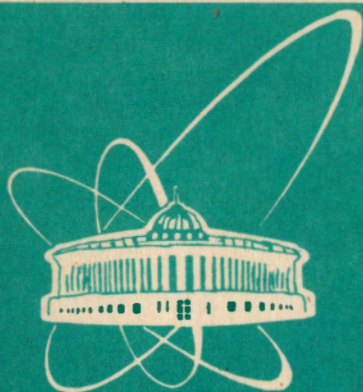


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ПОЛУЧЕНИЕ ОПТИМАЛЬНЫХ ПАРАМЕТРОВ
УРАВНЕНИЙ ДВИЖЕНИЯ ЗАРЯЖЕННОЙ
ЧАСТИЦЫ В МАГНИТНОМ ПОЛЕ
ПРИ РЕШЕНИИ ОБРАТНОЙ ЗАДАЧИ

1993

Движение заряженной частицы в магнитном поле описывается дифференциальными уравнениями второго порядка вида^{1/1}:

$$\begin{aligned} x'' &= aq/p(1+x'^2+y'^2)^{1/2}(B_x x' y' - B_y(1+x'^2) + B_z y') = \Phi(x, y, z, x', y'), \\ y'' &= aq/p(1+x'^2+y'^2)^{1/2}(B_x(1+y'^2) - B_y x' y' - B_z x') = f(x, y, z, x', y'), \end{aligned} \quad (1)$$

где $a=0,2998$, $q = \pm 1, \pm 2, \dots$, - заряд частицы, p - ее импульс, B_x, B_y, B_z - компоненты вектора напряженности магнитного поля \vec{B} в точке (x, y, z) , $x' = dx/dz$, $x'' = d^2x/dz^2$.

Решение прямой задачи - нахождение траектории движения частицы в магнитном поле с известным импульсом p - можно получить численным интегрированием методом Рунге-Кутты при начальных условиях: $z_1, x_1 = x(z_1), y_1 = y(z_1), x'_1 = x'(z_1), y'_1 = y'(z_1)^{2/}$. (2)
На $(i+1)$ -м шаге

$$\begin{aligned} z_{i+1} &= z_i + h = z_i + hi, \\ x_{i+1} &= x_i + x'_i h + 1/6(m_1^i + m_2^i + m_3^i)h^2, \\ y_{i+1} &= y_i + y'_i h + 1/6(k_1^i + k_2^i + k_3^i)h^2, \\ x'_{i+1} &= x'_i + 1/6(m_1^i + 2m_2^i + 2m_3^i + m_4^i)h, \\ y'_{i+1} &= y'_i + 1/6(k_1^i + 2k_2^i + 2k_3^i + k_4^i)h, \end{aligned} \quad (3)$$

где $h = \Delta z$ - шаг интегрирования,

$$\begin{aligned} m_1^i &= \Phi_1(x_i, y_i, z_i, x'_i, y'_i), \quad k_1^i = f_1(x_i, y_i, z_i, x'_i, y'_i), \\ m_2^i &= \Phi_2(\chi_i, \alpha_i, \zeta_i, \chi'_i, \alpha'_i), \quad k_2^i = f_2(\chi_i, \alpha_i, \zeta_i, \chi'_i, \alpha'_i), \\ m_3^i &= \Phi_3(o_i, \omega_i, \zeta_i, o'_i, \omega'_i), \quad k_3^i = f_3(o_i, \omega_i, \zeta_i, o'_i, \omega'_i), \\ m_4^i &= \Phi_4(\gamma_i, v_i, \xi_i, \gamma'_i, v'_i), \quad k_4^i = f_4(\gamma_i, v_i, \xi_i, \gamma'_i, v'_i), \end{aligned} \quad (4)$$

