Note that here the space $T^{\prime}$ of integral surfaces is a principal fibre bundle over $P T$ with group the non-vanishing complex numbers. Following Ward 1979, here PT is just the neighbourhood of a line in $C P^{3}$, but not the whole of $C P^{3}$.

For the mathematically-oriented reader, we should say that, in the language of sheaf cohomology, one has the exact sequence

$$
\begin{equation*}
\ldots \rightarrow H^{1}(P T, Z) \rightarrow H^{1}(P T, \mathcal{O}) \rightarrow H^{1}\left(P T, \mathcal{O}^{*}\right) \rightarrow H^{2}(P T, Z) \rightarrow \ldots \tag{9.9.9}
\end{equation*}
$$

If $P T$ has $R^{4} \times S^{2}$ topology (see chapter four), $H^{1}(P T, Z)=0$. Moreover, $H^{1}(P T, O)$ is isomorphic to the space of left-handed Maxwell fields $\phi_{A B}$ satisfying the massless free-field equations

$$
\begin{equation*}
\nabla^{\boldsymbol{A} \boldsymbol{A}^{\prime}} \phi_{A B}=0 \tag{9.9.10}
\end{equation*}
$$

$H^{1}\left(P T, O^{*}\right)$ is the space of line bundles over $P T$, and $H^{2}(P T, Z) \cong Z$ is the space of possible Chern classes of such bundles. Thus, the space of left-handed Maxwell fields is isomorphic to the space of deformed line bundles $T^{\prime}$. To realize this correspondence, we should bear in mind that a twistor determines an $\alpha$-surface, jointly with a primed spinor field $\pi_{A^{\prime}}$ propagated over the a-surface (chapter four). The usual propagation is parallel transport:

$$
\begin{equation*}
\pi^{A^{\prime}} \nabla_{A A^{\prime}} \pi_{B^{\prime}}=0 \tag{9.9.11}
\end{equation*}
$$

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However, in the deformed case, the propagation equation is taken to be

$$
\begin{equation*}
\pi^{A^{\prime}}\left(\nabla_{A A^{\prime}}+i \Phi_{A A^{\prime}}\right) \pi_{B^{\prime}}=0 \tag{9.9.12}
\end{equation*}
$$

Remarkably, the integrability condition for Eq. (9.9.12) is Eq. (9.9.8) (Ward 1979 and our problem 9.4). This property suggests that also Eq. (8.9.4) may be viewed as an integrability condition. In Penrose 1994, this geometrical interpretation has been investigated for spin- $\frac{3}{2}$ fields. It appears striking that the equations of the local theory of primary and secondary potentials lead naturally to equations which can be related to integrability conditions. Conversely, out of some suitable integrability conditions, one may hope of constructing a local theory of primary and secondary potentials for gauge fields. The interplay between these two points of view deserves further thinking.

### 9.10 Quantization of Field Theories

The boundary conditions studied in chapters seven and eight are a part of the boundary conditions which should be imposed on multiplets of bosonic and fermionic fields to respect BRST invariance and local supersymmetry. In this chapter devoted to mathematical foundations we describe some recent progress on these issues, but we do not repeat our early analysis appearing in Esposito 1994.

The way in which quantum fields respond to the presence of boundaries is responsible for many interesting physical effects such as, for example, the Casimir effect, and the quantization program of spinor fields, gauge fields and gravitation in the presence of boundaries is currently leading to a better understanding of modern quantum field theories. The motivations for this investigation come from at least three areas of physics and mathematics, i.e.
(i) Cosmology. One wants to understand what is the quantum state of the universe, and how to formulate boundary conditions for the universe (Esposito 1994 and references therein).
(ii) Field Theory. It appears necessary to get a deeper understanding of different quantization techniques in field theory, i.e. the reduction to physical degrees of freedom before quantization, or the Faddeev-Popov Lagrangian method, or the Batalin-Fradkin-Vilkovisky extended phase space. Moreover, perturbative properties of supergravity theories and conformal anomalies in field theory deserve further thinking, especially within the framework of semiclassical evaluation of path integrals in field theory via zeta-function regularization.
(iii) Mathematics. A (pure) mathematician may regard quantum cosmology as a problem in cobordism theory (i.e. when a compact manifold may be regarded as the boundary of another compact manifold), and one-loop quantum cosmology as a relevant application of the theory of eigenvalues in Riemannian geometry, of self-adjointness theory, and of the analysis of asymptotic heat kernels for manifolds with boundary.

On using zeta-function regularization (Esposito 1994), the $\zeta(0)$ value yields the scaling of quantum amplitudes and the one-loop divergences of physical theories. The choices to be made concern the quantization technique, the background four-geometry, the boundary three-geometry, the boundary conditions respecting Becchi-Rouet-Stora-Tyutin invariance and local supersymmetry, the gauge condition, the regularization algorithm. We are here interested in the mode-by-mode analysis of BRST-covariant Faddeev-Popov amplitudes for Euclidean Maxwell theory, which relies on the expansion of the electromagnetic potential in harmonics on the boundary three-geometry. In the case of three-sphere boundaries, one has (Esposito 1994)

$$
\begin{gather*}
A_{0}(x, \tau)=\sum_{n=1}^{\infty} R_{n}(\tau) Q^{(n)}(x)  \tag{9.10.1}\\
A_{k}(x, \tau)=\sum_{n=2}^{\infty}\left[f_{n}(\tau) S_{k}^{(n)}(x)+g_{n}(\tau) P_{k}^{(n)}(x)\right] \tag{9.10.2}
\end{gather*}
$$

where $Q^{(n)}(x), S_{k}^{(n)}(x)$ and $P_{k}^{(n)}(x)$ are scalar, transverse and longitudinal vector harmonics on $S^{3}$ respectively.

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Magnetic conditions set to zero at the boundary the gauge-averaging function, the tangential components of the potential, and the ghost field, i.e.

$$
\begin{equation*}
\left.\Phi(A)\right|_{\theta M}=0 \quad,\left.\quad A_{k}\right|_{\theta M}=0 \quad,\left.\quad \epsilon\right|_{\theta M}=0 . \tag{9.10.3}
\end{equation*}
$$

Alternatively, electric conditions set to zero at the boundary the normal component of the potential, the normal derivative of the ghost field, and the partial derivative with respect to $\tau$ of the tangential components of the potential, i.e.

$$
\begin{equation*}
\left.A_{0}\right|_{\partial M}=0 \quad,\left.\quad \frac{\partial \epsilon}{\partial n}\right|_{\partial M}=0 \quad,\left.\quad \frac{\partial A_{k}}{\partial \tau}\right|_{\partial M}=0 \tag{9.10.4}
\end{equation*}
$$

One may check that these boundary conditions are compatible with BRST transformations, and do not give rise to additional boundary conditions after a gauge transformation.

