

# ОБЪЕДИНЕННЫЙ ИНСТИТУТ ЯДЕРНЫХ ИССЛЕДОВАНИЙ 

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A PROGRAM FOR COMPUTING COHOMOLOGY OF LIE SUPERALGEBRAS OF VECTOR FIELDS

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[^0]
## 1 Introduction and basic definitions

There are many applications of the Lie (super)algebra cohomology in mathematics: characteristic classes of foliations; invariant differential operators; MacDonaldtype combinatorial identities, etc. (see [1] for details). Besides, the cohomology is used widely in mathematical and theoretical physics [2]: construction of the central extensions and deformations for Lie superalgebras; construction of supergravity equations for $N$-extended Minkowski superspaces and search for possible models for these superspaces; study of stability for nonholonomic systems like ballbearings, gyroscopes, electro-mechanical devices, waves in plasma, etc.; description of an analogue of the curvature tensor for nonlinear nonholonomic constraints; new methods for the study of integrability of dynamical systems.

General definitions and properties of cohomology of Lie algebras and superalgebras are described in [1]. Let's recall briefly some basic definitions.

A Lie superalgebra is a $\mathbf{Z}_{2}$-graded algebra over a commutative ring $K$ with a unit:

$$
L=L_{\overline{0}} \oplus L_{\overline{1}}, u \in L_{\alpha}, v \in L_{\beta}, \alpha, \beta \in \mathbf{Z}_{2}=\{\overline{0}, \overline{1}\} \Longrightarrow[u, v] \in L_{\alpha+\beta}
$$

The elements of $L_{\overline{0}}$ and $L_{\overline{1}}$ are called even and odd, respectively. We shall assume $K$ is one of the fields $\mathbf{C}$ or $\mathbf{R}$. By definition, the Lie product (shortly, brackets) [, ] satisfies the following axioms

$$
\begin{array}{cl}
{[u, v]=-(-1)^{p(u) p(v)}[v, u],} & \text { skew-symmetry, } \\
{[u,[v, w]]=[[u, v], w]+(-1)^{p(u) p(v)}[v,[u, w]],} & \text { Jacobi identity, }
\end{array}
$$

where $p(a)$ is the parity of element $a \in L_{p(a)}$.
A module over a Lie superalgebra $A$ is a vector space $M$ (over the same field $K$ ) with a mapping $A \times M \rightarrow M$, such that $\left[a_{1}, a_{2}\right] m=a_{1}\left(a_{2} m\right)-(-1)^{p\left(a_{1}\right) p\left(a_{2}\right)} a_{2}\left(a_{1} m\right)$, where $a_{1}, a_{2} \in A, m \in M$. The most important for our purposes are trivial ( $M$ is arbitrary vector space, e.g., $M=K ; a m=0$ ), adjoint $(M=A ; a m=[a, m])$ and coadjoint ( $M=A^{\prime} ; a m=\{a, m\}$ is coadjoint action) modules.

A cochain complex is a sequence of linear spaces $C^{k}$ with linear mappings $d^{k}$

$$
0 \rightarrow C^{0} \xrightarrow{d^{0}} \cdots \xrightarrow{d^{k-2}} C^{k-1} \xrightarrow{d^{k-1}} C^{k} \xrightarrow{d^{k}} C^{k+1} \xrightarrow{d^{k+1}} \cdots,
$$

where the linear space $C^{k}=C^{k}(A ; M)$ is a super skew-symmetric $k$-linear mapping $A \times \cdots \times A \rightarrow M, C^{0}=M$ by definition. The super skew-symmetry means symmetry w.r.t. transpositions of odd elements of $A$ and antisymmetry for all other transpositions. Elements of $C^{k}$ are called cochains.

The linear mapping $d^{k}$ (or, briefly, $d$ ) is called the differential and satisfies the following property: $d^{k} \circ d^{k-1}=0\left(\right.$ or $\left.d^{2}=0\right)$.