$$\begin{aligned} \chi_i &= \chi_i(x_i, \zeta_i, x'_i) = x_i + x'_i \frac{h}{2}, \quad \chi'_i = \chi'_i(x'_i, \zeta_i, m_1^i) = x'_i + m_1^i \frac{h}{2}, \quad \zeta_i = z_i + \frac{h}{2}, \\ \alpha_i &= \alpha_i(y_i, \zeta_i, y'_i) = y_i + y'_i \frac{h}{2}, \quad \alpha'_i = \alpha'_i(y'_i, \zeta_i, k_1^i) = y'_i + k_1^i \frac{h}{2}, \quad \zeta_i = z_i + \frac{h}{2}, \\ o_i &= o_i(x_i, \zeta_i, x'_i, m_1^i) = x_i + x'_i \frac{h}{2} + m_1^i \frac{h^2}{4}, \quad o'_i = o'_i(x'_i, \zeta_i, m_2^i) = x'_i + m_2^i \frac{h}{2}, \quad \zeta_i = z_i + \frac{h}{2}, \\ \omega_i &= \omega_i(y_i, \zeta_i, y'_i, k_1^i) = y_i + y'_i \frac{h}{2} + k_1^i \frac{h^2}{4}, \quad \omega'_i = \omega'_i(y'_i, \zeta_i, k_2^i) = y'_i + k_2^i \frac{h}{2}, \quad \zeta_i = z_i + \frac{h}{2}, \\ \gamma_i &= \gamma_i(x_i, \xi_i, x'_i, m_2^i) = x_i + x'_i h + m_2^i \frac{h^2}{2}, \quad \gamma'_i = \gamma'_i(x'_i, \xi_i, m_3^i) = x'_i + m_3^i h, \quad \xi_i = z_i + h, \\ v_i &= v_i(y_i, \xi_i, y'_i, k_2^i) = y_i + y'_i h + k_2^i \frac{h^2}{2}, \quad v'_i = v'_i(y'_i, \xi_i, k_3^i) = y'_i + k_3^i h, \quad \xi_i = z_i + h. \end{aligned} \quad (5)$$

Таким образом, при известных импульсе, шаге интегрирования и карте магнитного поля траектория движения заряженной частицы представится набором (x, y, z) - координат N точек.

Теперь решим обратную задачу: по известным N точкам траектории движения и напряженности магнитного поля в этих точках восстановим импульс частицы. Как правило, подобные задачи решаются методом фитирования заданной интегральной кривой уравнения движения (1), где импульс p является искомым параметром. Для получения как можно более точного результата, вообще говоря, необходим выбор оптимального шага интегрирования h при численном решении задачи с использованием уравнений (3)-(5). Величина шага интегрирования h существенно зависит от конфигурации магнитного поля и точности его описания. Таким образом, h является вторым искомым параметром.

Как известно, решение указанной задачи связано с вычислением производных по параметрам уравнений движения частицы в заданных точках траектории, описываемых этими уравнениями. В работе^{/3/} получены представления для производных по импульсу p от решений уравнений (3) как параметру.

Целью настоящей работы является получение представлений для производных по шагу интегрирования h от решений уравнений движения частицы в виде (3)-(5).

Выполним дифференцирование в (3) по параметру h :

$$\begin{aligned} \frac{\partial z_{i+1}}{\partial h} &= i, \quad \frac{\partial z_1}{\partial h} = 0, \\ \frac{\partial x_{i+1}}{\partial h} &= \frac{\partial x_i}{\partial h} + \frac{\partial x'_i}{\partial h} h + 1/6 \left(\frac{\partial m_1^i}{\partial h} + \frac{\partial m_2^i}{\partial h} + \frac{\partial m_3^i}{\partial h} \right) h^2 + x'_i + 1/3(m_1^i + m_2^i + m_3^i)h, \\ \frac{\partial y_{i+1}}{\partial h} &= \frac{\partial y_i}{\partial h} + \frac{\partial y'_i}{\partial h} h + 1/6 \left(\frac{\partial k_1^i}{\partial h} + \frac{\partial k_2^i}{\partial h} + \frac{\partial k_3^i}{\partial h} \right) h^2 + y'_i + 1/3(k_1^i + k_2^i + k_3^i)h, \\ \frac{\partial x'_{i+1}}{\partial h} &= \frac{\partial x'_i}{\partial h} + 1/6 \left(\frac{\partial m_1^i}{\partial h} + 2\frac{\partial m_2^i}{\partial h} + 2\frac{\partial m_3^i}{\partial h} + \frac{\partial m_4^i}{\partial h} \right) h + 1/6(m_1^i + 2m_2^i + 2m_3^i + m_4^i), \\ \frac{\partial y'_{i+1}}{\partial h} &= \frac{\partial y'_i}{\partial h} + 1/6 \left(\frac{\partial k_1^i}{\partial h} + 2\frac{\partial k_2^i}{\partial h} + 2\frac{\partial k_3^i}{\partial h} + \frac{\partial k_4^i}{\partial h} \right) h + 1/6(k_1^i + 2k_2^i + 2k_3^i + k_4^i). \end{aligned} \quad (7)$$