By using zeta-function regularization and flat Euclidean backgrounds, the effects of relativistic gauges are as follows (Esposito and Kamenshchik 1994, and references therein).
(i) In the Lorentz gauge, the mode-by-mode analysis of one-loop amplitudes agrees with the results of the Schwinger-DeWitt technique, both in the one-boundary case (i.e. the disk) and in the two-boundary case (i.e. the ring).
(ii) In the presence of boundaries, the effects of gauge modes and ghost modes do not cancel each other.
(iii) When combined with the contribution of physical degrees of freedom, i.e. the transverse part of the potential, this lack of cancellation is exactly what one needs to achieve agreement with the results of the Schwinger-DeWitt technique.
(iv) Thus, physical degrees of freedom are, by themselves, insufficient to recover the full information about one-loop amplitudes.
(v) Moreover, even on taking into account physical, non-physical and ghost modes, the analysis of relativistic gauges different from the Lorentz gauge yields gaugeinvariant amplitudes only in the two-boundary case.
(vi) Gauge modes obey a coupled set of second-order eigenvalue equations. For some particular choices of gauge conditions it is possible to decouple such a set of differential equations, by means of two functional matrices which diagonalize the original operator matrix.
(vii) For arbitrary choices of relativistic gauges, gauge modes remain coupled. The explicit proof of gauge invariance of quantum amplitudes becomes a problem in homotopy theory. Hence there seems to be a deep relation between the Atiyah-Patodi-Singer theory of Riemannian four-manifolds with boundary (Atiyah et al. 1976), the zeta-function, and the BKKM function (Barvinsky et al. 1992b):

$$
\begin{equation*}
I\left(M^{2}, s\right) \equiv \sum_{n=n_{0}}^{\infty} d(n) n^{-2 s} \log \left[f_{n}\left(M^{2}\right)\right] \tag{9.10.5}
\end{equation*}
$$

In (9.10.5), $d(n)$ is the degeneracy of the eigenvalues parametrized by the integer $n$, and $f_{n}\left(M^{2}\right)$ is the function occurring in the equation obeyed by the eigenvalues by virtue of boundary conditions, after taking out fake roots. The analytic continuation of $(9.10 .5)$ to the whole complex-s plane is given by

$$
\begin{equation*}
" I\left(M^{2}, s\right) "=\frac{I_{\text {pole }}\left(M^{2}\right)}{s}+I^{R}\left(M^{2}\right)+O(s) \tag{9.10.6}
\end{equation*}
$$

and enables one to evaluate $\zeta(0)$ as

$$
\begin{equation*}
\zeta(0)=I_{\mathrm{log}}+I_{\text {pole }}(\infty)-I_{\text {pole }}(0) \tag{9.10.7}
\end{equation*}
$$

$I_{\log }$ being the coefficient of $\log (M)$ appearing in $I^{R}$ as $M \rightarrow \infty$.
A detailed mode-by-mode study of perturbative quantum gravity about a flat Euclidean background bounded by two concentric three-spheres, including nonphysical degrees of freedom and ghost modes, leads to one-loop amplitudes in agreement with the covariant Schwinger-DeWitt method (Esposito, Kamenshchik et al. 1994). This calculation provides the generalization of the previous analysis of fermionic fields and electromagnetic fields (Esposito 1994). The basic idea is to expand the metric perturbations $h_{00}, h_{0 i}$ and $\mathrm{h}_{i j}$ on a family of three-spheres

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centred on the origin, and then use the de Donder gauge-averaging function in the Faddeev-Popov Euclidean action. The resulting eigenvalue equation for metric perturbations about a flat Euclidean background:

$$
\begin{equation*}
\square h_{\mu \nu}+\lambda h_{\mu \nu}=\mathbf{0}, \tag{9.10.8}
\end{equation*}
$$

gives rise to seven coupled eigenvalue equations for metric perturbations. On considering also the ghost one-form $\varphi_{\mu}$, and imposing the mixed boundary conditions for gauge-invariant amplitudes

$$
\begin{gather*}
\left.h_{i j}\right|_{\partial M}=\left.h_{i 0}\right|_{\partial M}=\left.\varphi_{0}\right|_{\partial M}=0  \tag{9.10.9}\\
\left.\left(\frac{\partial h_{00}}{\partial \tau}+\frac{6}{\tau} h_{00}-\frac{\partial}{\partial \tau}\left(g^{i j} h_{i j}\right)\right)\right|_{\partial M}=0  \tag{9.10.10}\\
\left.\left(\frac{\partial \varphi_{i}}{\partial \tau}-\frac{\varphi_{i}}{\tau}\right)\right|_{\partial M}=0 \tag{9.10.11}
\end{gather*}
$$

the analysis in Esposito, Kamenshchik et al. 1994 has shown that the full $\zeta(0)$ vanishes in the two-boundary problem, while the contributions of ghost modes and gauge modes do not cancel each other, as it already happens for Euclidean Maxwell theory.

The main open problem seems to be the explicit proof of gauge invariance of one-loop amplitudes for relativistic gauges, in the case of flat Euclidean space bounded by two concentric three-spheres. For this purpose, one may have to show that, for coupled gauge modes, $I_{\log }$ and the difference $I_{\text {pole }}(\infty)-I_{\text {pole }}(0)$ are not affected by a change in the gauge parameters. Three steps are in order:
(i) To relate the regularization at large $x$ used in Esposito 1994 to the BKKM regularization relying on (9.10.5).
(ii) To evaluate $I_{\log }$ from an asymptotic analysis of coupled eigenvalue equations.
(iii) To evaluate $I_{\text {pole }}(\infty)-I_{\text {pole }}(0)$ by relating the analytic continuation to the whole complex- $s$ plane of the difference $I(\infty, s)-I(0, s)$, to the analytic continuation of the zeta-function.

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The last step may involve a non-local, integral transform relating the ВККМ function to the zeta-function, and a non-trivial application of the Atiyah-PatodiSinger theory of Riemannian four-manifolds with boundary (Atiyah et al. 1976). In other words, one might have to prove that, in the two-boundary problem only, $I_{\text {pole }}(\infty)-I_{\text {pole }}(0)$ resulting from coupled gauge modes is the residue of a meromorphic function, invariant under a smooth variation in the gauge parameters of the matrix of elliptic self-adjoint operators appearing in the system

$$
\begin{array}{ll}
\widehat{\mathcal{A}}_{n} g_{n}+\widehat{\mathcal{B}}_{n} R_{n}=0, \quad \forall n \geq 2, \\
\widehat{\mathcal{C}}_{n} g_{n}+\widehat{\mathcal{D}}_{n} R_{n}=0, \quad \forall n \geq 2, \tag{9.10.13}
\end{array}
$$

where one has

$$
\begin{gather*}
\hat{\mathcal{A}}_{n} \equiv \frac{d^{2}}{d \tau^{2}}+\frac{1}{\tau} \frac{d}{d \tau}-\frac{\gamma_{3}^{2}}{\alpha} \frac{\left(n^{2}-1\right)}{\tau^{2}}+\lambda_{n},  \tag{9.10.14}\\
\widehat{\mathcal{B}}_{n} \equiv-\left(1+\frac{\gamma_{1} \gamma_{3}}{\alpha}\right)\left(n^{2}-1\right) \frac{d}{d \tau}-\left(1+\frac{\gamma_{2} \gamma_{3}}{\alpha}\right) \frac{\left(n^{2}-1\right)}{\tau},  \tag{9.10.15}\\
\widehat{\mathcal{C}}_{n} \equiv\left(1+\frac{\gamma_{1} \gamma_{3}}{\alpha}\right) \frac{1}{\tau^{2}} \frac{d}{d \tau}+\frac{\gamma_{3}}{\alpha}\left(\gamma_{1}-\gamma_{2}\right) \frac{1}{\tau^{3}},  \tag{9.10.16}\\
\widehat{\mathcal{D}}_{n} \equiv \frac{\gamma_{1}^{2}}{\alpha} \frac{d^{2}}{d \tau^{2}}+\frac{3 \gamma_{1}^{2}}{\alpha} \frac{1}{\tau} \frac{d}{d \tau}+\left[\frac{\gamma_{2}}{\alpha}\left(2 \gamma_{1}-\gamma_{2}\right)-\left(n^{2}-1\right)\right] \frac{1}{\tau^{2}}+\lambda_{n} . \tag{9.10.17}
\end{gather*}
$$