The cochains mapped into zero by the differential are called the cocycles, i.e., the space of cocycles is

$$
Z^{k}=\operatorname{Ker} d^{k}=\left\{C^{k} \mid d C^{k}=0\right\}
$$



Those cochains which can be represented as differentials of other cochains are called the coboundaries, i.e., the space of coboundaries is

$$
B^{k}=\operatorname{Im} d^{k-1}=\left\{C^{k} \mid C^{k}=d C^{k-1}\right\}
$$

Any coboundary is, obviously, a cocycle.
The non-trivial cocycles, i.e., those of them which are not coboundaries, form the cohomology. In other words, the cohomology is the quotient space

$$
H^{k}(A ; M)=Z^{k} / B^{k}
$$

The explicit form of the differential for a Lie superalgebra is

$$
\begin{gathered}
d C\left(e_{0}, \ldots, e_{q} ; O_{q+1}, \ldots, O_{k}\right)= \\
\sum_{i<j}^{q}(-1)^{j} C\left(e_{0}, \ldots, e_{i-1},\left[e_{i}, e_{j}\right], \ldots, \widehat{e}_{j}, \ldots, e_{q} ; O_{q+1}, \ldots, O_{k}\right)+ \\
(-1)^{q+1} \sum_{i=0}^{q} \sum_{j=q+1}^{k} C\left(e_{0}, \ldots, e_{i-1},\left[e_{i}, O_{j}\right], \ldots, e_{q} ; O_{q+1}, \ldots, \widehat{O_{j}}, \ldots, O_{k}\right)+ \\
(-1)^{i+1} \sum_{i=q+1}^{k-1} \sum_{j=q+2}^{k} C\left(e_{0}, \ldots, e_{q} ; O_{q+1}, \ldots, O_{i-1},\left[O_{i}, O_{j}\right], \ldots, \widehat{O_{j}}, \ldots, O_{k}\right)+ \\
\sum_{i=0}^{q}(-1)^{i+1} e_{i} C\left(e_{0}, \ldots, \widehat{e}_{i}, \ldots, e_{q} ; O_{q+1}, \ldots, O_{k}\right)+ \\
(-1)^{q} \sum_{i=q+1}^{k} O_{i} C\left(e_{0}, \ldots, e_{q} ; O_{q+1}, \ldots, \widehat{O_{i}}, \ldots, O_{k}\right) .
\end{gathered}
$$

Here $e_{i}$ and $O_{i}$ are even and odd elements of the algebra, respectively, and the hat " $\sim$ " marks the omitted elements.

Here are some properties and statements we use in the sequel.
An algebra and a module are called graded if they can be presented as sums of homogeneous components in a way compatible with the algebra brackets and the action of the algebra on the module:

$$
A=\oplus_{g \in G} A_{g}, M=\oplus_{g \in G} M_{g},\left[A_{g_{1}}, A_{g_{2}}\right] \subset A_{g_{1}+g_{2}}, A_{g_{1}} M_{g_{2}} \subset M_{g_{1}+g_{2}}
$$

where $G$ is some abelian (semi)group. The grading in the algebra and module induces a grading on cochains and, hence, in the cohomology:

$$
C^{*}(A ; M)=\oplus_{g \in G} C_{g}^{*}(A ; M), \quad H^{*}(A ; M)=\oplus_{g \in G} H_{g}^{*}(A ; M)
$$

This property allows one to compute the cohomology separately for different homogeneous components; this is especially useful when the homogeneous components are finite-dimensional.

If there is an element $a_{0} \in A$, such that eigenvectors of the operator $a \mapsto\left[a_{0}, a\right]$ form a (topological) basis of algebra $A$, then $H^{*}(A) \simeq H_{0}^{*}(A)$. In other words, all the non-trivial cocycles of the cohomology in the trivial module lie in the zero grade
component. The element $a_{0}$ is called an internal grading element. If also eigenvectors of the operator $m \mapsto a_{0} m$ form a topological basis of module $M$, then the same statement holds for the cohomology in the module $M: H^{*}(A ; M) \simeq H_{0}^{*}(A ; M)$.