Введём обозначения:

$$\begin{aligned} \alpha_i &= \alpha_i(x'_i, y'_i) = (1 + x_i'^2 + y_i'^2)^{1/2}, \quad c = aq/p, \\ \beta_{xj}^i &= \frac{\partial m_j^i}{\partial B_x^i} = c\alpha_i x'_i y'_i, \quad \beta_{yj}^i = \frac{\partial m_j^i}{\partial B_y^i} = -c\alpha_i (1 + x_i'^2), \quad \beta_{zj}^i = \frac{\partial m_j^i}{\partial B_z^i} = c\alpha_i y'_i, \\ \mathfrak{B}_{xj}^i &= \frac{\partial k_j^i}{\partial B_x^i} = c\alpha_i (1 + y_i'^2), \quad \mathfrak{B}_{yj}^i = \frac{\partial k_j^i}{\partial B_y^i} = -c\alpha_i x'_i y'_i, \quad \mathfrak{B}_{zj}^i = \frac{\partial k_j^i}{\partial B_z^i} = -c\alpha_i x'_i, \end{aligned} \quad (8)$$

$$\begin{aligned} \mathfrak{m}_{xj}^i &= \frac{\partial B_j^i}{\partial x_i} = \beta_{xj}^i \frac{\partial B_x^i}{\partial x_i} + \beta_{yj}^i \frac{\partial B_y^i}{\partial x_i} + \beta_{zj}^i \frac{\partial B_z^i}{\partial x_i}, \\ \mathfrak{m}_{yj}^i &= \frac{\partial B_j^i}{\partial y_i} = \beta_{xj}^i \frac{\partial B_x^i}{\partial y_i} + \beta_{yj}^i \frac{\partial B_y^i}{\partial y_i} + \beta_{zj}^i \frac{\partial B_z^i}{\partial y_i}, \\ \mathfrak{m}_{zj}^i &= \frac{\partial B_j^i}{\partial z} = \beta_{xj}^i \frac{\partial B_x^i}{\partial z} + \beta_{yj}^i \frac{\partial B_y^i}{\partial z} + \beta_{zj}^i \frac{\partial B_z^i}{\partial z}, \\ \mathfrak{R}_{xj}^i &= \frac{\partial k_j^i}{\partial x_i} = \mathfrak{B}_{xj}^i \frac{\partial B_x^i}{\partial x_i} + \mathfrak{B}_{yj}^i \frac{\partial B_y^i}{\partial x_i} + \mathfrak{B}_{zj}^i \frac{\partial B_z^i}{\partial x_i}, \\ \mathfrak{R}_{yj}^i &= \frac{\partial k_j^i}{\partial y_i} = \mathfrak{B}_{xj}^i \frac{\partial B_x^i}{\partial y_i} + \mathfrak{B}_{yj}^i \frac{\partial B_y^i}{\partial y_i} + \mathfrak{B}_{zj}^i \frac{\partial B_z^i}{\partial y_i}, \\ \mathfrak{R}_{zj}^i &= \frac{\partial k_j^i}{\partial z} = \mathfrak{B}_{xj}^i \frac{\partial B_x^i}{\partial z} + \mathfrak{B}_{yj}^i \frac{\partial B_y^i}{\partial z} + \mathfrak{B}_{zj}^i \frac{\partial B_z^i}{\partial z}, \end{aligned} \quad (9)$$

$$\begin{aligned} \mathfrak{Q}_{xj}^i &= \frac{\partial m_j^i}{\partial x_i} = m_j^i x'_i / \alpha_i^2 + c\alpha_i (B_x^i y'_i - 2B_y^i x'_i), \\ \mathfrak{Q}_{yj}^i &= \frac{\partial m_j^i}{\partial y_i} = m_j^i y'_i / \alpha_i^2 + c\alpha_i (B_x^i x'_i + B_z^i), \\ \mathfrak{Q}_{zj}^i &= \frac{\partial m_j^i}{\partial z} = k_j^i x'_i / \alpha_i^2 - c\alpha_i (B_y^i y'_i + B_z^i), \\ \mathfrak{Q}_{yj}^i &= \frac{\partial k_j^i}{\partial y_i} = k_j^i y'_i / \alpha_i^2 + c\alpha_i (2B_x^i y'_i - B_y^i x'_i), \quad j=1, \dots, 4, \quad i=1, \dots, N. \end{aligned} \quad (10)$$