With our notation, $\gamma_{1}, \gamma_{2}$ and $\gamma_{3}$ are dimensionless parameters which enable one to study the most general gauge-averaging function. This may be written in the form (the boundary being given by three-spheres)

$$
\begin{equation*}
\Phi(A) \equiv \gamma_{1}{ }^{(4)} \nabla^{0} A_{0}+\frac{\gamma_{2}}{3} A_{0} \operatorname{Tr}(K)-\gamma_{3}{ }^{(3)} \nabla^{i} A_{i} \tag{9.10.18}
\end{equation*}
$$

where $K$ is the extrinsic-curvature tensor of the boundary.
Other relevant research problems are the mode-by-mode analysis of one-loop amplitudes for gravitinos, including gauge modes and ghost modes studied within the Faddeev-Popov formalism. Last, but not least, the mode-by-mode analysis of linearized gravity in the de Donder gauge in the one-boundary case, the unitary gauge for linearized gravity, and the mode-by-mode analysis of one-loop amplitudes

## 9. Underlying Mathematical Structures

in the case of curved backgrounds, appear to be necessary to complete the picture outlined so far. The recent progress on problems with boundaries, however, seems to strengthen the evidence in favour of new perspectives being in sight in quantum field theory.

## PROBLEMS FOR THE READER

Problem 1.1 Prove the complex-manifold structure of $C^{m}$, complex projective space $P_{m}(C)$,complex torus, orientable surfaces. What is the physical relevance of $P_{2}(C)$ and $P_{3}(C)$ ?

Problem 2.1Write down the Infeld-van der Waerden symbols for Lorentzian and for real Riemannian four-manifolds.

Problem 2.2 What is the relation between $S L(2, C)$ and $S U(2)$ soldering forms (cf. Ashtekar 1988) ?

Problem 2.3 Prove that unprimed and primed spin-spaces are no longer antiisomorphic if a Lorentzian four-dimensional space-time is replaced by a complex or real Riemannian four-manifold.

Problem 2.4Using the Euclidean conjugation defined in section 2.1, prove that there are no Majorana spinors in real Riemannian four-manifolds.

Problem 2.5Define a spinor conjugation in a pseudo-Riemannian four-manifold with a metric of signature (-,,,-++ . Can one find Majorana spinors in this manifold ?

Problem 2.6Give a two-spinor description of the Riemann curvature tensor in a pseudo-Riemannian four-manifold endowed with a metric of signature (,,,--++ ). Describe in detail the differences with respect to the Lorentzian or Riemannian formalisms.

Problem 2.7 Denoting by $\square$ the operator $\nabla_{C A^{\prime}} \nabla^{C A^{\prime}}$, prove that its action on solutions of the massless free-field equations is given by

$$
\begin{gather*}
\square \phi_{A}=-6 \Lambda \phi_{A},  \tag{P.1}\\
\square \varphi_{A B}=2 \psi_{A B C D} \varphi^{C D}-8 \Lambda \varphi_{A B} \tag{P.2}
\end{gather*}
$$

$$
\begin{gather*}
\square \varphi_{A B C}=4 \psi_{(A B}{ }^{M N} \varphi_{C) M N}-10 \Lambda \varphi_{A B C},  \tag{P.3}\\
\square \psi_{A B C D}=6 \psi_{(A B}{ }^{E F} \psi_{C D) E F}-12 \Lambda \psi_{A B C D} . \tag{P.4}
\end{gather*}
$$

Problem 3.1 Prove Eqs. (3.2.12)-(3.2.13).

Problem 4.1 Write the twistor equation (4.1.5) in terms of $\gamma$-matrices (Penrose 1975).

Problem 4.2To study the relation between null twistors and null geodesics, find the equation which replaces Eq. (4.1.27) if the geodesics $\gamma_{X}$ and $\gamma_{Y}$ are parallel.

Problem 4.3 What is the integrability condition for $\beta$-surfaces in a complex vacuum space-time?

Problem 4.4 Prove that, by virtue of the equations of local twistor transport, Eq. (4.3.25) holds.

Problem 5.1One wants to evaluate explicitly the conformal structure of an anti-self-dual space-time. For this purpose, following section 5.1, prove that the righthand side of Eq. (5.1.34) vanishes and complete the derivation of Eq. (5.1.42) therein.

Problem 5.2 Can you construct explicitly a self-dual space-time, by comparison with the work in section 5.1 on anti-self-dual space-times ?

Problem 5.3 Prove that the charge $Q$ in Eq. (5.3.26) is such that $D^{B B^{\prime}} Q=0$. What is the relation between Eqs. (5.3.24) and (5.3.26) ?

Problem 5.4Write a dissertation on (anti)-self-duality in Riemannian geometry, twistor theory and gauge theory.

Problem 6.1 Try to derive Eq. (6.4.2) by using the formulae relating curvature spinors of the Levi-Civita connection to torsion and curvature spinors of the $U_{4}$ connection.

Problem 6.2 Can you say how the integrability condition (6.4.2) for $\alpha$-surfaces in complex space-times with non-vanishing torsion is modified if the torsion tensor is completely antisymmetric ?

Problem 7.1 If the spinor field $\phi_{A}$ solves the Weyl equation $\nabla^{A A^{\prime}} \phi_{A}=0$, what can we say about $\nabla_{B} C^{\prime} \phi_{A}$ ?

Problem 8.1Prove that spin-raising and spin-lowering operators yield solutions of the massless free-field equations.

Problem 8.2 Check Eqs. (8.4.28)-(8.4.29).

Problem 8.3 Prove that Eq. (8.9.5) results from Eq. (8.9.4).
Problem 9.1 Following Penrose 1975 and chapter nine, write an essay on the various definitions of twistors in curved space-time.

Problem 9.2 Prove that, on the six-complex-dimensional space $S_{6}$ at the end of section $9.4, \omega$ is a non-degenerate, closed two-form which defines a symplectic structure (Penrose 1975).