Any Lie superalgebra acts on its cohomology trivially, i.e., $A \circ H^{k}(A ; M)=0$. The explicit formula for the algebra action on cochains is

$$
a \circ C^{k}\left(a_{1}, \ldots, a_{k}\right)=-\sum_{i=1}^{k} C^{k}\left(a_{1}, \ldots,\left[a, a_{i}\right], \ldots, a_{k}\right)+a C^{k}\left(a_{1}, \ldots, a_{k}\right)
$$

The triviality of the action allows one to reduce computation in some cases.

## 2 Lie superalgebras of vector fields

Below a list of the main Lie superalgebras of formal vector fields is given [3]. We consider some sets of even ( $x_{i}, q_{i}, p_{i}, t$ ) and odd (called also Grassmann) variables ( $U_{i}, W$ ). In many cases the vector fields can be expressed in terms of generating functions. The coordinates of vector fields and generating functions are assumed to be formal power series in the even and odd variables. Note that all the algebras depending only on the odd variables are finite-dimensional. All these algebras are graded due to prescribed grading of the variables. There are some standard gradings for the variables: all variables $x_{i}, q_{i}, p_{i}, U_{i}$ have grade 1 and the separate variables $t, W$ have grade 2 . Non-standard gradings with zero grades for some odd variables are possible too. The divergence-free algebras are called special. The symbol $\mathbf{Z}$ denotes the center of an algebra.

1. General vectorial superalgebra $\mathbf{W}(\mathbf{n} \mid \mathbf{m})$ or $\operatorname{vect}(\mathrm{n} \mid \mathrm{m})$

Variables: $x_{1}, \ldots, x_{n} ; U_{1}, \ldots, U_{m}$
The brackets denote the supercommutator of vector fields of the form
$\sum_{i=1}^{n} f_{i} \frac{\partial}{\partial x_{i}}+\sum_{k=1}^{m} g_{k} \frac{\partial}{\partial U_{k}}$
2. Special vectorial superalgebra $\mathbf{S}(\mathbf{n} \mid \mathrm{m})$ or $\operatorname{svect}(\mathbf{n} \mid \mathrm{m})$ consists of the elements from $\mathbf{W}(\mathrm{n} \mid \mathrm{m})$ satisfying the condition
$\sum_{i=1}^{n} \frac{\partial f_{i}}{\partial x_{i}}+\sum_{k=1}^{m}(-1)^{p\left(g_{k}\right)} \frac{\partial g_{k}}{\partial U_{k}}=0$
3. Poisson superalgebra $\mathbf{P o}(2 \mathrm{n} \mid \mathrm{m})$

Variables: $p_{1}, \ldots, p_{n}, q_{1}, \ldots, q_{n} ; U_{1}, \ldots, U_{m}$
Brackets: $\{f, g\}_{P b}=\sum_{i=1}^{n}\left(\frac{\partial}{\partial p_{i}} \frac{\partial g}{\partial q_{i}}-\frac{\partial l}{\partial q_{i}} \frac{\partial g}{\partial p_{i}}\right)-(-1)^{p(f)} \sum_{k=1}^{m} \frac{\partial f}{\partial U_{k}} \frac{\partial g}{\partial U_{k}}$
Hamiltonian superalgebra is $\mathbf{H}(\mathbf{2 n} \mid \mathbf{m})=\mathbf{P o}(\mathbf{2 n} \mid \mathbf{m}) / \mathbf{K}$
4. Contact superalgebra $K(2 n+1 \mid m)$

Variables: $t, p_{1}, \ldots, p_{n}, q_{1}, \ldots, q_{n} ; U_{1}, \ldots, U_{m}$
Brackets: $\{f, g\}_{K b}=\Delta(f) \frac{\partial g}{\partial t}-\frac{\partial I}{\partial t} \Delta(g)-\{f, g\}_{P b}$

$$
\Delta(f)=2 f-E(f), E=\sum_{i=1}^{n}\left(p_{i} \frac{\partial}{\partial p_{i}}+q_{i} \frac{\partial}{\partial q_{i}}\right)+\sum_{k=1}^{m} U_{k} \frac{\partial}{\partial l_{k}}
$$