Учитывая обозначения (8)-(10) настоящей работы и формулы (8)

работы^{/3/}, для $\left\{ \frac{\partial m_j^i}{\partial h}, \frac{\partial k_j^i}{\partial h} \right\}_{j=1}^4$ будем иметь:

$$\begin{aligned} \frac{\partial m_1^i}{\partial h} &= \mathfrak{m}_{x1}^i \frac{\partial x_i}{\partial h} + \mathfrak{m}_{y1}^i \frac{\partial y_i}{\partial h} + (i-1)\mathfrak{m}_{z1}^i + \mathfrak{Q}_{x1}^i \frac{\partial x'_i}{\partial h} + \mathfrak{Q}_{y1}^i \frac{\partial y'_i}{\partial h}, \\ \frac{\partial m_2^i}{\partial h} &= \mathfrak{m}_{x2}^i \frac{\partial x_i}{\partial h} + \mathfrak{m}_{y2}^i \frac{\partial y_i}{\partial h} + (i-1)\mathfrak{m}_{z2}^i + (\mathfrak{Q}_{x2}^i + \frac{h}{2}\mathfrak{m}_{x2}^i) \frac{\partial x'_i}{\partial h} + (\mathfrak{Q}_{y2}^i + \frac{h}{2}\mathfrak{m}_{y2}^i) \frac{\partial y'_i}{\partial h} \\ &\quad + \frac{h}{2}(\mathfrak{Q}_{x2}^i \frac{\partial m_1^i}{\partial h} + \mathfrak{Q}_{y2}^i \frac{\partial k_1^i}{\partial h}) + \frac{1}{2}(\mathfrak{m}_{x2}^i x'_i + \mathfrak{m}_{y2}^i y'_i + \mathfrak{m}_{z2}^i) + \frac{1}{2}(\mathfrak{Q}_{x2}^i m_1^i + \mathfrak{Q}_{y2}^i k_1^i), \\ \frac{\partial m_3^i}{\partial h} &= \mathfrak{m}_{x3}^i \frac{\partial x_i}{\partial h} + \mathfrak{m}_{y3}^i \frac{\partial y_i}{\partial h} + (i-1)\mathfrak{m}_{z3}^i + (\mathfrak{Q}_{x3}^i + \frac{h}{2}\mathfrak{m}_{x3}^i) \frac{\partial x'_i}{\partial h} + (\mathfrak{Q}_{y3}^i + \frac{h}{2}\mathfrak{m}_{y3}^i) \frac{\partial y'_i}{\partial h} \\ &\quad + \frac{h^2}{4}(\mathfrak{m}_{x3}^i \frac{\partial m_1^i}{\partial h} + \mathfrak{m}_{y3}^i \frac{\partial k_1^i}{\partial h}) + \frac{h}{2}(\mathfrak{Q}_{x3}^i \frac{\partial m_2^i}{\partial h} + \mathfrak{Q}_{y3}^i \frac{\partial k_2^i}{\partial h}) + \frac{h}{2}(\mathfrak{m}_{x3}^i m_1^i + \mathfrak{m}_{y3}^i k_1^i) + \\ &\quad + \frac{1}{2}(\mathfrak{m}_{x3}^i x'_i + \mathfrak{m}_{y3}^i y'_i + \mathfrak{m}_{z3}^i) + \frac{1}{2}(\mathfrak{Q}_{x3}^i m_2^i + \mathfrak{Q}_{y3}^i k_2^i), \end{aligned} \quad (11)$$

