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$1966, v .44 \mathrm{~A}$, ИНСТИТУТ ЯДЕРНЫХ ИССЛЕДОВАНИЙ

Дубна


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## CONDITIONS OF MACROSCOPIC CAUSALITY FOR THE SCATTERING MATRIX

Submitted to Nuovo Cimento



## Introduction

In modern theory the properties of the scattering matrix are formulated on the basis of local theory. However, the physical meaning of the scattering matrix, as was pointed out long ago by Heisenberg $/ 1$, can essentially be beyond the narrow framework of local theory $x /$. This is also seen from the axiomatic approach in which the ambiguity of extrapolating the scattering matrix off the mass surface $p_{0}^{2}=\vec{p}^{2}+m^{2} / 3 /$ is clearly displayed.

Whatever this extrapolation is, a direct physical meaning is kept only by the scattering matrix $S$ on the mass surface. Therefore we apply the causality condition only to this quantity which is physically defined, and we call it the condition of macroscopic causality unlike the condition of microscopic causality associated with the notion of local field.

The application of the causality condition to the scattering matrix meets with a difficulty that the scattering matrix transforms the states for $t=-T$ into the states for $t=+T$ at $T \rightarrow \infty$. During the time $2 T$ the waves fill the whole space. Therefore a stationary state arises which, in its very essence, excludes the conditions necessary for the causal connection to be formulated.

In 2 we will show that it is still possible to construct wave packets which allow a reasonable formulation of the macrocausality conditions and which are compatible with an interpretation of the limlt $T \rightarrow \infty$ such that the ternns of the order $\frac{1}{R}(R=v T, \quad, \quad v-\quad$ is the packet velocity) are assumed to be still finite while the terms of the order $1 / R^{2}$. and higher are neglected. By means of such packets we may formulate the conditions of macrocausality which is thought of as the usual causal connection characteristic of the relativistic metric; events at the points $9\left(x^{\circ}\right)$ and $\mathscr{I}\left(x^{\infty}\right)$ may be causally connected provided only that a) the interval $\left(x^{\prime \prime}-x^{\prime}\right)^{2}$ is a time interval, i.e. $\left(x^{\prime \prime}-x^{\prime}\right)^{2} \geq 0$ and b) the event at $9\left(x^{\prime}\right)$ (cause) precedes the event at $\varphi\left(x^{\prime \prime}\right)$ (consequ ence) so that $t^{\prime \prime}>t^{\prime}$.

In 3 an example of the unitary acausal scattering matrix satisfying this macrocausality condition ls given.

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x/ See also}2/
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## 2. Formulation of the Macrocausality Conditions

Let us consider the two wave packets a and $b$ which at $t_{1}=-T$ are going out of the diaphragms $A$ and $B$ (see Flg. 1). Such a description of the packet "creation" simulates most closely the real situation in experiment. Somewhat later a collision of the packets can occur, but for $t_{2}=+T$ they fly apart. Let for $t_{1}=-T$ the packets be at a distance $R$ which is much lar ger than the size of the packets $L(R \gg L)$. We shall assume that the prickets have a sufficiently definite momentum $p$, so that $p \gg \Delta p=t / L$. Now we require that the packets would not spread considerably during the time $2 T$ be. an increase of the packet width $\Delta \mathrm{L}$ must not be large as compared with the initial one $L$. The dispersion of the packet velocity $\Delta_{v}$ is

$$
\begin{equation*}
\Delta v=\frac{\partial^{2} E}{\partial p^{2}} \Delta p=\frac{\Delta p}{E} \frac{m^{2}}{E^{2}} \tag{1}
\end{equation*}
$$