5. Buttin superalgebra $\mathbf{B}(\mathrm{n})$

Variables: $q_{1}, \ldots, q_{n} ; U_{1}, \ldots, U_{n}$
Brackets: $\{f, g\}_{B b}=\sum_{i=1}^{n}\left(\frac{\partial f}{\partial q_{i}} \frac{\partial g}{\partial U_{i}}+(-1)^{p(f)} \frac{\partial f}{\partial U_{i}} \frac{\partial g}{\partial q_{i}}\right)$
Leites superalgebra is $\operatorname{Le}(\mathbf{n})=\mathbf{B}(\mathbf{n}) / \mathbf{Z}$
6. Special Buttin superalgebra $\operatorname{SB}(n)$ is subalgebra of $B(n)$
subject to the constraint $\sum_{i=1}^{n} \frac{\partial^{2} \rho}{\partial q_{i} \partial U_{i}}=0$ for generating function.
Special Leites superalgebra is $\operatorname{SLe}(\mathbf{n})=\mathbf{S B}(\mathbf{n}) / \mathbf{Z}$
7. Odd contact superalgebra $\mathbf{M}(\mathbf{n})$

Variables: $q_{1}, \ldots, q_{n} ; W, U_{1}, \ldots, U_{n}$
Brackets: $\{f, g\}_{M b}=\Delta(f) \frac{\partial g}{\partial W}+(-1)^{p(f)} \frac{\partial f}{\partial W} \Delta(g)-\{f, g\}_{B b}$
$\Delta(f)=2 f-E(f), E=\sum_{i=1}^{n}\left(q_{i} \frac{\partial}{\partial q_{i}}+U_{i} \frac{\partial}{\partial U_{i}}\right)$
8. Special odd contact superalgebra $\mathbf{S M}(\mathrm{n})$ is subalgebra of $\mathbf{M}(\mathrm{n})$ subject to the constraint $(1-E) \frac{\partial f}{\partial W}-\sum_{i=1}^{n} \frac{\partial^{2} f}{\partial q_{i} \partial U_{i}}=0$ for generating function.

## 3 Outline of algorithm and its implementation

To compute the cohomology one needs to solve the equation

$$
\begin{equation*}
d C^{k}=0, \tag{1}
\end{equation*}
$$

and throw away those solutions of (1) which can be expressed in the form

$$
C^{k}=d C^{k-1}
$$

In some exceptional cases it is possible to solve equation (1) in closed form. Generally, in the case of Lie superalgebras of vector fields, determining equation (1) is a system of linear homogeneous functional equations with integer arguments. Unfortunately there is no general method for solving such systems in closed form. Hence, we need to carry out the corresponding computation "numerically". There are several packages for computing cohomology of Lie algebras and superalgebras written in Reduce [4], [5] and Mathematica [2]. Some new results were obtained completely or partially with the help of these packages. However, these packages, being based on general purpose computer algebra systems, appeared to be too inefficient for large real problems. In view of this, we wrote the program in C language.

The C code, of total length near 10000 lines, contains about 300 functions realizing top level algorithms, simplification of indexed objects, working with Grassmannian objects, exterior calculus, linear algebra, substitutions, list processing, input and output, etc. As internal structures we use 8 types of lists for different objects. We represent Grassmann monomials by integer numbers using one-to-one
correspondence between (binary codes of) non-negative integers and Grassmann monomials. This representation allows one efficiently to implement the operations with Grassmann monomials by means of the basic computer commands.