$$\begin{aligned}
\frac{\partial m_4^i}{\partial h} &= \mathfrak{M}_{x_4}^i \frac{\partial x_1^i}{\partial h} + \mathfrak{M}_{y_4}^i \frac{\partial y_1^i}{\partial h} + (i-1)\mathfrak{M}_{z_4}^i + (\mathfrak{Q}_{x_4}^i + h\mathfrak{M}_{x_4}^i) \frac{\partial x_1^i}{\partial h} + (\mathfrak{Q}_{y_4}^i + h\mathfrak{M}_{y_4}^i) \frac{\partial y_1^i}{\partial h} + \\
&+ \frac{h^2}{2} (\mathfrak{R}_{x_4}^i \frac{\partial m_2^i}{\partial h} + \mathfrak{R}_{y_4}^i \frac{\partial k_2^i}{\partial h}) + h(\mathfrak{Q}_{x_4}^i \frac{\partial m_3^i}{\partial h} + \mathfrak{Q}_{y_4}^i \frac{\partial k_3^i}{\partial h}) + h(\mathfrak{M}_{x_4}^i m_2^i + \mathfrak{M}_{y_4}^i k_2^i) + \\
&+ \mathfrak{M}_{x_4}^i x_1^i + \mathfrak{M}_{y_4}^i y_1^i + \mathfrak{M}_{z_4}^i + \mathfrak{Q}_{x_4}^i m_2^i + \mathfrak{Q}_{y_4}^i k_2^i, \\
\frac{\partial k_1^i}{\partial p} &= \mathfrak{R}_{x_1}^i \frac{\partial x_1^i}{\partial h} + \mathfrak{R}_{y_1}^i \frac{\partial y_1^i}{\partial h} + (i-1)\mathfrak{R}_{z_1}^i + \mathfrak{M}_{x_1}^i \frac{\partial x_1^i}{\partial h} + \mathfrak{M}_{y_1}^i \frac{\partial y_1^i}{\partial h}, \quad (12) \\
\frac{\partial k_2^i}{\partial h} &= \mathfrak{R}_{x_2}^i \frac{\partial x_1^i}{\partial h} + \mathfrak{R}_{y_2}^i \frac{\partial y_1^i}{\partial h} + (i-1)\mathfrak{R}_{z_2}^i + (\mathfrak{M}_{x_2}^i + \frac{h\mathfrak{R}_{x_2}^i}{2}) \frac{\partial x_1^i}{\partial h} + (\mathfrak{M}_{y_2}^i + \frac{h\mathfrak{R}_{y_2}^i}{2}) \frac{\partial y_1^i}{\partial h} + \\
&+ \frac{h}{2} (\mathfrak{M}_{x_2}^i \frac{\partial m_1^i}{\partial h} + \mathfrak{M}_{y_2}^i \frac{\partial k_1^i}{\partial h}) + \frac{1}{2} (\mathfrak{R}_{x_2}^i x_1^i + \mathfrak{R}_{y_2}^i y_1^i + \mathfrak{R}_{z_2}^i) + \frac{1}{2} (\mathfrak{M}_{x_2}^i m_1^i + \mathfrak{M}_{y_2}^i k_1^i), \\
\frac{\partial k_3^i}{\partial h} &= \mathfrak{R}_{x_3}^i \frac{\partial x_1^i}{\partial h} + \mathfrak{R}_{y_3}^i \frac{\partial y_1^i}{\partial h} + (i-1)\mathfrak{R}_{z_3}^i + (\mathfrak{M}_{x_3}^i + \frac{h\mathfrak{R}_{x_3}^i}{2}) \frac{\partial x_1^i}{\partial h} + (\mathfrak{M}_{y_3}^i + \frac{h\mathfrak{R}_{y_3}^i}{2}) \frac{\partial y_1^i}{\partial h} + \\
&+ \frac{h^2}{4} (\mathfrak{R}_{x_3}^i \frac{\partial m_1^i}{\partial h} + \mathfrak{R}_{y_3}^i \frac{\partial k_1^i}{\partial h}) + \frac{h}{2} (\mathfrak{M}_{x_3}^i \frac{\partial m_2^i}{\partial h} + \mathfrak{M}_{y_3}^i \frac{\partial k_2^i}{\partial h}) + \frac{h}{2} (\mathfrak{R}_{x_3}^i m_1^i + \mathfrak{R}_{y_3}^i k_1^i) + \\
&+ \frac{1}{2} (\mathfrak{R}_{x_3}^i x_1^i + \mathfrak{R}_{y_3}^i y_1^i + \mathfrak{R}_{z_3}^i) + \frac{1}{2} (\mathfrak{M}_{x_3}^i m_2^i + \mathfrak{M}_{y_3}^i k_2^i), \\
\frac{\partial k_4^i}{\partial h} &= \mathfrak{R}_{x_4}^i \frac{\partial x_1^i}{\partial h} + \mathfrak{R}_{y_4}^i \frac{\partial y_1^i}{\partial h} + (i-1)\mathfrak{R}_{z_4}^i + (\mathfrak{M}_{x_4}^i + h\mathfrak{R}_{x_4}^i) \frac{\partial x_1^i}{\partial h} + (\mathfrak{M}_{y_4}^i + h\mathfrak{R}_{y_4}^i) \frac{\partial y_1^i}{\partial h} + \\
&+ \frac{h^2}{2} (\mathfrak{R}_{x_4}^i \frac{\partial m_2^i}{\partial h} + \mathfrak{R}_{y_4}^i \frac{\partial k_2^i}{\partial h}) + h(\mathfrak{R}_{x_4}^i \frac{\partial m_3^i}{\partial h} + \mathfrak{R}_{y_4}^i \frac{\partial k_3^i}{\partial h}) + h(\mathfrak{R}_{x_4}^i m_2^i + \mathfrak{R}_{y_4}^i k_2^i) + \\
&+ \mathfrak{R}_{x_4}^i x_1^i + \mathfrak{R}_{y_4}^i y_1^i + \mathfrak{R}_{z_4}^i + \mathfrak{M}_{x_4}^i m_2^i + \mathfrak{M}_{y_4}^i k_2^i.
\end{aligned}$$