( $m$ is the particle mass). So, we have $\Delta L=\Delta v \cdot T=\frac{\Delta p}{p} \frac{m^{2}}{E^{2}} R$. From the condition $L \gg \Delta L$ we get:

$$
\begin{equation*}
L>\frac{m}{E} \sqrt{R \lambda} \tag{2}
\end{equation*}
$$

where $\lambda=t / p \quad$ is the wave length. The condition (2) is compatible with the condition
R > L >>
if $R \gg \frac{\Lambda_{0}^{2}}{\hbar^{2}} \pi$ at $\lambda<\Lambda_{0}$, or if $R \gg \frac{\hbar^{2}}{\Lambda_{0}^{2}} \pi$ at $\lambda>\Lambda_{0}$ here $\Lambda_{0}=\hbar / m c$
Thuts, there are packets which can be used as in-states transformable to out-states by the $s$-matrix:

$$
\begin{equation*}
\langle f| S|i\rangle=\delta_{n}-(2 \pi)^{4} i \delta^{4}\left(p_{i}-p_{i}\right)\langle i| T|i\rangle, \tag{4}
\end{equation*}
$$

where, as usual (i) denote the quantum numbers of the in-stite, and (f) are those for the out-state. The matrix element $\langle f| T|l\rangle$ can be represented a more detailed form

$$
\begin{equation*}
\langle f| T|i\rangle=\frac{\left\langle p_{m} \cdot p_{m-1} \cdots \cdots p_{n+1} \mid \eta p_{n}, \cdots p_{1}\right\rangle}{\sqrt{2 p_{0 m} \quad 2 p_{0 m-1} \cdots \cdot 2 p_{01}}}, \tag{5}
\end{equation*}
$$

where $\left.\left.\left\langle p_{m}, p_{m-1}, \cdots p_{n+1}\right| I\right|_{p_{n}}, \cdots p_{1}\right\rangle$ is the invariant function of the four-momenta $P_{m}, P_{m, 1}, \ldots P_{1}$ and $P_{0_{m}, P_{0 m-1}} \ldots P_{0_{1}}$ are their fourth components. In what follows, we shall restrict ourselves to the simplest case of the pairing collision of two
particles, when in the initial state (i) there are only two particles described by the wave packets $u_{1}\left(x_{1}\right)$ and $u_{2}\left(x_{2}\right)$ of the above considered type. These packets can be represented in the form of the integrals:

$$
\begin{equation*}
u(x)=\frac{1}{(2 \pi)^{8 / 2}} \int \tilde{u}(\vec{p}) e^{i p x} \frac{d^{d} p}{2 p_{0}}, \tag{6}
\end{equation*}
$$

where $p_{0}=+\sqrt{\bar{p}^{2}+m^{2}}$. The wave function of the initial state in the momentum representation will be of the form:

$$
\begin{equation*}
\Phi_{i n}\left(p_{2} p_{1}\right)=\frac{\tilde{u}_{2}\left(\vec{p}_{2}\right)}{\sqrt{2 p_{02}}} \frac{\tilde{u}_{1}\left(\vec{p}_{1}\right)}{\sqrt{2 p_{01}}} . \tag{7}
\end{equation*}
$$

From (4), (5), (7) we get:

$$
\phi_{\text {out }}\left(p_{m}, p_{m-1}, \cdots p_{z}\right)=
$$

$$
\begin{equation*}
-(2 \pi)^{4} i \int \delta^{4}\left(p_{m}+p_{m+1}+\cdots+p_{z}-p_{2}-p_{1}\right) \times \tag{8}
\end{equation*}
$$

$$
\times \frac{\left\langle p_{m}, p_{m-1} ; \cdots p_{8}\right| I\left|p_{2} p_{1}\right\rangle}{\sqrt{2 p_{0 m} 2 p_{0 m-1} \cdots 2 p_{0 B}}} \ddot{p}_{2}\left(\vec{p}_{2}\right) q_{1}\left(\vec{p}_{1}\right) \frac{d^{8} p_{2} d^{8} p_{1}}{2 p_{02} 2 p_{01}} .
$$

and for $m=4$ (the elastic collision):

$$
\begin{aligned}
& \Phi_{\text {out }}\left(p_{4}, p_{8}\right)=\Phi_{i n}\left(p_{1}, p_{8}\right)-(2 r)^{4} i \int \delta^{4}\left(p_{i}+p_{8}-p_{2}-p_{1}\right) \times \\
+ & \frac{\left\langle p_{i} p_{8}\right| 1\left|p_{2} p_{i}\right\rangle}{\sqrt{2 p_{01} 2 p_{08}}} \tilde{U}_{2}\left(\vec{p}_{2}\right) \tilde{U}_{1}\left(\vec{p}_{1}\right) \frac{d p_{2} d^{2} p_{i} f}{2 p_{02} p_{01}} .
\end{aligned}
$$