Problem 9.3 Following Penrose 1975, differentiate $Z^{(a)} \widetilde{Z}_{(a)}$ in section 9.5 once independently with respect to $Z^{(a)}, \tilde{Z}_{(a)}$, and then set $\widetilde{Z}_{(a)}=\bar{Z}_{(a)}$ Prove that this defines a Hermitian metric tensor for the asymptotic twistor space at future null infinity. Moreover, prove that this construction makes $T\left(\mathcal{I}^{+}\right)$into a Kähler manifold.

Problem 9.4Prove that the integrability condition for Eq. (9.9.12) is indeed Eq. (9.9.8). Is it necessary to make assumptions on the conformal curvature ?

Problem 9.5 Is it possible to view Eq. (8.9.4) within the framework of integrability conditions relevant for twistor theory in Einstein backgrounds ?

## APPENDIX A: Clifford Algebras

In section 7.4 we have defined the total Dirac operator in Riemannian geometries as the first-order elliptic operator whose action on the sections is given by composition of Clifford multiplication with covariant differentiation. Following Ward and Wells 1990, this appendix presents a self-contained description of Clifford algebras and Clifford multiplication.

Let $V$ be a real vector space equipped with an inner product $<,>$, defined by a non-degenerate quadratic form of signature $(p, q)$. Let $T(V)$ be the tensor algebra of $V$ and consider the ideal $I$ in $T(V)$ generated by $x \otimes x+Q(x)$. By definition, $I$ consists of sums of terms of the kind $a \otimes\{x \otimes x+Q(x)\} \otimes b, x \in V, a, b \in T(V)$. The quotient space

$$
\begin{equation*}
C l(V) \equiv C l(V, Q) \equiv T(V) / \mathcal{I} \tag{A.1}
\end{equation*}
$$

is the Clifford algebra of the vector space $V$ equipped with the quadratic form $Q$. The product induced by the tensor product in $T(V)$ is known as Clifford multiplication or the Clifford product and is denoted by $x \cdot y$, for $x, y \in C l(V)$. The dimension of $C l(V)$ is $2^{n}$ if $\operatorname{dim}(V)=n$. A basis for $C l(V)$ is given by the scalar 1 and the products

$$
e_{i_{1}} \cdot e_{i_{2}} \cdot e_{i_{n}} \quad i_{1}<\ldots<i_{n}
$$

where $\left\{e_{1}, \ldots, e_{n}\right\}$ is an orthonormal basis for $V$. Moreover, the products satisfy

$$
\begin{gather*}
e_{i} \cdot e_{j}+e_{j} \cdot e_{i}=0 \quad i \neq j,  \tag{A.2}\\
e_{i} \cdot e_{i}=-2<e_{i}, e_{i}>\quad i=1, \ldots, n \tag{A.3}
\end{gather*}
$$

As a vector space, $C l(V)$ is isomorphic to $\Lambda^{*}(V)$, the Grassmann algebra, with

$$
e_{i_{1}} \ldots e_{i_{n}} \longrightarrow e_{i_{1}} \wedge \ldots \wedge e_{i_{n}}
$$

## Appendix A

There are two natural involutions on $C l(V)$. The first, denoted by $\alpha: C l(V) \rightarrow$ $C l(V)$, is induced by the involution $x \rightarrow-x$ defined on $V$, which extends to an automorphism of $C l(V)$. The eigenspace of $\alpha$ with eigenvalue +1 consists of the even elements of $C l(V)$, and the eigenspace of $\alpha$ of eigenvalue -1 consists of the odd elements of $C l(V)$.

The second involution is a mapping $x \rightarrow x^{t}$, induced on generators by

$$
\left(e_{i_{1}} \ldots e_{i_{p}}\right)^{t}=e_{i_{p}} \ldots e_{i_{1}}
$$

where $e_{i}$ are basis elements of $V$. Moreover, we define $x \rightarrow \bar{x}$, a third involution of $C l(V)$, by $\bar{x} \equiv \alpha\left(x^{t}\right)$.

One then defines $C l^{*}(V)$ to be the group of invertible elements of $C l(V)$, and the Clifford group $\Gamma(V)$ is the subgroup of $C l^{*}(V)$ defined by

$$
\begin{equation*}
\Gamma(V) \equiv\left\{x \in C l^{*}(V): y \in V \Rightarrow \alpha(x) y x^{-1} \in V\right\} \tag{A.4}
\end{equation*}
$$

One can show that the mapping $\rho(x): V \rightarrow V$ given by $\rho(x) y=\alpha(x) y x^{-1}$ is an isometry of $V$ with respect to the quadratic form $Q$. The mapping $x \rightarrow\|x\| \equiv x \overline{\boldsymbol{x}}$ is the square-norm mapping, and enables one to define a remarkable subgroup of the Clifford group, i.e.

$$
\begin{equation*}
\operatorname{Pin}(V) \equiv\{x \in \Gamma(V):\|x\|=1\} \tag{A.5}
\end{equation*}
$$

## APPENDIX B: Rarita-Schwinger Equations

Following Aichelburg and Urbantke 1981, one can express the $\Gamma$-potentials of (8.6.1) as (cf. (8.9.12))

$$
\begin{equation*}
\Gamma_{B B^{\prime}}^{A}=\nabla_{B B^{\prime}} \alpha^{A} . \tag{B.1}
\end{equation*}
$$

Thus, acting with $\nabla_{C C^{\prime}}$ on both sides of (B.1), symmetrizing over $C^{\prime} B^{\prime}$ and using the spinor Ricci identity (8.7.7), one finds

$$
\begin{equation*}
\nabla_{C\left(C^{\prime}\right.} \Gamma^{A C}{ }_{\left.B^{\prime}\right)}=\tilde{\Phi}_{B^{\prime} C^{\prime} L}{ }^{A} \alpha^{L} . \tag{B.2}
\end{equation*}
$$

Moreover, acting with $\nabla_{C}{ }^{C^{\prime}}$ on both sides of (B.1), putting $B^{\prime}=C^{\prime}$ (with contraction over this index), and using the spinor Ricci identity (8.7.4) leads to

$$
\begin{equation*}
\epsilon^{A B} \nabla_{(C}^{C^{\prime}} \Gamma_{|A| B) C^{\prime}}=-3 \Lambda \alpha_{C} \tag{B.3}
\end{equation*}
$$

Equations (B.1)-(B.3) rely on the conventions in Aichelburg and Urbantke 1981. However, to achieve agreement with the conventions in Penrose 1994 and in our book, the equations (8.6.3)-(8.6.6) are obtained by defining (cf. (B.1))

$$
\begin{equation*}
\Gamma_{B}{ }^{A}{ }_{B^{\prime}} \equiv \nabla_{B B^{\prime} \alpha^{A}}, \tag{B.4}
\end{equation*}
$$

and similarly for the $\gamma$-potentials of (8.6.2) (for the effect of torsion terms, see comments following equation (21) in Aichelburg and Urbantke 1981).

## APPENDIX C:Fibre Bundles

The basic idea in fibre-bundle theory is to deal with topological spaces which are locally, but not necessarily globally, a product of two spaces. This appendix begins with the definition of fibre bundles and the reconstruction theorem for bundles, jointly with a number of examples, following Nash and Sen 1983. A more formal presentation of some related topics is then given, for completeness.