Подставляя (11), (12) в (7), окончательно получим

$$\begin{aligned}
\frac{\partial z_{i+1}}{\partial h} &= i, \quad \frac{\partial z_1}{\partial h} = 0, \\
\frac{\partial x_{i+1}}{\partial h} &= \frac{\partial x_1}{\partial h} + h \frac{\partial x_1^i}{\partial h} + \frac{1}{3} (m_1^i + m_2^i + m_3^i) h + x_1^i + 1/6 \left\{ \sum_{j=1}^3 \mathfrak{M}_{x_j}^i \frac{\partial x_1^i}{\partial h} + \sum_{j=1}^3 \mathfrak{M}_{y_j}^i \frac{\partial y_1^i}{\partial h} + \right. \\
&+ (i-1) \sum_{j=1}^3 \mathfrak{M}_{z_j}^i + \sum_{j=1}^3 \mathfrak{Q}_{x_j}^i + \frac{h}{2} \sum_{j=2}^3 \mathfrak{M}_{y_j}^i \frac{\partial x_1^i}{\partial h} + \left(\sum_{j=1}^3 \mathfrak{Q}_{y_j}^i + \frac{h}{2} \sum_{j=2}^3 \mathfrak{M}_{y_j}^i \right) \frac{\partial y_1^i}{\partial h} + \\
&+ \frac{h}{2} \left[(\mathfrak{M}_{x_2}^i + \frac{h\mathfrak{R}_{x_2}^i}{2}) \frac{\partial m_1^i}{\partial h} + (\mathfrak{M}_{y_2}^i + \frac{h\mathfrak{R}_{y_2}^i}{2}) \frac{\partial k_1^i}{\partial h} \right] + \frac{h}{2} (\mathfrak{Q}_{x_3}^i \frac{\partial m_2^i}{\partial h} + \mathfrak{Q}_{y_3}^i \frac{\partial k_2^i}{\partial h}) + \\
&+ \frac{1}{2} \sum_{j=2}^3 \mathfrak{M}_{x_j}^i x_1^i + \frac{1}{2} \sum_{j=2}^3 \mathfrak{M}_{y_j}^i y_1^i + \frac{1}{2} \sum_{j=2}^3 \mathfrak{M}_{z_j}^i + \frac{1}{2} \sum_{j=2}^3 m_{j-1}^i \mathfrak{Q}_{x_j}^i + \frac{1}{2} \sum_{j=2}^3 k_{j-1}^i \mathfrak{Q}_{y_j}^i + \\
&+ \frac{h}{2} (m_1^i \mathfrak{M}_{x_3}^i + k_1^i \mathfrak{M}_{y_3}^i) \left. \right\} h^2,
\end{aligned}$$