Now we go over to the coordinate representation. For this we multiply the lefthand side of (8) by

$$
\frac{1}{(2 \pi)^{8 / 2(m-2)}} \frac{\exp i\left(p_{m} x_{m}+p_{m-1} x_{m-1}+\cdots+p_{8} x_{8}\right)}{\sqrt{2 p_{0 m}{ }^{2} p_{0 m-1}} \cdot \cdots \quad 2 p_{0 g}}
$$

 in terms of $u(x)$ :

$$
\frac{\bar{u}(\vec{p})}{2 p_{0}}=\frac{1}{(2 \pi)^{8 / 2}} \int u(x) e^{-l p x} d^{d} x .
$$

Then from (8) we get:

and in a similar way from ( $8^{\prime}$ )


In this case we have
or

$$
\begin{equation*}
g\left(x_{m}, x_{m-1}, \cdots, x_{2} \mid x_{2}, x_{1}\right)=-\frac{4 \partial^{2} g_{0}\left(x_{m} \cdot x_{m-1} ;\left.\cdots x_{2}\right|_{z} x_{1}\right)}{\partial t_{2} \partial t_{1}}, \tag{11}
\end{equation*}
$$

where $8_{0}$ is the invariant function of the coordinates

$$
\begin{align*}
& \varepsilon_{0}\left(x_{m}, x_{m-1} ;-, x_{3} \mid x_{2}, x_{1}\right)=\int \delta^{4}\left(p_{m}+p_{m-1}+\cdots+p_{2}-p_{2}-p_{1}\right) \times \\
& \left\langle p_{m}, p_{m-1}, \cdots p_{2}\right| \mid p_{2} p_{1}>\operatorname{coxp} 1\left(p_{m} x_{m}+\cdots+p_{s} x_{2}-p_{2} x_{2}-p_{1} x_{i}\right) x \tag{12}
\end{align*}
$$

$$
\frac{d^{2} p_{m} d^{2} p_{m-1} \cdots d^{2} p_{1}}{2 p_{0 m}{ }^{2 p_{0 m-1}}{ }^{\cdots 2 p_{01}}}
$$

$$
\Rightarrow \quad 2 p_{0 m} 2 p_{0=-1} \cdots 2 p_{01}
$$

We notice that due to the presence of the $\delta$ function under the integral in $s$ and 5. these functions are translation-invariant and depend only on the difference of the variables $x_{m}, x_{m-f ;} x_{1} \quad$. No we may formulate the principle of macrocausality: a) the wave packets $n_{2}\left(x_{2}\right)\left(\Delta x_{2}=L\right)$ and $u_{1}\left(x_{1}\right)\left(\Delta x_{1}=L\right)$ removed apart at the distance

$$
\begin{equation*}
\left|\stackrel{\rightharpoonup}{x}_{2}-\stackrel{\rightharpoonup}{x}_{1}\right|=|\stackrel{\rightharpoonup}{z}|=R>L \gg x \tag{13}
\end{equation*}
$$

contribute to provided only that

$$
\begin{equation*}
x^{2}=\left(t,-t_{1}\right)^{2}-\left(z_{2}-\vec{x}_{1}\right)^{2}>0 . \tag{14}
\end{equation*}
$$

b) Further $\Phi_{0.1}=0 \quad$ if the coordinates of the particles $x_{m}, x_{n=1} ;-x_{3}$ created in the collision lie out of the future light cone with respect to the points $x_{2}, x_{1}$ :

$$
\begin{equation*}
\left(x_{2}-x_{2}\right)^{2}>0 .\left(x_{2}-x_{1}\right)^{2}>0 . \tag{15}
\end{equation*}
$$

$$
\begin{align*}
& 8\left(x_{n}, x_{n-1}, \ldots, x_{2} \mid x_{2} x_{1}\right)= \\
& =\int 8^{4}\left(p_{m}+p_{m-1}+\cdots+p_{3}-p_{2}-p_{1}\right)<p_{m}, p_{m-1} \cdots p_{2}|I| p_{2} p_{1}>x \tag{10}
\end{align*}
$$

$$
t_{e}>t_{2}, \quad t_{E}>t_{1} .
$$

 vanish outside the above- mentioned space-time regions, however, only asymptoth cally, l.e. for

$$
\begin{equation*}
R \rightarrow \infty \quad,\left(t_{s}-t_{2}\right),\left(t_{s}-t_{1}\right) \rightarrow \infty \tag{16}
\end{equation*}
$$