The program performs sequentially the following steps:

1. Reading input information.
2. Constructing a basis for the algebra, The basis can be read from the input file; otherwise the program constructs it from the definition of the algebra. Non-trivial computations at this step arise only in the case of divergence-free algebras. The basis elements of such algebras should satisfy some conditions. In fact, we should construct the basis elements of a subspace given by a system of linear equations. The task is thereby reduced to some problem of linear algebra combined with shifts of indices. For example, among the divergencefree conditions for the special Buttin algebra $\mathbf{S B}(3)$ there are the following two equations

$$
\begin{aligned}
& i a_{i j k ; U V}-(k+1) a_{i-1, j, k+1 ; V W}=0 \\
& i a_{i j k ; U W}+(j+1) a_{i-1, j+1, k ; V W}=0 .
\end{aligned}
$$

Here $a_{i j k ; U V}, \ldots$ are coefficients at the monomials $p^{i} q^{j} r^{k} U V, \ldots$ in the generating function; $p, q, r$ and $U, V, W$ are even and odd variables, respectively. First of all, we have to shift indices $j$ and $k$ in the second equation to reduce the last terms of both equations to the same multiindices. Then, using some simple tricks of linear algebra, we can easily construct the corresponding basis element

$$
E_{i j k}=(k+1) p^{i} q^{j} r^{k} U V-j p^{i} q^{j-1} r^{k+1} U W+i p^{i+1} q^{j} r^{k+1} V W
$$

3. Constructing the commutator table for the algebra (if this table has not been read from the input file).
4. Creating the general form of expressions for coboundaries and determining equations for cocycles.
5. Transition to a particular grade in general expressions. At this step expressions for coboundaries take the form $\mathbf{x}=\mathrm{bt}$, equations for cocycles take the form $\mathbf{Z x}=\mathbf{0}$, where vector $\mathbf{x}$ corresponds to $C^{k}$, parameter vector $\mathbf{t}$ corresponds to $C^{k-1}$, matrices $\mathbf{Z}, \mathrm{b}$ correspond to the differential $d$. All these vector spaces are finite-dimensional for any particular grade.
6. Computing the quotient space $H^{k}(A ; M)=Z^{k} / B^{k}$. Here cocycle subspace $Z^{k}$ is given by relations $\mathbf{Z x}=\mathbf{0}$, and coboundary subspace $B^{k}$ is given parametrically by $\mathbf{x}=\mathrm{bt}$.

## Substeps:

(a) Eliminate $\mathbf{t}$ from $\mathbf{x}=\mathbf{b t}$ to get equations $\mathbf{B x}=\mathbf{0}$
(b) Reduce both relations $\mathbf{B x}=\mathbf{0}$ and $\mathbf{Z x}=\mathbf{0}$ to the canonical form by Gauss elimination. If $\operatorname{rank} B=\operatorname{rank} Z$, then there is no non-trivial cocycle; otherwise go to Substep (c).
(c) Set $\mathbf{B x}=\mathbf{y}$ and substitute these relations into $\mathbf{Z x}=\mathbf{0}$ to get relations $\mathbf{A y}=\mathbf{0}$. The parametric (non-leading) $y^{\prime} \mathrm{s}$ of the last relations are nontrivial cocycles; that is, they form a basis of the cohomology.
In fact, the above procedure is based on the relation for quotient spaces

$$
Z / B=\frac{Y / B}{Y / Z}
$$

where $Y$ is an artificially introduced space, combining the above $x^{\prime} \mathrm{s}$ and $y^{\prime}$ s.
7. Output the non-trivial cocycles.