$$\begin{aligned}
\frac{\partial y_{i+1}}{\partial h} &= \frac{\partial y_1}{\partial h} + h \frac{\partial y_1^i}{\partial h} + \frac{1}{3} (k_1^i + k_2^i + k_3^i) h + y_1^i + 1/6 \left\{ \sum_{j=1}^3 \mathfrak{R}_{x_j}^i \frac{\partial x_1^i}{\partial h} + \sum_{j=1}^3 \mathfrak{R}_{y_j}^i \frac{\partial y_1^i}{\partial h} + \right. \\
&+ (i-1) \sum_{j=1}^3 \mathfrak{R}_{z_j}^i + \sum_{j=1}^3 \mathfrak{M}_{x_j}^i + \frac{h}{2} \sum_{j=2}^3 \mathfrak{R}_{y_j}^i \frac{\partial x_1^i}{\partial h} + \left(\sum_{j=1}^3 \mathfrak{M}_{y_j}^i + \frac{h}{2} \sum_{j=2}^3 \mathfrak{R}_{y_j}^i \right) \frac{\partial y_1^i}{\partial h} + \\
&+ \frac{h}{2} \left[(\mathfrak{M}_{x_2}^i + \frac{h\mathfrak{R}_{x_2}^i}{2}) \frac{\partial m_1^i}{\partial h} + (\mathfrak{M}_{y_2}^i + \frac{h\mathfrak{R}_{y_2}^i}{2}) \frac{\partial k_1^i}{\partial h} \right] + \frac{h}{2} (\mathfrak{M}_{x_3}^i \frac{\partial m_2^i}{\partial h} + \mathfrak{M}_{y_3}^i \frac{\partial k_2^i}{\partial h}) + \\
&+ \frac{1}{2} \sum_{j=2}^3 \mathfrak{R}_{x_j}^i x_1^i + \frac{1}{2} \sum_{j=2}^3 \mathfrak{R}_{y_j}^i y_1^i + \frac{1}{2} \sum_{j=2}^3 \mathfrak{R}_{z_j}^i + \frac{1}{2} \sum_{j=2}^3 m_{j-1}^i \mathfrak{M}_{x_j}^i + \frac{1}{2} \sum_{j=2}^3 k_{j-1}^i \mathfrak{M}_{y_j}^i + \\
&+ \frac{h}{2} (m_1^i \mathfrak{R}_{x_3}^i + k_1^i \mathfrak{R}_{y_3}^i) \left. \right\} h^2, \\
\frac{\partial x_{i+1}^i}{\partial h} &= \frac{\partial x_1^i}{\partial h} + \frac{1}{6} (m_1^i + 2m_2^i + 2m_3^i + m_4^i) + 1/6 \left\{ (\mathfrak{M}_{x_1}^i + 2\mathfrak{M}_{x_2}^i + 2\mathfrak{M}_{x_3}^i + \mathfrak{M}_{x_4}^i) \frac{\partial x_1^i}{\partial h} + \right. \\
&+ (\mathfrak{M}_{y_1}^i + 2\mathfrak{M}_{y_2}^i + 2\mathfrak{M}_{y_3}^i + \mathfrak{M}_{y_4}^i) \frac{\partial y_1^i}{\partial h} + (\mathfrak{Q}_{x_1}^i + 2\mathfrak{Q}_{x_2}^i + 2\mathfrak{Q}_{x_3}^i + \mathfrak{Q}_{x_4}^i + h \sum_{j=2}^4 \mathfrak{M}_{x_j}^i) \frac{\partial x_1^i}{\partial h} + \\
&+ (\mathfrak{Q}_{y_1}^i + 2\mathfrak{Q}_{y_2}^i + 2\mathfrak{Q}_{y_3}^i + \mathfrak{Q}_{y_4}^i + h \sum_{j=2}^4 \mathfrak{M}_{y_j}^i) \frac{\partial y_1^i}{\partial h} + h \left[(\mathfrak{Q}_{x_2}^i + \frac{h\mathfrak{M}_{x_2}^i}{2}) \frac{\partial m_1^i}{\partial h} + \right. \\
&+ (\mathfrak{Q}_{y_2}^i + \frac{h\mathfrak{M}_{y_2}^i}{2}) \frac{\partial k_1^i}{\partial h} \left. \right] + h \left[(\mathfrak{Q}_{x_3}^i + \frac{h\mathfrak{M}_{x_3}^i}{2}) \frac{\partial m_2^i}{\partial h} + (\mathfrak{Q}_{y_3}^i + \frac{h\mathfrak{M}_{y_3}^i}{2}) \frac{\partial k_2^i}{\partial h} \right] + \\
&+ h(\mathfrak{Q}_{x_4}^i \frac{\partial m_3^i}{\partial h} + \mathfrak{Q}_{y_4}^i \frac{\partial k_3^i}{\partial h}) + (i-1)(\mathfrak{M}_{z_1}^i + 2\mathfrak{M}_{z_2}^i + 2\mathfrak{M}_{z_3}^i + \mathfrak{M}_{z_4}^i) + \\