From the physical point of view these conditions are identical with the requirements of classical macroscopic causality and imply the assumption that all the particles in the final state $\Phi_{\text {out }}$ can be produced (or change their state) later than the initial packets exchange the field quanta (see Fig. 2).

The usual local theory satisfies, of course, the above stated requirement of macrocausality (for example see Appendix A). This requirement will be satisfied also by any scattering matrix in which the macrocausality is violated only in a small localized space-time region.

In 3 we give an example of the acausal unitary srattering matrix obeying the requirements of macroscopic causality.

## 3. Acausal Scattering Matrix

Now we turn to a formal construction of the nonlocal scattering matrix, obeying the requirements of unitarity and macroscopic causality.

We represent the scattering matrix $S$ in the form:

$$
\begin{equation*}
S=\frac{1-(1 / 2) K}{1+(1 / 2) \mathrm{R}} \tag{17}
\end{equation*}
$$

where $K$ is the Hermitean matrix, i.e.

$$
\begin{equation*}
\mathbf{K}=\mathbf{K}^{+} \tag{18}
\end{equation*}
$$

This provides the unitarity of the considered matrix. To study the structure of the $\quad S$-matrix we shall assume that there is a small parameter which permits to expand our scattering matrix in a power series in this parameter

$$
\begin{equation*}
S=\sum_{n=0}^{\infty} a_{n}(i K)^{n} \tag{19}
\end{equation*}
$$

where a are the real numbers. After singling out the imvariant functions the matrix $\overline{\mathbf{F}}$ can be written in the form

$$
\begin{equation*}
K=\frac{\tilde{F}\left(p_{1}, \cdots p_{z} \mid p_{a+i}, \cdots p_{m}\right)}{\sqrt{2 p_{01} P_{0} p_{0} \cdots p_{0}}} . \tag{20}
\end{equation*}
$$

where $p_{01}=+\sqrt{\overrightarrow{\vec{p}_{1}^{2}}+m^{2}}$ : We shall consider only scalar particles. Owing to the $C P T$ theorem, we have for the matrix elements K :

$$
\begin{equation*}
K\left(p_{1}, \cdots p_{a} \mid p_{m+1} ; \cdots p_{m}\right)=K\left(p_{n+1}, \cdots p_{m} \mid p_{1} ; \cdots p_{m}\right) \tag{21}
\end{equation*}
$$

and taking into account (18):

$$
\begin{equation*}
K\left(p_{1} ; \cdots p_{n} \mid p_{n+1}, \cdots p_{n}\right)-K K^{*}\left(p_{1}, \cdots p_{n} \mid p_{n+1} ; \cdots p_{n}\right) . \tag{22}
\end{equation*}
$$

This means that the function must be reol. Now we note the following properties of the functions

$$
\begin{equation*}
\tilde{F}\left(p_{1}, \cdots p_{m}\right)=\frac{1}{(2 \pi)^{a / 2 m}} \int F\left(x_{1}, x_{2} ; \cdots x_{m}\right) \exp \left(\sum_{1=1}^{\sum_{i}} p_{1} x_{1}\right)_{l_{1=1} \|_{1} x_{1}} \tag{23}
\end{equation*}
$$

in this case

$$
\begin{equation*}
F\left(x_{1} ; \cdots x_{m}\right)=F\left(-x_{1},-x_{2}, \cdots-x_{m}\right) \tag{24}
\end{equation*}
$$