A fibre bundle may be defined as the collection of the following five mathematical objects:
(1) A topological space $E$ called the total space.
(2) A topological space $X$, i.e. the base space, and a projection $\pi: E \rightarrow X$ of $E$ onto $X$.
(3) A third topological space $F$, i.e. the fibre.
(4) A group $G$ of homeomorphisms of $F$, called the structure group.
(5) A set $\left\{U_{\alpha}\right\}$ of open coordinate neighbourhoods which cover $X$. These reflect the local product structure of $E$. Thus, a homeomorphism $\phi_{\alpha}$ is given

$$
\begin{equation*}
\phi_{\alpha}: \pi^{-1}\left(U_{\alpha}\right) \rightarrow U_{\alpha} \times F \quad, \tag{C.1}
\end{equation*}
$$

such that the composition of the projection map $\pi$ with the inverse of $\phi_{\alpha}$ yields points of $U_{\alpha}$, i.e.

$$
\begin{equation*}
\pi \phi_{\alpha}^{-1}(x, f)=x \quad x \in U_{\alpha} \quad, \quad f \in F \tag{C.2}
\end{equation*}
$$

To see how this abstract definition works, let us focus on the Möbius strip, which can be obtained by twisting ends of a rectangular strip before joining them. In this case, the base space $X$ is the circle $S^{1}$, while the fibre $F$ is a line segment. For any $x \in X$, the action of $\pi^{-1}$ on $x$ yields the fibre over $x$. The structure group $G$ appears on going from local coordinates $\left(U_{\alpha}, \phi_{\alpha}\right)$ to local coordinates $\left(U_{\beta}, \phi_{\beta}\right)$.

## Appendix C

If $U_{\alpha}$ and $U_{\beta}$ have a non-empty intersection, then $\phi_{\alpha} 0 \phi_{\beta}^{-1}$ is a continuous invertible map

$$
\begin{equation*}
\phi_{\alpha} \circ \phi_{\beta}^{-1}:\left(U_{\alpha} \cap U_{\beta}\right) \times F \rightarrow\left(U_{\alpha} \cap U_{\beta}\right) \times F \tag{C.3}
\end{equation*}
$$

For fixed $x \in U_{\alpha} \cap U_{\beta}$, such a map becomes a map $h_{\alpha \beta}$ from $F$ to $F$. This is, by definition, the transition function, and yields a homeomorphism of the fibre $F$. The structure group $G$ of $E$ is then defined as the set of all these maps $h_{\alpha \beta}$ for all choices of local coordinates $\left(U_{\alpha}, \phi_{\alpha}\right)$. Here, it consists of just two elements $\{e, h\}$. This is best seen on considering the covering $\left\{U_{\alpha}\right\}$ which is given by two open arcs of $S^{1}$ denoted by $U_{1}$ and $U_{2}$. Their intersection consists of two disjoint open $\operatorname{arcs} A$ and $B$, and hence the transition functions $h_{\alpha \beta}$ are found to be

$$
\begin{gather*}
h_{12}(x)=e \quad \text { if } \quad x \in A \quad, \quad h \quad \text { if } \quad x \in B  \tag{C.4}\\
h_{12}(x)=h_{21}^{-1}(x)  \tag{C.5}\\
h_{11}(x)=h_{22}(x)=e \tag{C.6}
\end{gather*}
$$

To detect the group $G=\{e, h\}$ it is enough to move the fibre once round the Möbius strip. By virtue of this operation, $F$ is reflected in its midpoint, which implies that the group element $h$ is responsible for such a reflection. Moreover, on squaring up the reflection one obtains the identity $e$, and hence $G$ has indeed just two elements.

So far, our definition of a bundle involves the total space, the base space, the fibre, the structure group and the set of open coordinate neighbourhoods covering the base space. However, the essential information about a fibre bundle can be obtained from a smaller set of mathematical objects, i.e. the base space, the fibre, the structure group and the transition functions $h_{\alpha \beta}$. Following again Nash and Sen 1983 we now prove the reconstruction theorem for bundles, which tells us how to obtain the total space $E$, the projection map $\pi$ and the homeomorphisms $\phi_{\alpha}$ out of $\left(X, F, G,\left\{h_{\alpha \beta}\right\}\right)$.

## Appendix $C$

First, $E$ is obtained out of an equivalence relation, as follows. One considers the set $\tilde{E}$ defined as the union of all products of the form $U_{\alpha} \times F$, i.e.

$$
\begin{equation*}
\widetilde{E} \equiv \bigcup_{\alpha} U_{\alpha} \times F \tag{C.7}
\end{equation*}
$$

One here writes $(x, f)$ for an element of $\widetilde{\boldsymbol{E}}$, where $x \in U_{\alpha}$. An equivalence relation $\sim$ is then introduced by requiring that, given $(x, f) \in U_{\alpha} \times F$ and $\left(x^{\prime}, f^{\prime}\right) \in U_{\beta} \times F$, these elements are equivalent,

$$
\begin{equation*}
(x, f) \sim\left(x^{\prime}, f^{\prime}\right) \tag{C.8}
\end{equation*}
$$

if

$$
\begin{equation*}
x=x^{\prime} \quad \text { and } \quad h_{\alpha \beta}(x) f=f^{\prime} . \tag{C.9}
\end{equation*}
$$

This means that the transition functions enable one to pass from $f$ to $f^{\prime}$, while the points $x$ and $x^{\prime}$ coincide. The desired total space $E$ is hence given as

$$
\begin{equation*}
E \equiv \tilde{E} / \sim \tag{C.10}
\end{equation*}
$$

i.e. $E$ is the set of all equivalence classes under $\sim$.

Second, denoting by $[(x, f)]$ the euivalence class containing the element $(x, f)$ of $U_{\alpha} \times F$, the projection $\pi: E \rightarrow X$ is defined as the map

$$
\begin{equation*}
\pi:[(x, f)] \rightarrow x \tag{C.11}
\end{equation*}
$$

In other words, $\pi$ maps the equivalence class $[(x, f)]$ to $x \in \mathcal{U}_{\alpha}$.
Third, the function $\phi_{\alpha}$ is defined (indirectly) by giving its inverse

$$
\begin{equation*}
\phi_{\alpha}^{-1}: U_{\alpha} \times F \rightarrow \pi^{-1}\left(U_{\alpha}\right) \tag{C.12}
\end{equation*}
$$

Note that, by construction, $\phi_{\alpha}^{-1}$ satisfies the condition

$$
\begin{equation*}
\pi \phi_{\alpha}^{-1}(x, f)=x \in U_{\alpha} \tag{C.13}
\end{equation*}
$$

and this is what we actually need, despite one might be tempted to think in terms of $\phi_{\alpha}$ rather than its inverse.