&+ \sum_{j=2}^4 \mathfrak{M}_{x_j}^i x_1^i + \sum_{j=2}^4 \mathfrak{M}_{y_j}^i y_1^i + \sum_{j=2}^4 \mathfrak{M}_{z_j}^i + \sum_{j=2}^4 \mathfrak{Q}_{x_j}^i m_{j-1}^i + \sum_{j=2}^4 \mathfrak{Q}_{y_j}^i k_{j-1}^i + \\
&+ h(m_1^i \mathfrak{M}_{x_3}^i + m_2^i \mathfrak{M}_{x_4}^i + k_1^i \mathfrak{M}_{y_3}^i + k_2^i \mathfrak{M}_{y_4}^i) \left. \right\} h, \quad (13) \\
\frac{\partial y_{i+1}^i}{\partial h} &= \frac{\partial y_1^i}{\partial h} + \frac{1}{6} (k_1^i + 2k_2^i + 2k_3^i + k_4^i) + 1/6 \left\{ (\mathfrak{R}_{x_1}^i + 2\mathfrak{R}_{x_2}^i + 2\mathfrak{R}_{x_3}^i + \mathfrak{R}_{x_4}^i) \frac{\partial x_1^i}{\partial h} + \right. \\
&+ (\mathfrak{R}_{y_1}^i + 2\mathfrak{R}_{y_2}^i + 2\mathfrak{R}_{y_3}^i + \mathfrak{R}_{y_4}^i) \frac{\partial y_1^i}{\partial h} + (\mathfrak{M}_{x_1}^i + 2\mathfrak{M}_{x_2}^i + 2\mathfrak{M}_{x_3}^i + \mathfrak{M}_{x_4}^i + h \sum_{j=2}^4 \mathfrak{R}_{x_j}^i) \frac{\partial x_1^i}{\partial h} + \\
&+ (\mathfrak{M}_{y_1}^i + 2\mathfrak{M}_{y_2}^i + 2\mathfrak{M}_{y_3}^i + \mathfrak{M}_{y_4}^i + h \sum_{j=2}^4 \mathfrak{R}_{y_j}^i) \frac{\partial y_1^i}{\partial h} + h \left[(\mathfrak{M}_{x_2}^i + \frac{h\mathfrak{R}_{x_2}^i}{2}) \frac{\partial m_1^i}{\partial h} + \right. \\
&+ (\mathfrak{M}_{y_2}^i + \frac{h\mathfrak{R}_{y_2}^i}{2}) \frac{\partial k_1^i}{\partial h} \left. \right] + h \left[(\mathfrak{M}_{x_3}^i + \frac{h\mathfrak{R}_{x_3}^i}{2}) \frac{\partial m_2^i}{\partial h} + (\mathfrak{M}_{y_3}^i + \frac{h\mathfrak{R}_{y_3}^i}{2}) \frac{\partial k_2^i}{\partial h} \right] + \\
&+ h(\mathfrak{M}_{x_4}^i \frac{\partial m_3^i}{\partial h} + \mathfrak{M}_{y_4}^i \frac{\partial k_3^i}{\partial h}) + (i-1)(\mathfrak{R}_{z_1}^i + 2\mathfrak{R}_{z_2}^i + 2\mathfrak{R}_{z_3}^i + \mathfrak{R}_{z_4}^i) + \\
&+ \sum_{j=2}^4 \mathfrak{R}_{x_j}^i x_1^i + \sum_{j=2}^4 \mathfrak{R}_{y_j}^i y_1^i + \sum_{j=2}^4 \mathfrak{R}_{z_j}^i + \sum_{j=2}^4 \mathfrak{M}_{x_j}^i m_{j-1}^i + \sum_{j=2}^4 \mathfrak{M}_{y_j}^i k_{j-1}^i + \\
&+ h(m_1^i \mathfrak{R}_{x_3}^i + m_2^i \mathfrak{R}_{x_4}^i + k_1^i \mathfrak{R}_{y_3}^i + k_2^i \mathfrak{R}_{y_4}^i) \left. \right\} h.
\end{aligned}$$

Теперь предположим, что мы располагаем известными: траекторией движения заряженной частицы, состоящей из N точек, картой напряженности магнитного поля и импульсом частицы. Фитируя заданную траекторию по h как параметру с помощью уравнений, представленных формулами (1)-(5), и используя для вычисления производных от решения уравнений (3) по h полученные выше формулы (13), мы тем самым определим оптимальный шаг интегрирования кривой в данном событии. Усредняя полученное в заданном событии значение h на статистике из некоторого числа событий, мы установим оптимальное значение шага интегрирования, которое обеспечит решение поставленной задачи с заданной точностью.

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