Further $F\left(x_{1}, \cdots x_{n}\right)$ is translation - invariant. In particular, it can be represented as a function of the variables $\xi_{i}-x_{1}-x_{1+1}, j=1,2, \cdots m-1$. Then we may write down (23) in the form:

$$
\begin{equation*}
\tilde{F}\left(p_{1}, p_{2} ; \cdots p\right)=\delta^{4}\left(p_{1}+p_{2}+\cdots+p_{n}\right) \times \tag{23}
\end{equation*}
$$

$$
\frac{1}{(2 \pi)^{d 2(m-1)}} \int F\left(\xi_{1}, \xi_{2}, \cdots \xi_{--1}\right) \exp \left(\sum_{1=1}^{=-1} Q_{1} \xi_{1}\right)_{1=1}^{-1} d^{6} \xi_{1} .
$$

Now we turn to the macrocausality condition and, for the sake of definitness, we restrict ourselves to the simplest case of the elastic collsion. Basing on (19) we have:

$$
\begin{gathered}
\left\langle p_{1}, p_{2}\right| S\left|p_{2}, p_{4}\right\rangle=1-1 \frac{\tilde{F}\left(p_{1}, p_{2}, p_{8}, p_{4}\right)}{\sqrt{2 p_{01} 2 p_{02} 2 p_{08} 2 p_{04}}}+ \\
+\int \frac{\tilde{F}\left(p_{1}, p_{2}, p^{\prime}, p^{\prime \prime}\right) \tilde{F}\left(p_{i}^{\prime} p^{\prime \prime}, p_{8}, p_{4}\right)}{\sqrt{2 p_{01}-\cdots 2 p_{04}}} \times \\
\times \delta\left(p^{\prime 2}-m^{2}\right) \theta\left(p_{0}^{\prime}\right) \delta\left(p^{\prime \prime 2}-m^{2}\right) \theta\left(p_{0}^{\prime \prime}\right) d^{4} p^{\prime} d^{4} p^{\prime \prime \prime} .
\end{gathered}
$$

In the coordinate representation we have:

$$
\begin{gather*}
S\left(x_{1}, \cdots, x_{4}\right)=1-i F\left(x_{1}, \cdots, x_{4}\right)+ \\
+\iint F\left(x_{1}, x_{2}, x^{\prime}, x^{\prime \prime \prime}\right) D^{+}\left(x^{\prime}-y^{\prime}\right) D^{+}\left(x^{\prime \prime}-y^{\prime \prime \prime}\right) x  \tag{26}\\
x F\left(y^{\prime}, y^{\prime \prime}, x_{2}, x_{4}\right) d^{4} x^{\prime} d^{4} x^{\prime \prime} d^{4} y^{\prime} d^{4} y^{\mu} \cdots+\cdots
\end{gather*}
$$

In the ordinary local theory the function $S\left(x_{1}, \cdots x_{4}\right)$ being based on the mio rocausality, satisfies the requirements of macrocausality ( 14,15 ) (cf.Appendix A). It has singularities on the light cone with respect to the variables $\xi_{1}-x_{1}-x_{2}$, $\xi_{2}=x_{2}-x_{8}, \xi_{g}=x_{3}-x_{4} ;$ the nature of these singularities is essentially related to causality. The same may be said about the functions $s$ with a larger number of arguments. We denote the corresponding functions of the local theory by $\mathbf{F}_{0}\left(\xi_{1}, \xi_{2},-\xi_{\mathbf{l}}\right)$.

We do not violate the macrocausality condition (14), (15) if, instead of the causal functions $F_{0}\left(\xi_{1}, \xi_{2} \cdots, \xi_{m}\right)$, we introduce the acausal ones $F_{\mathrm{a}}\left(\xi_{1}, \xi_{2}, \cdots, \xi_{\mathrm{m}}\right)$ which will differ from $F_{0}\left(\xi_{1}, \xi_{9}, \cdots \xi_{m}\right)$ only in a small space-time region near the vertex of the light cone $\xi_{i}^{2}=0, \Omega\left(\xi_{j}\right)=a^{4}$. The quantity a plays the role of an "elementary length". The functions $F_{\Delta}(\xi)$ possessing such properties, as was shown in ref. $4 /$, can be constructed by averaging the possible singuiarities of the function $F_{0}(\xi)$ near the light cone vertex $\xi^{2}=0$ :

$$
\begin{equation*}
F_{\Delta}(\xi)=\int F_{0}\left(\xi-\xi^{*}\right) \rho\left(\xi^{\circ} ; \mathrm{a}\right) \mathrm{d}^{4} \xi^{\prime} \tag{27}
\end{equation*}
$$

where $\rho\left(\xi^{\circ}, n\right)$ is the weighting function (formfactor), by means of which we average the singularities in that space-time region where the usual, causatity and the usual geometry may be violated