## 4 Computation of $H_{(-2)}^{5}(P o(2))$

The algebra $P o(2)$ of 2D Poisson polynomial vector fields has basis elements

$$
E_{i j}=p^{i+1} q^{j+1}
$$

satisfying the commutator table

$$
\left[E_{i j}, E_{k l}\right]=(i+i l-j-j k-k+l) E_{i+k, j+l} .
$$

The 5 -coboundaries are given by the formula

$$
\begin{aligned}
d C^{4}= & \left\{(p+p s-q-q r-r+s) C\left(E_{i j}, E_{k l}, E_{m n}, E_{p+r, q+s}\right)\right. \\
& +(-m-m q+n+n p+p-q) C\left(E_{i j}, E_{k l}, E_{m+p, n+q}, E_{r s}\right) \\
& +(m+m s-n-n r-r+s) C\left(E_{i j}, E_{k l}, E_{m+r, n+s}, E_{p q}\right) \\
& +(k+k n-l-l m-m+n) C\left(E_{i j}, E_{k+m, l+n}, E_{p q}, E_{r s}\right) \\
& +(-k-k q+l+l p+p-q) C\left(E_{i j}, E_{k+p, l+q}, E_{m n}, E_{r s}\right) \\
& +(k+k s-l-l r-r+s) C\left(E_{i j}, E_{k+r, l+s}, E_{m n}, E_{p q}\right) \\
& +(-i-i l+j+j k+k-l) C\left(E_{i+k, j+l}, E_{m n}, E_{p q}, E_{r s}\right) \\
& +(i+i n-j-j m-m+n) C\left(E_{i+m, j+n}, E_{k l}, E_{p q}, E_{r s}\right) \\
& +(-i-i q+j+j p+p-q) C\left(E_{i+p, j+q}, E_{k l}, E_{m n}, E_{r s}\right) \\
& \left.+(i+i s-j-j r-r+s) C\left(E_{i+r, j+s}, E_{k l}, E_{m n}, E_{p q}\right)\right\} \\
& E_{i j}^{\prime} \wedge E_{k l}^{\prime} \wedge E_{m n}^{\prime} \wedge E_{p q}^{\prime} \wedge E_{r s}^{\prime} .
\end{aligned}
$$

The determining equation for 5 -cocycles takes the form

$$
\begin{aligned}
d C^{5}= & \left\{(-q-q t+r+r s+s-t) C\left(E_{i j}, E_{k l}, E_{m n}, E_{o p}, E_{q+s, r+t}\right)\right. \\
& +(o+o r-p-p q-q+r) C\left(E_{i j}, E_{k l}, E_{m n}, E_{o+q, p+r}, E_{s t}\right) \\
& +(-o-o t+p+p s+s-t) C\left(E_{i j}, E_{k l}, E_{m n}, E_{o+s, p+t}, E_{q r}\right) \\
& +(-m-m p+n+n o+o-p) C\left(E_{i j}, E_{k l}, E_{m+o, n+p}, E_{q r}, E_{s t}\right) \\
& +(m+m r-n-n q-q+r) C\left(E_{i j}, E_{k l}, E_{m+q, n+r}, E_{o p}, E_{s t}\right) \\
& +(-m-m t+n+n s+s-t) C\left(E_{i j}, E_{k l}, E_{m+s, n+t}, E_{o p}, E_{q r}\right) \\
& +(k+k n-l-l m-m+n) C\left(E_{i j}, E_{k+m, l+n}, E_{o p}, E_{q r}, E_{s t}\right) \\
& +(-k-k p+l+l o+o-p) C\left(E_{i j}, E_{k+o l+p}, E_{m n}, E_{q r}, E_{s t}\right) \\
& +(k+k r-l-l q-q+r) C\left(E_{i j}, E_{k+q, l+r}, E_{m n}, E_{o p}, E_{s t}\right) \\
& +(-k-k t+l+l s+s-t) C\left(E_{i j}, E_{k+s, l+t}, E_{m n}, E_{o p}, E_{q r}\right) \\
& +(-i-i l+j+j k+k-l) C\left(E_{i+k, j+l}, E_{m n}, E_{o p}, E_{q r}, E_{s t}\right) \\
& +(i+i n-j-j m-m+n) C\left(E_{i+m, j+n}, E_{k l}, E_{o p}, E_{q r}, E_{s t}\right) \\
& +(-i-i p+j+j o+o-p) C\left(E_{i+o, j+p}, E_{k l}, E_{m n}, E_{q r}, E_{s t}\right) \\
& +(i+i r-j-j q-q+r) C\left(E_{i+q, j+r}, E_{k l}, E_{m n}, E_{o p}, E_{s t}\right) \\
& \left.+(-i-i t+j+j s+s-t) C\left(E_{i+s, j+t}, E_{k l}, E_{m n}, E_{o p}, E_{q r}\right)\right\} \\
& E_{i j}^{\prime} \wedge E_{k l}^{\prime} \wedge E_{m n}^{\prime} \wedge E_{o p}^{\prime} \wedge E_{q r}^{\prime} \wedge E_{s t}^{\prime}=0 .
\end{aligned}
$$