## Appendix C

The readers who are not familiar with fibre-bundle theory may find it helpful to see an application of this reconstruction theorem. For this purpose, we focus again on the Möbius strip. Thus, our data are the base $X=S^{1}$, a line segment representing the fibre, the structure group $\{e, h\}$, where $h$ is responsible for $F$ being reflected in its midpoint, and the transition functions $h_{\alpha \beta}$ in (C.4)-(C.6). Following the definition (C.8)-(C.9) of equivalence relation, and bearing in mind that $h_{12}=h$, one finds

$$
\begin{align*}
& f=f^{\prime} \text { if } x \in A,  \tag{C.14}\\
& h f=f^{\prime} \text { if } x \in B, \tag{C.15}
\end{align*}
$$

where $A$ and $B$ are the two open arcs whose disjoint union gives the intersection of the covering arcs $U_{1}$ and $U_{2}$. In the light of (C.14)-(C.15), if $x \in A$ then the equivalence class $[(x, f)]$ consists of $(x, f)$ only, whereas, if $x \in B,[(x, f)]$ consists of two elements, i.e. $(x, f)$ and $(x, h f)$. Hence it should be clear how to construct the total space $E$ by using equivalence classes, according to (C.10). What happens can be divided into three steps (Nash and Sen 1983):
(i) The base space splits into two, and one has the covering arcs $U_{1}, \mathrm{U}_{2}$ and the intersection regions $A$ and $B$.
(ii) The space $\widetilde{\boldsymbol{E}}$ defined in (C.7) splits into two. The regions $A \cap F$ are glued together without a twist, since the equivalence class $[(x, f)]$ has only the element $(x, f)$ if $x \in A$. By contrast, a twist is necessary to glue together the regions $B \cap F$, since $[(x, f)]$ consists of two elements if $x \in B$. The identification of $(x, f)$ and ( $x, h f$ ) under the action of $\sim$, makes it necessary to glue with twist the regions $B \cap F$.
(iii) The bundle $E \equiv \tilde{\boldsymbol{E}} / \sim$ has been obtained. Shaded regions may be drawn, which are isomorphic to $A \cap F$ and $B \cap F$ respectively.

If we now come back to the general theory of fibre bundles, we should mention some important properties of the transition functions $h_{\alpha \beta}$. They obey a set of

## Appendix C

compatibility conditions, where repeated indices are not summed over, i.e.

$$
\begin{gather*}
h_{\alpha \alpha}(x)=e \quad, \quad x \in U_{\alpha},  \tag{C.16}\\
h_{\alpha \beta}(x)=\left(h_{\beta \alpha}(x)\right)^{-1} \quad, \quad x \in U_{\alpha} \cap U_{\beta} \quad,  \tag{C.17}\\
h_{\alpha \beta}(x) h_{\beta \gamma}(x)=h_{\alpha \gamma}(x) \quad, \quad x \in U_{\alpha} \cap U_{\beta} \cap U_{\gamma} . \tag{C.18}
\end{gather*}
$$

A simple calculation can be now made which shows that any bundle can be actually seen as an equivalence class of bundles. The underlying argument is as follows. Suppose two bundles $E$ and $E^{\prime}$ are given, with the same base space, fibre, and group. Moreover, let $\left\{\phi_{\alpha}, U_{\alpha}\right\}$ and $\left\{\psi_{\alpha}, U_{\alpha}\right\}$ be the sets of coordinates and coverings for $E$ and $E^{\prime}$ respectively. The map

$$
\lambda_{\alpha} \equiv \phi_{\alpha} \circ \psi_{\alpha}^{-1}: U_{\alpha} \times F \rightarrow U_{\alpha} \times F
$$

is now required to be a homeomorphism of $F$ belonging to the structure group $G$. Thus, if one combines the definitions

$$
\begin{align*}
& \lambda_{\alpha}(x) \equiv \phi_{\alpha} \circ \psi_{\alpha}^{-1}(x)  \tag{C.19}\\
& h_{\alpha \beta}(x) \equiv \phi_{\alpha} \circ \phi_{\beta}^{-1}(x)  \tag{C.20}\\
& h_{\alpha \beta}^{\prime}(x) \equiv \psi_{\alpha} \circ \psi_{\beta}^{-1}(x) \tag{C.21}
\end{align*}
$$

one finds

$$
\begin{equation*}
\lambda_{\alpha}^{-1}(x) h_{\alpha \beta}(x) \lambda_{\beta}(x)=\psi_{\alpha} \circ \phi_{\alpha}^{-1} \circ \phi_{\alpha} \circ \phi_{\beta}^{-1} \circ \phi_{\beta} \circ \psi_{\beta}^{-1}(x)=h_{\alpha \beta}^{\prime}(x) \tag{C.22}
\end{equation*}
$$

Thus, since $\lambda_{\alpha}$ belongs to the structure group $G$ by hypothesis, as the transition function $h_{\alpha \beta}$ varies, both $\lambda_{\alpha}^{-1} h_{\alpha \beta} \lambda_{\beta}$ and $h_{\alpha \beta}^{\prime}$ generate all elements of $G$. The only difference between the bundles $E$ and $E^{\prime}$ lies in the assignment of coordinates, and the equivalence of such bundles is expressed by (C.22). The careful reader may have noticed that in our argument the coverings of the base space for $E$ and $E^{\prime}$ have been taken to coincide. However, this restriction is unnecessary. One may instead consider coordinates and coverings given by $\left\{\phi_{\alpha}, U_{\alpha}\right\}$ for $E$, and by

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$\left\{\psi_{\alpha}, \mathrm{V}_{\alpha}\right\}$ for $E^{\prime}$. The equivalence of $E$ and $E^{\prime}$ is then defined by requiring that the homeomorphism $\phi_{\alpha} 0 \psi_{\beta}-1(x)$ should coincide with an element of the structure group $G$ for $x \in U_{\alpha} \cap V_{\beta}$ (Nash and Sen 1983).

Besides the Möbius strip, the naturally occurring examples of bundles are the tangent and cotangent bundles and the frame bundle. The tangent bundle $T(M)$ is defined as the collection of all tangent spaces $T_{p}(M)$, for all points $p$ in the manifold $M$, i.e.

$$
\begin{equation*}
T(M) \equiv \bigcup_{p \in M} T_{p}(M) \tag{C.23}
\end{equation*}
$$

By construction, the base space is $M$ itself, and the fibre at $p \in M$ is the tangent space $T p(M)$. Moreover, the projection map $\pi: T(M) \rightarrow M$ associates to any tangent vector $\in T_{p}(M)$ the point $p \in M$. Note that, if $M$ is $n$-dimensional, the fibre at $p$ is an $n$-dimensional vector space isomorphic to $R^{n}$. The local product structure of $T(M)$ becomes evident if one can construct a homeomorphism $\phi_{\alpha}$ : $\pi^{-1}\left(U_{\alpha}\right) \rightarrow U_{\alpha} \times R^{n}$. Thus, we are expressing $T(M)$ in terms of points of $M$ and tangent vectors at such points. This is indeed the case since, for a tangent vector $V$ at $p$, its expression in local coordinates is

$$
\begin{equation*}
V=\left.b^{i}(p) \frac{\partial}{\partial x^{i}}\right|_{p} \tag{C.24}
\end{equation*}
$$

Hence the desired $\phi_{\alpha}$ has to map $V$ to the pair $\left(p, b^{i}(p)\right)$. Moreover, the structure group is the general linear group $G L(n, R)$, whose action on elements of the fibre should be viewed as the action of a matrix on a vector.