The weighting function $\rho(\xi, n)$ depends on some time-like vector $n$, by means of which the domain $\Omega(\xi)=a^{4} \quad$ is determined in an invariant manner. In particular, $\rho$ may be assumed to be a function of the invariant $R$ :

$$
\begin{equation*}
R^{2}-2\left(\xi_{0}\right)^{2}-\xi^{2} \geq 0 \tag{28}
\end{equation*}
$$

and $\rho(R) \rightarrow 0$ for $R \gg a \quad(c f . / 4 /)$.
The physical meaning of the vector a may be different and is discussed in detail in ref. $/ 5$ /. In principle, two types of the vectors a are conceived: the first one, when the vector $n$ is connected with a system of interacting particles ("internal" vector o ) ${ }^{x /}$.

[^0]In this case a violation of geometry occurs only inside the system of interacting particles for extremely small distances and time intervals. Another possibility is that the vector a is related to the physical vacuum ("external" vector i). o In this case one of the trames of reference, namely the frame of reference of the "physical vacuum", turns out to be singled out (cf. $6,7 /$ ).

To summarize, it should he stressed that we consider the introduced averaging of the singularity near the vertices of the light cones only as a tool of a formal description of the situation at small scales which may be very different from the wellknown one in contemporary theory.

## APPENDIX

For the simplest case of the point interaction $\mathbb{V}=\lambda \phi{ }^{4}$ the function $\tilde{F}\left(p_{1} ;-p_{4}\right)$ (see (25)) is simply equal to $\delta^{4}\left(p_{1}+p_{2}-p_{3}-p_{4}\right)$. Theretore in the first approximation the function $S\left(x_{1}, \ldots x_{4}\right)$

$$
\begin{align*}
& S\left(x_{1} ;-x_{4}\right)=\lambda \operatorname{sexpi}^{\left(p_{1} x_{1}+p_{9} x_{2}-p_{8} x_{8}-p_{4} x_{4}\right) \times}  \tag{1}\\
& \quad \times 8^{4}\left(p_{1}+p_{2}-p_{3}-p_{4}\right) \frac{d^{3} p_{1} d^{2} p_{9} d^{2} p_{8} d^{2} p_{4}}{2 p_{01} 2 p_{02} 2 p_{08}^{2} p_{04}}
\end{align*}
$$

We introduce the variables

$$
\begin{align*}
& k=p_{1}, w=p_{1}+p_{2}-p_{8}, \quad \xi=x_{1}-x_{2}, \xi_{3}=x_{2}-x_{4},  \tag{2}\\
& q=p_{8}+p_{2}, k_{4}=p_{1}+p_{2}-p_{8}-p_{4}, \xi_{1}-x_{2}-x_{8}
\end{align*}
$$

$$
\begin{align*}
& S\left(x_{1} ;-x_{4}\right)=\int \exp i\left(\xi k+\xi_{9} q+\xi_{8} u+x_{4} k_{4}\right) \theta\left(k_{0}\right) \delta\left(k^{2}-m^{2}\right) \times \\
& \times \theta\left(q_{0}-k_{0}\right) \delta\left[(q-k)^{2}-m^{2}\right] \theta\left(q_{0}-u_{0}\right) \delta\left[(q-a)^{2}-m^{2}\right] \cdot x  \tag{3}\\
& \quad \times \theta\left(u_{0}-k_{04}\right) \delta\left[\left(a-k_{4}\right)^{2}-m^{2}\right] \delta^{4}\left(k_{4}\right) d^{4} k d^{4} u d^{4} q d^{4} k_{4}
\end{align*}
$$

By integrating we get

$$
\begin{equation*}
S\left(\xi \xi_{2} \xi_{2}\right)-\int D^{+}(\xi-x) y^{-}(x) \int D^{+}\left(x+\xi_{2}-y\right) D^{+}\left(\xi_{2}+y\right) d^{4} y d^{4} x . \tag{4}
\end{equation*}
$$