Computation in the grade -2 shows that the ranks of the coboundary and cocycle subspaces are equal to 24 and 23 , respectively. The non-trivial cocycle can be expressed in the form

$$
\begin{aligned}
& 12 C\left(E_{-1,-1}, E_{-1,0}, E_{0,-1}, E_{01}, E_{10}\right)-6 C\left(E_{-1,-1}, E_{-1,0}, E_{0,-1}, E_{02}, E_{1,-1}\right) \\
& -12 C\left(E_{-1,-1}, E_{-1,1}, E_{0,-1}, E_{00}, E_{10}\right)+3 C\left(E_{-1,-1}, E_{-1,1}, E_{0,-1}, E_{01}, E_{1,-1}\right) \\
& +14 C\left(E_{-1,-1}, E_{-1,2}, E_{0,-1}, E_{00}, E_{1,-1}\right)-36 C\left(E_{-1,0}, E_{-1,1}, E_{0,-1}, E_{00}, E_{1,-1}\right) \\
& \equiv 12 C\left(1, q, p, p q^{2}, p^{2} q\right)-6 C\left(1, q, p, p q^{3}, p^{2}\right)-12 C\left(1, q^{2}, p, p q, p^{2} q\right) \\
& \quad+3 C\left(1, q^{2}, p, p q^{2}, p^{2}\right)+14 C\left(1, q^{3}, p, p q, p^{2}\right)-36 C\left(q, q^{2}, p, p q, p^{2}\right) .
\end{aligned}
$$

Note that $H_{(-4)}^{3}(P o(2))$ also contains a non-trivial cocycle

$$
C\left(E_{-1,-1}, E_{-1,0}, E_{0,-1}\right) \equiv C(1, q, p) .
$$

Other cocycles up to number 5 and grade 10 are trivial.

## 5 Conclusion

We have not found reports of an explicit computation of cohomology for the algebra $P o(2)$. In [6] some results of computation of cohomology for the algebra of Hamiltonian vector fields $H(2)=P o(2) / Z$ are presented. That computation was also based
on the use of a computer. Though our program is oriented to work with algebras of vector fields, it can be easily adapted to work with Lie superalgebras of other types. It is necessary only to write some additional input functions. The current preliminary version of the program uses standard 32 -bit words for integers. As our experience shows, the computation of more than 5th cohomologies and in more than 10th grades for $P o(2)$ leads to overflow of such integers. Thus, it is necessary to add to the program the arithmetic of arbitrary precision. It would be useful to add also the arithmetic of finite fields, because there is a lot of unsolved problems even for cohomology of finite-dimensional Lie algebras over such fields.

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Программа для вычисления когомологий супералгебр Ли векторных полей

Описан алгоритм и его реализация на языке С для вычисления когомологий алгебр и супералгебр Ли. При разработке алгоритма основное внимание было уделено когомологиям в тривиальном, присоединенном и коприсоединенном модулях для (супер)алгебр Ли формальных векторных полей. Эти алгебры широко используются в современных суперсимметричных моделях теоретической и математической физики. В качестве примера мы приводим найденные компьютером 3- и 5-коциклы из когомологии в тривиальном модуле для алгебры Пуассона $\operatorname{Po}$ (2).

Работа выполнена в Лаборатории вычислительной техники и автоматизации ОИЯИ.

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A Program for Computing Cohomology of Lie Superalgebras of Vector Fields

An algorithm and its $C$ implementation for computing the cohomology of Lie algebras and superalgebras is described. When elaborating the algorithm we paid primary attention to cohomology in trivial, adjoint and coajoint modules for Lie algebras and superalgebras of the formal vector fields. These algebras have found many applications to modern supersymmetric models of theoretical and mathematical physics. As an example, we present 3- and 5-cocycles from the cohomology in the trivial module for the Poisson algebra Po (2), as found by computer.

The investigation has been performed at the Laboratory of Computing Techniques and Automation, JINR.


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