The frame bundle of $M$ requires taking a total space $B(M)$ as the set of all frames at all points in $M$. Such (linear) frames $b$ at $x \in M$ are, of course, an ordered set $\left(b_{1}, b_{2}, \ldots, b_{n}\right)$ of basis vectors for the tangent space $T_{x}(M)$. The projection $\pi: B(\mathrm{M}) \rightarrow M$ acts by mapping a base $b$ into the point of $M$ to which $b$ is attached. Denoting by $u$ an element of $G L(n, R)$, the $G L(n, R)$ action on $B(M)$ is defined by

$$
\begin{equation*}
\left(b_{1}, \ldots, b_{n}\right) u \equiv\left(b_{j} u_{j 1}, \ldots, b_{j} u_{j n}\right) \tag{C.25}
\end{equation*}
$$

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The coordinates for a differentiable structure on $B(M)$ are $\left(\boldsymbol{x}^{\mathbf{1}}, \ldots, \boldsymbol{x}^{\boldsymbol{n}} ; \boldsymbol{u}_{\boldsymbol{i}}^{\boldsymbol{j}}\right)$, where $x^{1}, \ldots, x^{n}$ are coordinate functions in a coordinate neighbourhood $V \subset M$, while $u_{i}^{j}$ appear in the representation of the map

$$
\begin{equation*}
\gamma: V \times G L(n, R) \rightarrow \mathrm{p}^{-1}(V) \tag{C.26}
\end{equation*}
$$

by means of the rule (Isham 1989)

$$
(x, u) \rightarrow\left(u_{1}^{j}\left(\partial_{j}\right)_{x}, \ldots, u_{n}^{j}\left(\partial_{j}\right)_{x}\right)
$$

To complete our introduction to fibre bundles, we now define cross-sections, sub-bundles, vector bundles, and connections on principal bundles, following Isham 1989.
(i) Cross-sections are very important from the point of view of physical applications, since in classical field theory the physical fields may be viewed as sections of a suitable class of bundles. The idea is to deal with functions defined on the base space and taking values in the fibre of the bundle. Thus, given a bundle ( $E, \pi, M$ ), a cross-section is a map $s: M \rightarrow E$ such that the image of each point $x \in M$ lies in the fibre $\pi^{-1}(x)$ over $x$ :

$$
\begin{equation*}
\pi \mathrm{o} s=\operatorname{id}_{M} \tag{C.27}
\end{equation*}
$$

In other words, one has the projection map from $E$ to $M$, and the cross-section from $M$ to $E$, and their composition yields the identity on the base space. In the particular case of a product bundle, a cross-section defines a unique function $\widehat{s}: M \rightarrow F$ given by

$$
\begin{equation*}
s(x)=(x, \widehat{s}(x)) \quad, \quad \forall x \in M \tag{C.28}
\end{equation*}
$$

(ii) The advantage of introducing the sub-bundle $E^{\prime}$ of a given bundle $E$ lies in the possibility to refer to a mathematical structure less complicated than the original $E^{\prime}$. Let $(E, \pi, M)$ be a fibre bundle with fibre $F$. A sub-bundle of $(E, \pi, M)$ is a sub-space of $E$ with the extra property that it always contains complete fibres

## Appendix $C$

of $E$, and hence is itself a fibre bundle. The formal definition demands that the following conditions on $\left(E^{\prime}, \pi^{\prime}, M^{\prime}\right)$ should hold:

$$
\begin{gather*}
E^{\prime} \subset E  \tag{C.29}\\
M^{\prime} \subset M  \tag{C.30}\\
\pi^{\prime}=\left.\pi\right|_{E} \tag{C.31}
\end{gather*}
$$

In particular, if $T \equiv(E, \pi, M)$ is a sub-bundle of the product bundle $(M \times$ $\left.F, \mathrm{pr}_{1}, M\right)$, then cross-sections of $T$ have the form $s(x)=(x, \widehat{\boldsymbol{s}}(x))$, where $\widehat{\boldsymbol{s}}$ : $M \rightarrow F$ is a function such that, $\forall x \in M,(x, \widehat{s}(x)) \in E$. For example, the tangent bundle $T S^{n}$ of the $n$-sphere $S^{n}$ may be viewed as the sub-bundle of $S^{n} \times R^{n+1}$ (Isham 1989)

$$
\begin{equation*}
E\left(T S^{n}\right) \approx\left\{(x, y) \in S^{n} \times R^{n+1}: x \cdot y=0\right\} \tag{C.32}
\end{equation*}
$$

Cross-sections of $T S^{n}$ are vector fields on the $n$-sphere. It is also instructive to introduce the normal bundle $v\left(S^{n}\right)$ of $S^{n}$, i.e. the set of all vectors in $R^{n+1}$ which are normal to points on $\mathrm{S}^{n}$ (Isham 1989):

$$
\begin{equation*}
E\left(\nu\left(S^{n}\right)\right) \equiv\left\{(x, y) \in S^{n} \times R^{n+1}: \exists k \in R: y=k x\right\} \tag{C.33}
\end{equation*}
$$

(iii) In the case of vector bundles, the fibres are isomorphic to a vector space, and the space of cross-sections has the structure of a vector space. Vector bundles are relevant for theoretical physics, since gauge theory may be formulated in terms of vector bundles (Ward and Wells 1990), and the space of cross-sections can replace the space of functions on a manifold (although, in this respect, the opposite point of view may be taken). By definition, a $n$-dimensional real (resp. complex) vector bundle $(E, \pi, M)$ is a fibre bundle in which each fibre is isomorphic to a $n$-dimensional real (resp. complex) vector space. Moreover, $\forall x \in M$, a neighbourhood $U \subset M$ of $x$ exists, jointly with a local trivialization $\rho: U \times R^{n} \rightarrow \pi^{-1}(U)$ such that, $\forall y \in U, \rho:\{y\} \times R^{n} \rightarrow \pi^{-1}(y)$ is a linear map.

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The simplest examples are the product space $M \times R^{n}$, and the tangent and cotangent bundles of a manifold $M$. A less trivial example is given by the normal bundle (cf. (C.33)). If $M$ is a $m$-dimensional sub-manifold of $R^{n}$, its normal bundle is a $(n-m)$-dimensional vector bundle $v(M)$ over $M$, with total space (Isham 1989)

$$
\begin{equation*}
E(\nu(M)) \equiv\left\{(x, v) \in M \times R^{n}: v \cdot w=0, \forall w \in T_{x}(M)\right\} \tag{C.34}
\end{equation*}
$$

and projection map $\pi: E(v(M)) \rightarrow M$ defined by $\pi(x, v) \equiv x$. Last, but not least, we should mention the canonical real line bundle $\gamma_{n}$ over the real projective space $R P^{n}$, with total space

$$
\begin{equation*}
E\left(\gamma_{n}\right) \equiv\left\{([x], v) \in R P^{n} \times R^{n+1}: v=\lambda x, \lambda \in R\right\}, \tag{C.35}
\end{equation*}
$$

where $[x]$ denotes the line passing through $x \in R^{n+1}$. The projection map $\pi$ : $E\left(\gamma_{n}\right) \rightarrow R P^{n}$ is defined by the condition

$$
\begin{equation*}
\pi([x], v) \equiv[x] . \tag{C.36}
\end{equation*}
$$

Its inverse is therefore the line in $R^{n+1}$ passing through $x$. Note that $\gamma_{n}$ is a one-dimensional vector bundle.
(iv) In Nash and Sen 1983, principal bundles are defined by requiring that the fibre $F$ should be (isomorphic to) the structure group. However, a more precise definition, such as the one given in Isham 1989, relies on the theory of Lie groups. Since it is impossible to describe such a theory in a short appendix, we refer the reader to Isham 1989 and references therein for the theory of Lie groups, and we limit ourselves to the following definitions.