Since we are interested in the dependence of $S$ on the variable $\boldsymbol{G}$, then making the replacement

$$
\begin{align*}
& \xi_{1}+y=a \\
& x+\xi_{2}+\xi_{2}-\beta  \tag{5}\\
& \xi_{2}+\xi_{1}=c
\end{align*}
$$

$$
\begin{equation*}
S(\xi)=\int D^{+}(\xi+\varepsilon-\beta) \mathrm{D}^{-}(\beta-\varepsilon) \int \mathrm{D}^{+}(\beta-\alpha) \mathrm{D}^{+}(\alpha) \mathrm{d}^{4} \beta \mathrm{~d}^{4} a \cdot \tag{6}
\end{equation*}
$$

From eq.(6) it is seen that outside the forward light cone the function $s(\xi)$ exponentially decreases and turns out to be important only along the Compton wave length.

## APPENDIX B

If we assume the weighting function $\rho(\xi, 1)$ being independent of the vector athen will be a function of only $\xi^{2}: \rho=\rho\left(\xi^{2}\right)$ and coincides with the form factor of nonlocal theory $/ 8 /$.

The role of the vector (which is necessary for the localization of acousality) is now played by the momentum vector or by a set of such vectors connected with the wave packets; i.e. the vector a is in this case taken from the original data (Le. from $\Phi_{\text {in }}$ ). As Owas shown in ref. $/ 9 /$, in doing so, we may ensure macrocausality only for sufficiently smooth wave packets. For very narrow wave packets macroscopic causality will be violated. Indeed, we consider a wave packet which corresponds to the quantum transition from the state
$\psi_{p}(x, t)=e^{i p x} \phi_{p}(x-v t)$
to the state $\psi_{p} \cdot(x, t)=t^{1 p^{\prime} x} \phi_{p} \cdot(x-v t)$.

The current density for the transition $p-p^{\prime}$. is

$$
\begin{equation*}
J_{\Delta \theta}=\exp \left[1\left(p-p^{0}, x\right)\right] \phi_{D}(x-v t) \phi_{p}^{*} \cdot(x-v t) . \tag{1}
\end{equation*}
$$

Its nonlocal image is

$$
J_{4 A}=\int p\left(E^{2}\right) J_{40}\left(x^{0}, t^{0}\right) d x^{\prime} d t^{\prime} \text {, where } B^{2}=\left(t-t^{\prime}\right)^{2}-\left(x-x^{\prime}\right)^{2} \text {. (2) }
$$

If the wave packets $\psi_{p}(x, t), \psi_{p} \cdot(x, t)$ are very sharp (and $\delta$-shaped in the limiting case) then $J_{4}(x, t)$ is nonzero only at the point $x=0, t=0$ (the point of collision of the packets). So, we may assume:

$$
J_{4 a}(x, t)=\theta x p\left[t\left(p-p^{p} ; x\right)\right] \delta(x) \delta(t)
$$

Then from (2) we have:

$$
\begin{equation*}
J_{4 n}(x, t)=\rho\left(t^{2}-x^{2}\right) \tag{3}
\end{equation*}
$$

and causality is essentially volated because $\rho\left(t^{2}-x^{2}\right) \neq 0$ for $t= \pm|x|$
for any whatever large $|x|$.

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F1g. 1. $A$ and $B$ are the diaphragms; $a$ and $b$ are the wave packets of the initial state (the ir-state). I is the initial size of the packets, $R$ is the distance between them at the momentum $t=-\mathrm{I}, \Delta \mathrm{L}$ is the increase of the dit mensions of these packets during the time $2 T$.


Fig. 2. Relations of causality: $u_{1}\left(x_{1}\right), n_{2}\left(x_{2}\right)$ are the initial packets (the in-state) $\nabla_{i}\left(x_{3}\right), v_{i}\left(x_{4}\right)$ are the scattered waves of the out-state $A_{1}^{\prime} A_{1} A_{1}^{N}, A_{9}^{\%} A_{2} A_{2}^{\prime \prime}$ are the light cones.


[^0]:    $x$ For the connection of our scheme with the usual nonlocal theory, see Appendix B.