A bundle $(E, \pi, M)$ is a $G$-bundle if $E$ is a right $G$-space and if $(E, \pi, M)$ is isomorphic to the bundle $(E, \sigma, E / G)$, where $E / G$ is the orbit space of the $G$ action on $E$, and $\sigma$ is the usual projection map. Moreover, if $G$ acts freely on $E$, then $(E, \pi, M)$ is said to be a principal $G$-bundle, and $G$ is the structure group of the bundle. Since $G$ acts freely on $E$ by hypothesis, each orbit is homeomorphic to $G$, and hence one has a fibre bundle with fibre $G$ (see earlier remarks).

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To define connections in a principal bundle, with the associated covariant differentiation, one has to look for vector fields on the bundle space $P$ that point from one fibre to another. The first basic remark is that the tangent space $T_{p}(P)$ at a point $p \in P$ admits a natural direct-sum decomposition into two sub-spaces $V_{p}(P)$ and $H_{p}(P)$, and the connection enables one to obtain such a split of $T_{p}(P)$. Hence the elements of $T_{p}(P)$ are uniquely decomposed into a sum of components lying in $V_{p}(P)$ and $H_{p}(P)$ by virtue of the connection. The first sub-space, $V_{p}(P)$, is defined as

$$
\begin{equation*}
V_{p}(P) \equiv\left\{t \in T_{p}(P): \pi_{*} t=0\right\} \tag{C.37}
\end{equation*}
$$

where $\pi: P \rightarrow M$ is the projection map from the total space to the base space. The elements of $V_{p}(P)$ are, by construction, vertical vectors in that they point along the fibre. The desired vectors, which point away from the fibres, lie instead in the horizontal sub-space $H_{p}(P)$. By definition, a connection in a principal bundle $P \rightarrow M$ with group $G$ is a smooth assignment, to each $p \in P$, of a horizontal sub-space $H_{p}(P)$ of $T_{p}(P)$ such that

$$
\begin{equation*}
T_{p}(P) \approx V_{p}(P) \oplus H_{p}(P) \tag{C.38}
\end{equation*}
$$

By virtue of (C.38), a connection is also called, within this framework, a distribution. Moreover, the decomposition (C.38) is required to be compatible with the right action of $G$ on $P$.

The constructions outlined in this appendix are the first step towards a geometrical and intrinsic formulation of gauge theories, and they are frequently applied also in twistor theory (sections 5.1-5.3, 9.6-9.7). Thus, despite the incompleteness, we hope that the reader will find them useful.

## APPENDIX D: Sheaf Theory

In chapter four we have given an elementary introduction to sheaf cohomology. However, to understand the language of section 9.6, it may be helpful to supplement our early treatment by some more precise definitions. This is here achieved by relying on Chern 1979.

The definition of a sheaf of Abelian groups involves two topological spaces $S$ and $M$, jointly with a map $\pi: S \rightarrow M$. The sheaf of Abelian groups is then the pair $(S, \pi)$ such that:
(i) $\pi$ is a local homeomorphism;
(ii) $\forall x \in M$, the set $\pi^{-1}(x)$, i.e. the stalk over $x$, is an Abelian group;
(iii) the group operations are continuous in the topology of $S$.

Denoting by $U$ an open set of $M$, a section of the sheaf $S$ over $U$ is a continuous map $f: U \rightarrow S$ such that its composition with $\pi$ yields the identity (cf. appendix C). The set $\Gamma(U, S)$ of all (smooth) sections over $U$ is an Abelian group, since if $f, g \in \Gamma(U, S)$, one can define $f-g$ by the condition $(f-g)(x) \equiv f(x)-g(x), x \in U$. The zero of $\Gamma(U, S)$ is the zero section assigning the zero of the stalk $\pi^{-1}(x)$ to every $x \in U$.

The following step is the definition of presheaf of Abelian groups over $M$. This is obtained on considering the homomorphism between sections over $U$ and sections over $V$, for $V$ an open subset of $U$. More precisely, by a presheaf of Abelian groups over $M$ we mean (Chern 1979):
(i) a basis for the open sets of $M$;
(ii) an Abelian group $S_{U}$ assigned to each open set $U$ of the basis;
(iii) a homomorphism $\rho_{V U}: S_{U} \rightarrow S_{V}$ associated to each inclusion $V \subset U$, such that

$$
\rho_{W V} \rho V U=\rho_{W U} \quad \text { whenever } \quad W \subset V \subset U .
$$

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The sheaf is then obtained from the presheaf by a limiting procedure (cf. chapter four).

For a given complex manifold $M$, the following sheaves play a very important role (cf. section 9.6):
(i) The sheaf $A_{p q}$ of germs of complex-valued $C^{\infty}$ forms of type ( $p, q$ ). In particular, the sheaf of germs of complex-valued $C^{\infty}$ functions is denoted by $A_{00}$.
(ii) The sheaf $C_{p}{ }_{q}$ of germs of complex-valued $C^{\infty}$ forms of type ( $p, q$ ), closed under the operator $\overline{\boldsymbol{\jmath}}$. The sheaf of germs of holomorphic functions (i.e. zero-forms) is denoted by $\mathcal{O}=C_{00}$. This is the most important sheaf in twistor theory (as well as in the theory of complex manifolds, cf. Chern 1979).
(iii) The sheaf $\mathcal{O}^{*}$ of germs of nowhere-vanishing holomorphic functions. The group operation is the multiplication of germs of holomorphic functions.

Following again Chern 1979, we complete this brief review by introducing fine sheaves. They are fine in that they admit a partition of unity subordinate to any locally finite open covering, and play a fundamental role in cohomology, since the corresponding cohomology groups $H^{q}(M, S)$ vanish $\forall q \geq 1$. Partitions of unity of a sheaf of Abelian groups, subordinate to the locally finite open covering $U$ of $M$, are a collection of sheaf homomorphisms $\eta_{i}: S \rightarrow S$ such that:
(i) $\eta_{i}$ is the zero map in an open neighbourhood of $M-U_{i}$;
(ii) $\Sigma_{i} \eta_{i}$ equals the identity map of the sheaf $(S, \pi)$.

The sheaf of germs of complex-valued $C^{\infty}$ forms is indeed fine, while $C_{p q}$ and the constant sheaf are not fine.

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